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SYSTEM ANALYSIS

For The

Huntsville Operation Support Center  
Distributed Computer System

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Interim Report for Period March 1985 through June 1985

ANNUAL REPORT

1985

Submitted by:

D. Massey, Associate Investigator  
F. M. Ingels, Principal Investigator

Mississippi State University  
Electrical Engineering Department  
Mississippi State, MS 39762  
(601) 325-3912

Submitted to:

NASA MSFC, Alabama  
Technical Monitor: Frank Emmens, EB32  
(205) 453-4629

NAS8-34906



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## OVERVIEW OF REPORT

Network Systems Corporation's HYPERchannel network is a baseband, 50 Megabit per second, high speed local area network. HYPERchannel utilizes a Carrier Sense Multiple Access (CSMA) data trunk access protocol, with prioritized staggered delays. This network has the capability of interconnecting various computer resources of differing manufacture, into a single efficient computing facility.

This network is currently in use at the Huntsville Operations Support Center (HOSC). HOSC as a distributed computing system, is responsible for data acquisition and analysis during National Aeronautics and Space Administration's (NASA) Space Shuttle operations. HOSC also provides computing services for Marshall Space Flight Center's (MSFC) non-mission activities. As mission and non-mission activities change, so do the support functions of HOSC change, demonstrating the need for some method of simulating activity at HOSC in various configurations.

The simulation developed in this work primarily models NSC's HYPERchannel network, since this network basically determines HOSC's efficiency in accomplishing its mission. The model simulates the activity of a steady-state network, reporting statistics such as, transmitted bits, collision statistics, frame sequences transmitted, and average message delay. These statistics may be used to evaluate such performance indicators as throughput, utilization, and delay. Thus the overall performance of the network may be evaluated, as well as predicting possible overload conditions.

## HOW TO READ THIS REPORT

This report is a fully detailed report concerning the inner workings of the HYPERchannel Local Area Network, Chapter 2; a description of the HOSC system, Chapter 3; a full detailed description of the simulation software (design architecture Chapter 4, individual software module description Appendix III); and a presentation of the simulation results for single and dual trunk operation, Chapter 5. The reader interested in a quick overview and a survey of the HOSC system performance may read Chapter 1 and Chapter 5 only. However knowledge of the HYPERchannel adapter's inner workings including message frame construction and timing is desirable, Chapter 2.

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## LIST OF ACRONYMS

ASCII	American Standard Code for Information Interchange
BDP	Buffered Data Path
BR	Bus Request
CATV	Community Area Television
CPU	Central Processing Unit
CSMA	Carrier Sense Multiple Access
DDP	Direct Data Path
DEC	Digital Equipment Corporation
DMA	Direct Memory Access
ECIO	Experiment Computer Input/Output
ET	External Tanks
FEP	Front End Processor
HSLN	High Speed Local Network
HOSC	Huntsville Operation Support Center
I/O	Input/Output
ISO	International Standards Organization
JSC	Johnson Space Center
KSC	Kennedy Space Center
LPS	Launch Processing System
Mbps	Megabits per second
MECO	Main Engine Cut off
MER	Mission Evaluation Room
MIPS	Mission Integration Plannin System
MPS	Main Propulsion System
MSFC	Marshall Space Flight Center
NASA	National Aeronautics and Space Administration
NPR	Non-Processor Request
NSC	Network Systems Corporation
OD	Operational Data
OSI	Open Systems Interconnection
PE	Perkin Elmer
POCC	Payload Operations Control Center
RSS	Range Safety System
SBI	Synchronous Backplane Interface
SRB	Solid Rocket Booster
SSME	Space Shuttle Main Engine
STS	Shuttle Transport System
UBA	UNIBUS Adapter
UBUS	UNIBUS
usec	Microsecond



## Chapter 1 Introduction

### 1.1 NSC's HYPERchannel Local Area Network

Network Systems Corporation's (NSC) HYPERchannel local area network is a widely used very high speed, 50 Megabits per second, digital communications facility. HYPERchannel utilizes microcomputer-based adapters and standard 75 ohm CATV coaxial cable as data trunks, to interconnect various computer resources within a computing installation. There are three types of adapters (Processor, Device, and Link) used to interface individual equipment to the network of data trunks. These adapters provide for:

- o interconnection of equipment from various manufacturers.
- o high performance communication between processors.
- o a sharing of peripheral systems between multiple processors.
- o realistic physical location of interconnected equipment.
- o increased utilization of interconnected equipment.
- o increased tolerance to individual equipment failures.

Finally, Data movement within a HYPERchannel network is accomplished by use of frames and frame sequences. These frames contain the necessary information for addressing and routing, along with associated user messages and data. A sophisticated internal protocol

is used to provide for contention allocation, error detection, retransmission allocation, and data movement. These capabilities provide a reliable network that is insensitive to configuration, and single points of failure. This internal protocol is the basis for HYPERchannel system performance and will be described further in a subsequent chapter.

## 1.2 HOSC System Overview

The Huntsville Operations Support Center (HOSC), as implemented at the Marshall Space Flight Center (MSFC) in Huntsville, Alabama, is a distributed computer resource facility. HOSC is designed to provide real time acquisition, analysis, and display of data during National Aeronautics and Space Administration's (NASA) space missions. HOSC provides support primarily for the Space Shuttle, Space Telescope, and Space Laboratory missions. Among the resources available at HOSC are various large minicomputers and peripherals. A large portion of these resources are interconnected using NSC's HYPERchannel network. The configuration flexibility afforded by HYPERchannel provides HOSC with the ability to adapt to future mission requirements and also provides MSFC with a large computing facility for non-mission activities.

Data handling at HOSC falls into two main categories, mission and non-mission activities. Mission

activities are those that take place during powered flight. For example, the space shuttle main engine data is analyzed by the Main Propulsion System (MPS) processor, which is also sent to a back up processor simultaneously. Data arrives via direct ground links or satellite communication links from the Kennedy Space Center Firing Room at NASA's Kennedy Space Center (KSC) in Florida or from NASA's Johnson Space Center (JSC) in Texas. Services provided by the network during missions are data analysis and presentation services for HOSC mission support teams. Non-mission activities are also provided by HOSC, one of these is support for the Payload Operations Control Center (POCC) preplanning activity. Future expansion at HOSC may include computer resource support for Digital Equipment Corporation's interactive graphics data base (IGDS), and XEROX Corporation's text-processing operation (SIGMA), both of which, are non-mission activities.

### 1.3 Research Objective

NSC's HYPERchannel local area network is a sophisticated computer network allowing considerable flexibility and adaptability with regard to computer resources. HYPERchannel allows a wide variety of minicomputers, not necessarily manufactured by the same company, to be interconnected in a single or

multi-trunk network. Thus, computer resources which may be separated by distance or manufacturer may be utilized by one another within this distributed computer network. HOSC, as a distributed computing facility, utilizes HYPERchannel to accomplish the interconnection of various computer resources. Mission requirements imposed on the HOSC, require that it possess the ability to adapt and change its resources according to the dictates of a particular mission. The configuration of the HOSC's resources are mission dependent and may be readily changed, however, the effects of those changes on system performance are not readily apparent. The data handling capability of the HYPERchannel network and its performance in various configurations affect HOSC's system performance directly. With this in mind, the primary goal of the research effort was the development of a simulation model of the HYPERchannel network that could be manipulated to predict and characterize the behavior of the HOSC in a variety of scenarios.

The first step in this analysis was an investigation of the operating properties and characteristics of a HYPERchannel network. In Chapter 2 of this document, a functional description of HYPERchannel is detailed with particular emphasis on the protocols used by the network. The second step,

detailed in Chapter 3, was the characterization of various computer resources and possible HOSC activity scenarios. The third step, detailed in Chapter 4, was the definition and development of a software model of a HYPERchannel network. Using this simulation model, system parameters were varied to simulate changes to the operating environment of the HOSC. Finally, the results and conclusions of these manipulations to the simulation model were compiled and analyzed in order to provide some insight into the present and perhaps future operating characteristics of the HOSC.

## Chapter 2 HYPERchannel Network Description

### 2.1 Network Components

Network Systems Corporation's (NSC) HYPERchannel network is a high speed, baseband local area network. A HYPERchannel network consists of standard Community Area Television (CATV) coaxial cables used as data trunks and various adapters to control network traffic flow. These adapters use a carrier sense multiple access (CSMA) protocol with prioritized, staggered delays to implement traffic flow and control. Network messages generated by an adapter are composed of frames and are called frame sequences. These messages are broadcast over a given trunk at a fixed rate of 50 Megabits per second, using a phase modulation technique with a manchester data format, and are received by network components through nondirectional taps or ports (Figure 2.1). Network components at these ports are known as **network adapters**, which control access to a given trunk. A network adapter can be attached to as many as four independent network trunks, enabling a configuration to match a specific installation and provide:

- o incremental expansion
- o linear interconnect cost
- o no single point of failure

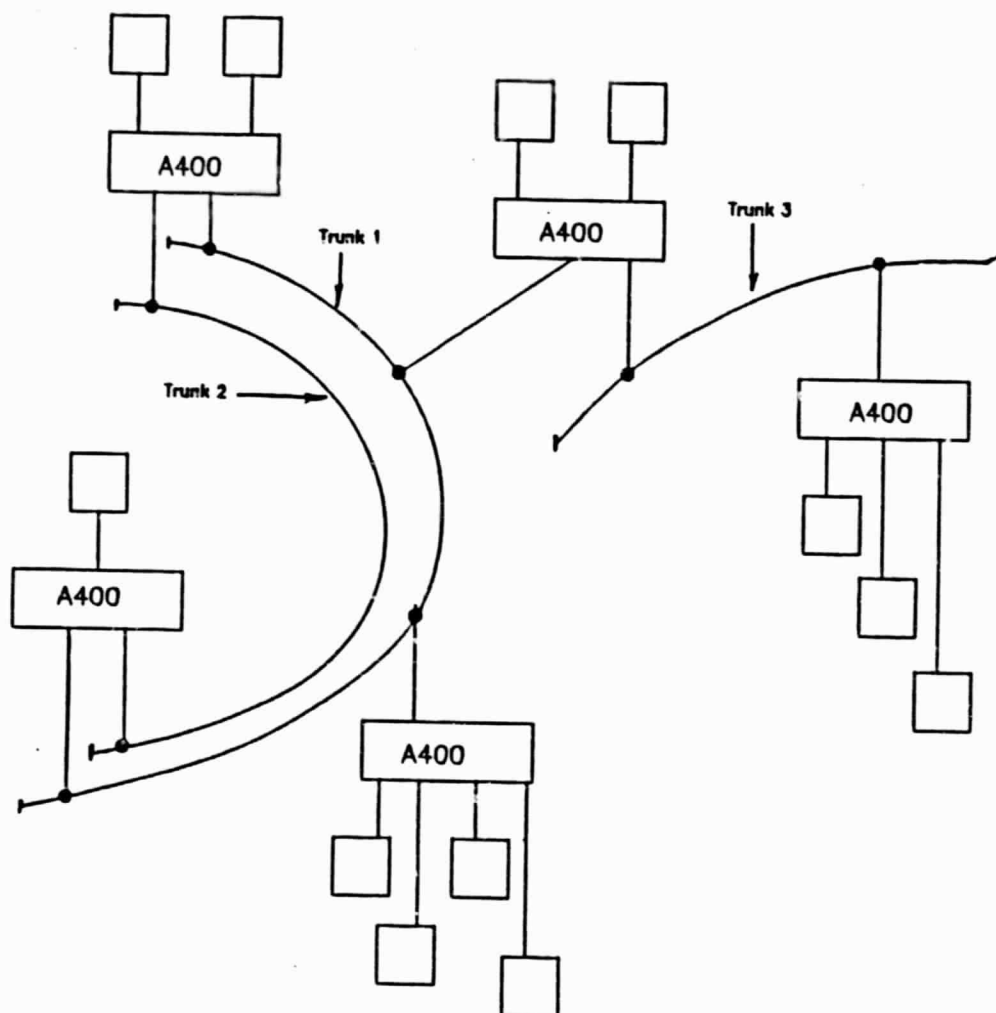


Figure 2.1 Typical HYPERchannel Interconnection.

NSC manufactures three main types of network adapters: processor, device and link. A **processor adapter** interfaces a computer data channel to the network of data trunks. It serves as buffered data path between the computer attached, and the trunk network. The computer communicates with data buffers in the adapter at its own rate and asynchronous with transmissions on the network trunks. The adapter provides the necessary formatting and internal protocol to transmit the contents of its buffers over the selected network trunk. The processor adapter receives data from the trunk network and provides status information to the originator of the data. The computer at the receiving adapter may then access the data and any associated message in the adapter buffer. NSC has designated this adapter type as **A400 HYPERchannel adapters**, herein referred to as adapters. The **device adapter** functions as a remote channel providing a computer data channel for the attachment of peripheral control units. This adapter is driven by network messages from the data trunks. It receives network messages containing device commands, data, and control information. It generates messages containing status or device data. The device adapter operates multiple devices in the same manner as a data channel produced by a computer manufacturer operates multiple devices.



The link adapter is used in pairs to provide communication between remote HYPERchannel networks. A link adapter receiving a network message destined for a remote network transmits this message over a wide band communications link to the remote network. The link adapter at the remote location receives this message and retransmits it over its own local network. There are two types of link adapters, the terrestrial link adapter and the satellite link adapter.

Finally, due to the nature of the HOSC computing facility only the processor adapter will be included in the model.

#### 2.1.1 Adapter Architecture

Each adapter, regardless of the type of user equipment attached, consists of the following:

- o A 16-bit micro-processor with 4096 words of read-only memory (ROM)
- o Storage section (Buffer and Control logic)
  - 1024 8-bit bytes of control memory with odd parity
  - 4096 8-bit bytes of buffer memory with odd parity
  - 16 working registers
  - 16 trunk registers
  - 256 extension registers
- o One trunk interface

This portion of an adapter is termed the Nucleus Adapter. The nucleus adapter has two general

applications, (processor and device adapter) determined by the type of equipment attached and the necessary interface required. Thus an adapter consists of a specific device interface and a nucleus adapter. The device interface will then define the particular adapter type. An adapter can be divided into four main sections: micro-processor, buffer, and control logic, trunk interface, and device or equipment interface (Figure 2.2). The micro-processor has a 4096 16-bit word read-only instruction memory with a 320 nanosecond cycle time. It handles equipment functions and responses and manages data flow on the direct data path between the equipment and the adapter buffers. The buffer and control logic along with the trunk interfaces control the high speed trunk transmissions. It consists of a 1024 8-bit byte control buffer, normally used to stack control information, and a data buffer containing 4096 or (optionally) 8192 8-bit bytes. This section also contains a flag register and other registers to specify buffer address, length of data transmission, and network addressing functions. The control logic contained in this section allow concurrent access to memory by both trunk interfaces and equipment interfaces. The 100 Mbps buffers allow a 50 Mbps data movement on the data trunks along with a 50 Mbps data movement with the attached equipment. The

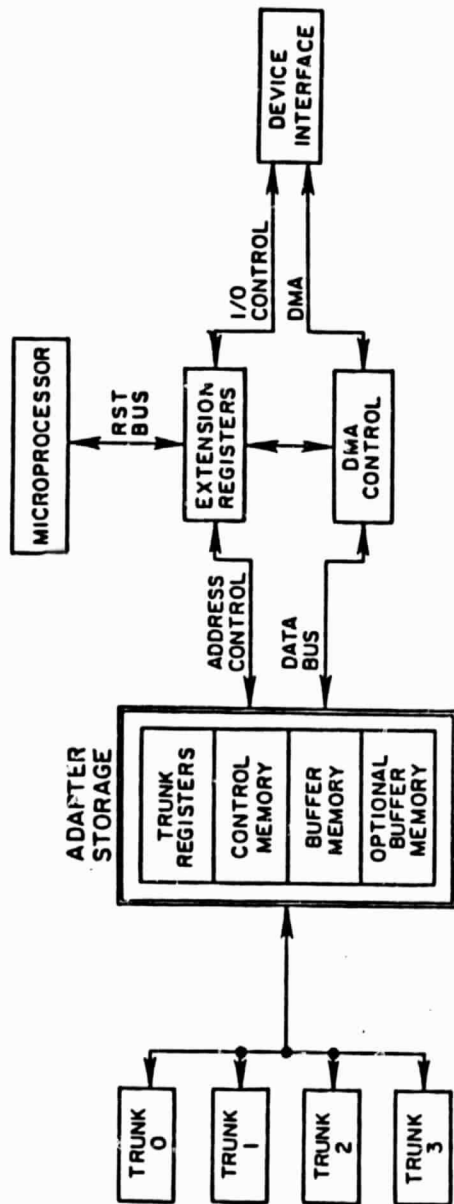


Figure 2.2 Block Diagram of Adapter [NSC80a].

trunk interface board (up to four) contains the necessary transmitting and receiving electronics and the high speed logic to control the transmission envelope-checkwords, access code, and network address. Each trunk interface has the ability to generate a busy or reserved response and contains the logic to control trunk contention on its attached data trunk. Finally, the device interface (up to four) or equipment interface contains the circuitry needed to interface a specific equipment or device to the adapter. This interface is unique to a given device and determines the adapter type.

## 2.2 HYPERchannel Protocols

HYPERchannel adapters support trunk selection, trunk-access, adapter-adapter virtual circuit, and host-adapter protocols. The trunk selection protocol is based on a cyclic scan of the connected data trunks. The trunk-access protocol is of the carrier sense multiple access (CSMA) type, with ordered priorities assigned to each adapter. The adapter-adapter virtual circuit protocol involves connection (adapter reservation and deadlock avoidance) and data flow control. The assumption of a steady state model precludes inclusion of the host-adapter protocol since a host is represented as a fixed rate data source. In order to understand the impact of the various protocols

on system performance, they will be described in detail in the remainder of this section.

### 2.2.1 Trunk Access Protocol

HYPERchannel uses a carrier sense multiple access scheme with prioritized staggered delays to implement a trunk access protocol. The intention of this scheme is to:

- o ensure that ready adapters defer to on-going transmissions
- o ensure that response (acknowledgement) frames are transmitted without interference
- o provide as much trunk capacity to the highest priority adapter as it requests by prioritized access, and provide as much capacity to the next highest priority adapter as it requests, and so on
- o sort out collisions without the necessity of generating random retry delays and ensuring that colliding frames are not involved in collisions when retransmitted.

HYPERchannel accomplishes this with four primary mechanisms: transmitter disable, fixed delay, N delay or priority delay, and end delay. These functions are implemented on each trunk interface board and can be different for each trunk attached.

Any time the trunk is sensed busy the adapter transmitter is disabled (unless it is transmitting) so that an ongoing transmission will not be interfered with. The fixed delay period is a delay period

following any transmission in which only the receiving adapter for the last transmission is allowed to transmit. This period of time allows a receiving adapter to respond immediately without being interfered with by other ready "sending adapters". A transmitting adapter which does not receive a response to a transmission during this period assumes that its last transmission was lost and will schedule a retransmission. Following the fixed delay period a scheduling period begins. This period is the **N delay** or **Priority delay** period and is a unique event for each adapter on a given trunk. An adapter's priority delay is assigned based on the priority (user defined) and placement on the trunk of the adapter in question. Following the fixed delay period an adapter ready to transmit will wait until its priority delay, at which time it is allowed to transmit without interference if the trunk is idle. If an adapter becomes ready to transmit during this scheduling period, but after its priority delay has expired it must wait until its priority delay occurs again or until the end delay period (defined next) is encountered. The **end delay** period occurs if an entire scheduling period passes without an adapter transmission. After this event a free-for-all or contention period begins in which any adapter which becomes ready to transmit may do so. In

this contention period, collisions become possible if two adapters sense the trunk idle and attempt to transmit nearly simultaneously. These various delay events are implemented in each adapter by a timer. This timer is enabled any time the trunk is sensed idle and begins to count down to its respective delay events. If at any time the trunk is sensed busy the timer is disabled and loaded with the end delay value. As the timer counts down the fixed delay, priority delay, and the end delay events are signaled (Figure 2.3).

These delay settings are set into what NSC terms as contention switches (SW1-SW9), located on each trunk interface board. These contention switches have 16 discrete positions (0 through F), with each position providing 160 nanoseconds of delay. These switches are grouped in sets of three switches per parameter. SW1, SW2 and SW3 are the least-significant bit position switches and SW7, SW8 and SW9 are the most-significant bit position switches. An adapter's fixed delay is set into switches (SW7, SW4 and SW1), its priority delay is set into switches (SW8, SW5 and SW2) and finally, its end delay is set into switches (SW9, SW6 and SW3). The actual settings for these switches are calculated from expressions given by NSC. These expressions when evaluated, yield decimal numbers which are then

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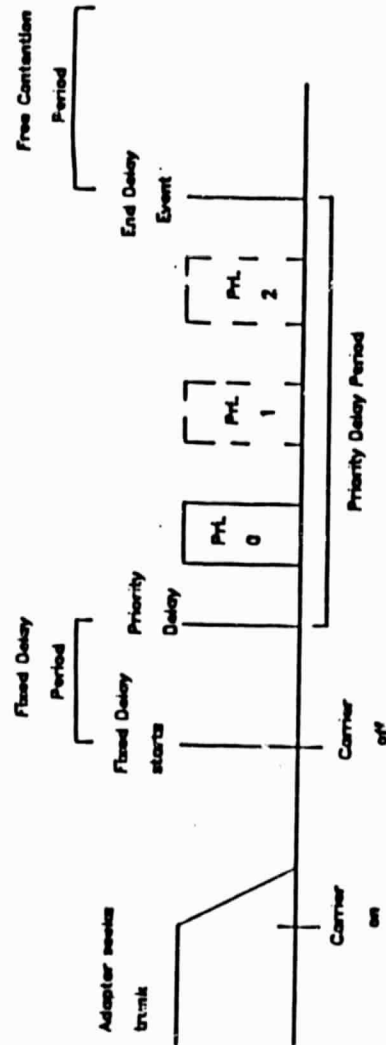


Figure 2.3 HYPERchannel Delay Time Events.



converted to hexadecimal equivalents. The hexadecimal equivalents are then set into the contention switches.

When an adapter receives a transmission frame it will immediately generate and transmit a response frame. So that all ready-to-send adapters will not interfere with this response, the fixed delay period must be such that all adapters will sense the response before this delay expires. This relation as given by NSC [NSC80a] is:

$$\text{Fixed Delay} = \frac{\text{Total trunk cable length (ft.)}}{40} + 13 \quad (1)$$

This value as calculated will be the same for all adapters on a given trunk. The priority delay refers to the period of time uniquely assigned to each adapter on a trunk. This time period occurs following the fixed delay period and is determined by the adapter's assigned priority and position on the trunk. The highest priority adapter is assigned a priority delay of 0.48 microseconds, this allows sufficient time for the highest priority adapter to prepare to retransmit an unacknowledged frame prior to its scheduled transmission time.

The priority delays for the remaining adapters on the trunk is given by [NSC80a]:

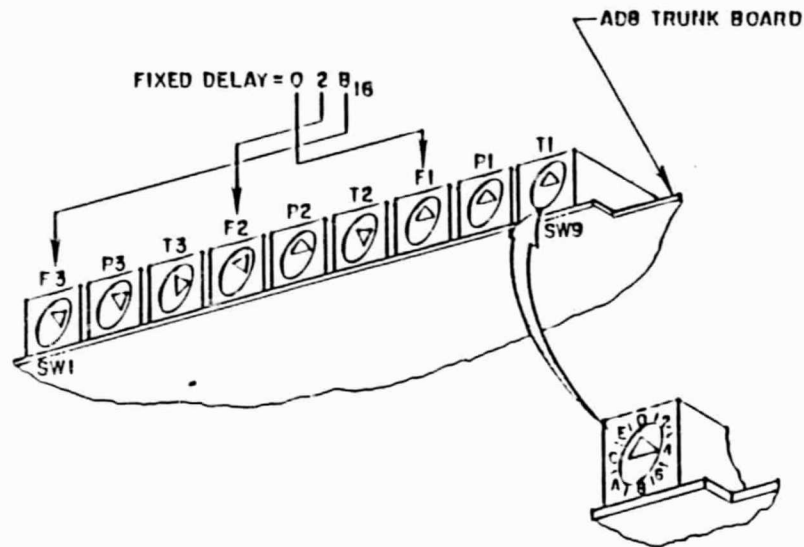
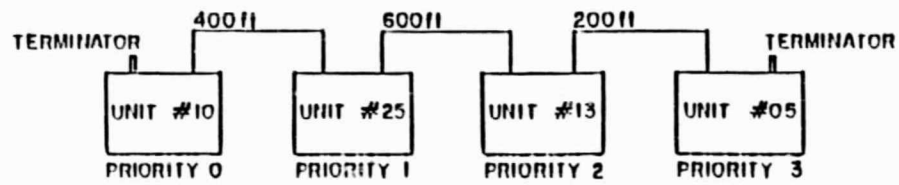
$$\begin{aligned}
 & \text{Priority delay of next} \\
 \text{Priority} = 10 + & \text{ highest adapter (decimal value)} \\
 \text{Delay} & \\
 & (2) \\
 & + \frac{\text{Cable length (ft.) to next highest} \\
 & \quad \text{priority adapter}}{40}
 \end{aligned}$$

NSC recommends that priorities should be assigned sequentially in order to maximize throughput on the trunk. The end delay is calculated for each adapter such that the lowest priority adapter on making a transmission is sensed by all other adapters on the trunk. This is necessary since an adapter may transmit immediately when its end delay is signaled (contention period). This delay is calculated as follows [NSC80a]:

$$\begin{aligned}
 & \text{Priority delay of lowest} \\
 \text{End Delay} = 10 + & \text{ priority adapter (decimal value)} \\
 & (3) \\
 & + \frac{\text{Cable length (ft.) from this} \\
 & \quad \text{adapter to farthest adapter}}{40}
 \end{aligned}$$

An example of the use of (1), (2) and (3) is illustrated in Figure 2.4. The calculations which follow are performed for unit #25, trunk 0.

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SWITCH SETTING	UNIT 10	UNIT 25	UNIT 13	UNIT 05
FIXED DELAY	28	28	28	28
PRIORITY DELAY	3	17	30	3F
END DELAY	67	50	62	67

Figure 2.4 Sample AD8 Contention Timing Calculations [NSC80a].

$$\text{Fixed delay} = \frac{1200 \text{ feet}}{40} + 13 = 43_{10} = 2B_{16}$$

$$\text{Priority delay} = 10 + 3 + \frac{400}{40} = 23_{10} = 17_{16}$$

$$\text{End delay} = 10 + 63_{10} + \frac{800}{40} = 93_{10} = 5D_{16}$$

These values are then set into the contention switches located on the AD8 trunk interface board as indicated. Finally, in the access scheme described thus far, the highest priority adapters could possibly monopolize the trunk. To prevent this a device known as a wait flip-flop is implemented in each adapter. This flip-flop is set when an adapter transmits and is cleared when the adapter end delay is signaled. When the flip-flop is set the adapter is prohibited from transmitting, the intention of this device is to provide a fair allocation of the trunk. All adapters are equipped with this device and adapters with this flip-flop enabled may coexist, on the same trunk, with adapters whose flip-flop is disabled.

### 2.2.2 Adapter-Adapter Link Level and Virtual Circuit Protocols

The following sections will deal with data movement and the protocols involved once an adapter has gained access to the trunk through the trunk access protocol. The data link protocol may be viewed as

having two basic information grouping levels. The basic information unit is the frame and a higher level grouping is the frame sequence.

#### **2.2.2.1 Frame and Frame Sequence Structure**

The smallest unit of information transmitted over the network is the frame. There are three classes of frames: transmission frames, data frames, and response frames. Transmission frames are generally short frames (up to 38 bytes) used by adapters for signalling and status exchanges. Table 2.1 lists these frames and their functions. There are two forms of data frames, message proper frames and associated data frames following a message proper frame (Figure 2.8). An adapter receiving a transmission frame, message proper or a data frame will generate and transmit a response frame. This response frame serves to acknowledge receipt of a frame and in some cases returns information to the transmitting adapter. Frame formats are listed in Table 2.2. Note from Figure 2.8, that the fixed delay period is used to initiate transmission of other than acknowledgement frames as will be explained.

As stated previously, a higher level information structure is achieved by grouping frames together into frame sequences. All information exchanges occurring on the network will be in the form of frame sequences. There are two types of frame sequences used on the

Table 2.1 HYPERchannel Protocol Frames [Fran 84].

Transmission Frames

Set Reserve	- Reserve receiving adapter
Copy Register	- Request for Register information
Clear Flag 8	- When set, Flag 8 indicates that the adapter is ready to receive a frame. When clear, it indicates that the frame has been received.
Set Flag A Clear Flag A	- Flag A, when set, indicates that the receiver will receive associated data. It is cleared when the last block of associated data is received.
Clear Flag 9	- When set in the receiver, Flag 9 indicates that the receiver is ready to receive data. When set in the transmitter, it indicates that the transmitter is ready to send data. When cleared in receiver, it indicates that the data block has been received. When cleared in the transmitter, it indicates that data can now be transmitted.

Data and Message Frames

Message Proper	- Used to transmit host messages of length less than or equal to 64 bytes.
Associated Data	- Used to transmit data blocks of length up to 2 Kbytes.

Response Frames

Response	- A receiving adapter sends a response frame for each non-response frame received. Its purpose is to acknowledge received frames or, as in the case of the response to a copy registers frame, to send requested data.
----------	--

Table 2.2 Frame Formats [FRAN82].

Field	Length (bytes)
leading syncs . . .	12-18
frame type . . . .	1
access code . . . .	2
to address . . . .	1
from address . . . .	1
function code . . . .	2
message length . . .	2
check word . . . .	2
trailing sync . . .	8

Transmission Frame Format

Field	Length (bytes)
leading syncs . . . .	3
frame type . . . .	1
access code . . . .	2
to address . . . .	1
from address . . . .	1
function code . . . .	2
message length . . .	2
check word . . . .	2
trailing . . . . .	8

Response Frame Format  
(no data)

Field	Length (bytes)
leading syncs . . .	12-18
frame type . . . .	1
access code . . . .	2
to address . . . .	1
from address . . . .	1
function code . . . .	2
message length . . .	2
check word . . . .	2
message/data . . . .	8-64/ 0-2K
message/data	
checkword . . . .	2
trailing sync . . .	8

Message Proper and Associated  
Data Frame Format

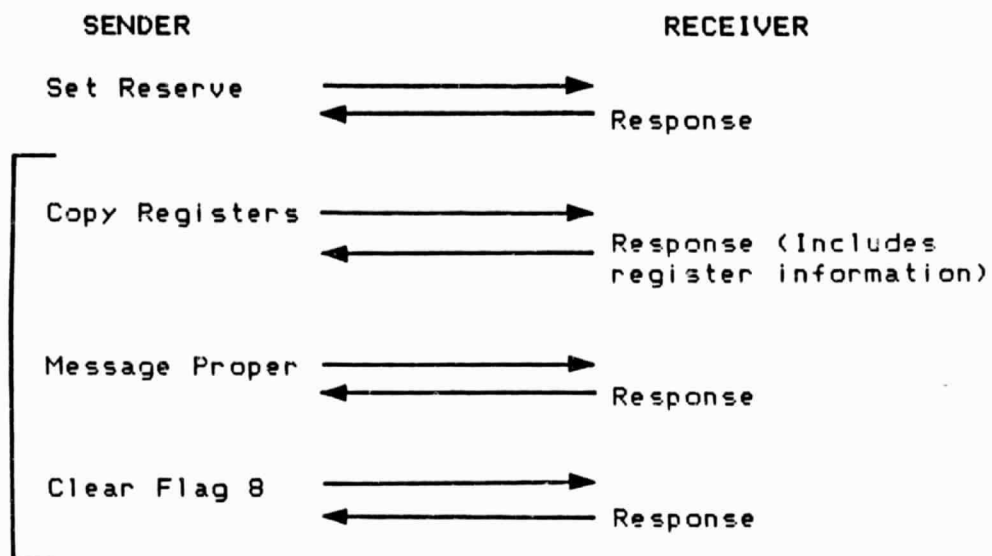
Field	Length (bytes)
leading syncs . . .	3
frame type . . . .	1
access code . . . .	2
to address . . . .	1
from address . . . .	1
function code . . . .	2
message length . . .	2
check word . . . .	2
register information . . . .	2
checkword . . . .	2
trailing sync . . .	8

Response Frame Format  
(with data)

network: message-only and message-with-data sequences. A message-only sequence is normally used to transmit short messages of up to 64 bytes between devices on the network. The sequence of frames which make up a message-only sequence are shown in Figures 2.5 and 2.6. Data is transmitted on the network in 2K byte blocks (optionally 4K byte blocks) in message-with-data frame sequences, as shown in Figures 2.7 and 2.8.

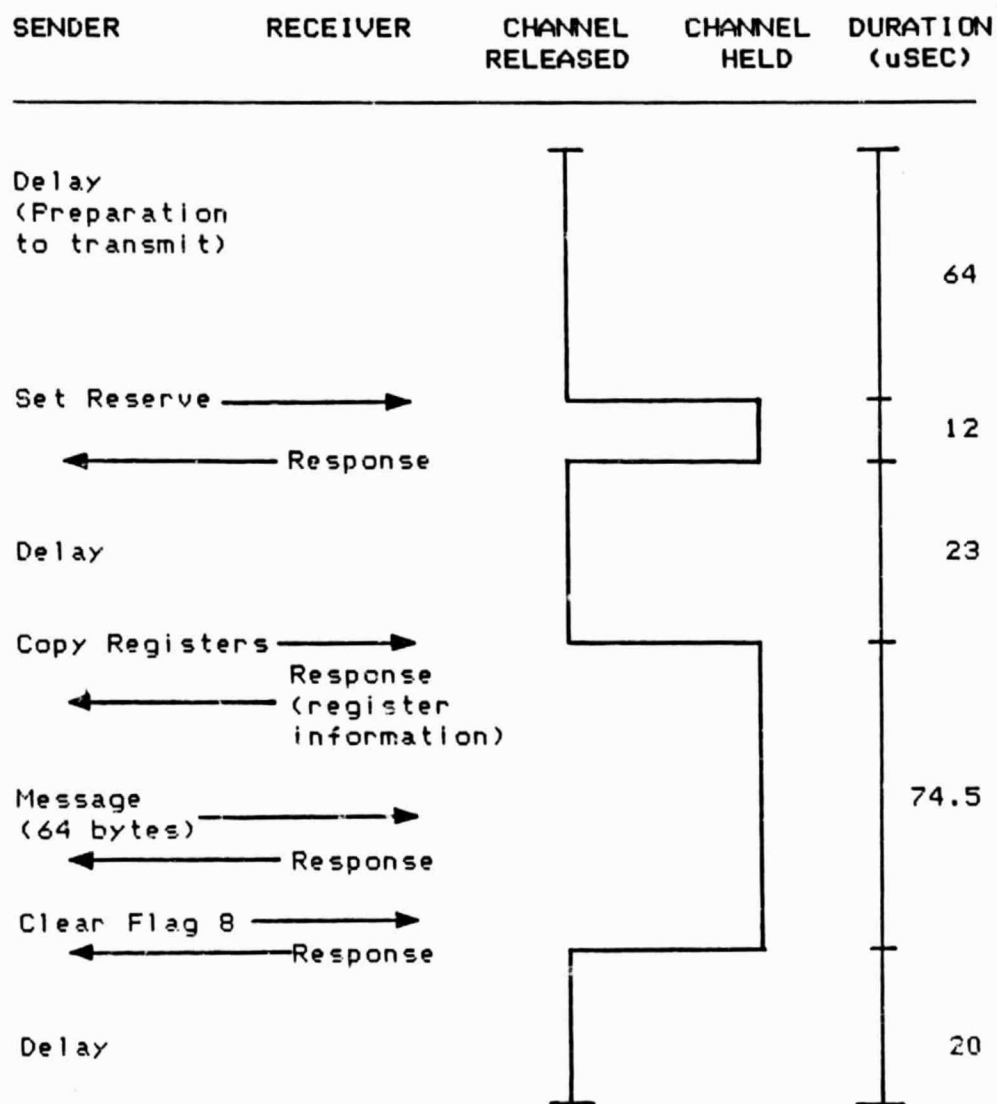
In order to promote efficient utilization of the trunk an adapter does not maintain control of the trunk throughout an entire message-only or message-with-data sequence. An adapter will relinquish the trunk while performing tasks not requiring the trunk, these periods are depicted as delays in the Figures representing the two types of message sequences. After transmitting the first frame of a sequence the trunk is released. When the transmitting adapter is ready to continue transmitting it must compete with the other adapters for trunk access. After regaining access to the trunk the adapter will transmit a copy register frame, if this frame is transmitted without a collision, the receiving adapter will send a response frame to the sender. Upon receipt of a response frame the adapter captures the trunk by transmitting during the fixed delay period that follows. The trunk is regained without interference since any ready to send adapter is





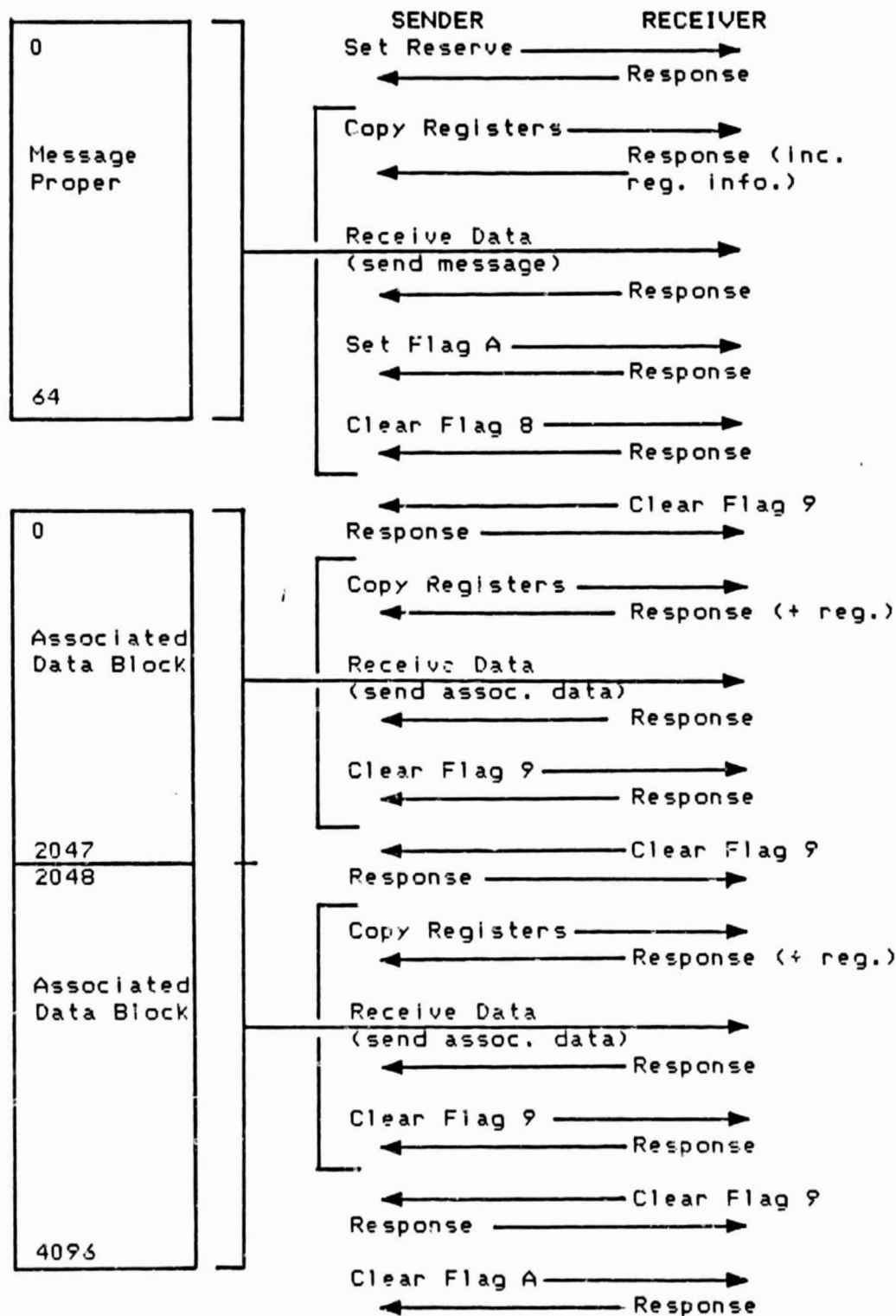
Note: Frames enclosed within bracket are transmitted without interference by beginning their transmission in the fixed delay period.

Figure 2.5 Message-Only Frame Sequence [FRAN84].



Note: Transmission times do not include propagation delay.

Figure 2.6 Timings for Message-Only Sequences [FRAN84].



Note: Frames in brackets transmitted without interference by beginning their transmission in the fixed delay period.

Figure 2.7 Message-with-Data Frame Sequence [FRAN82].

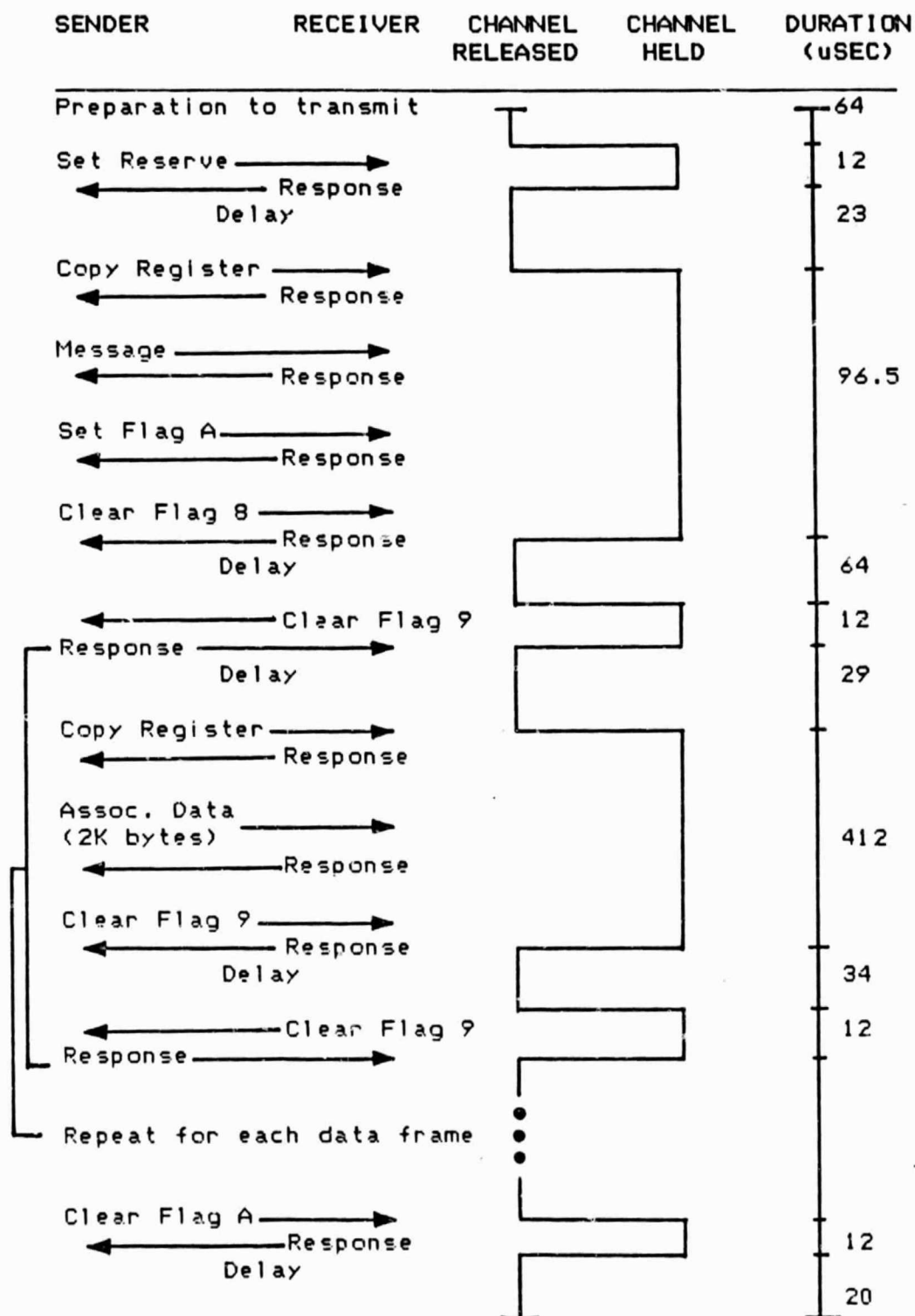


Figure 2.8 Timings for Message-with-Data Sequences [FRAN84].

prevented from transmitting during the fixed delay period. If the sequence to be transmitted is a message-only sequence, control of the trunk is not relinquished until the entire remaining sequence is transmitted, see Figure 2.6. The timing and duration of a message-only sequence is shown in Figure 2.6.

A message-with-data sequence is preceded by a message-only sequence, following the transmission of the message proper the trunk is released, see Figure 2.7. When the receiver indicates that it is ready to receive more data by sending a clear flag 9 frame to the sender, the sender will compete to regain access to the trunk. Once the sender regains access to the trunk it will send a copy register frame to the receiver. If successful, it will regain control of the trunk as described before. Control of the trunk will not be relinquished until an associated data frame and clear flag 9 frame are transmitted by the sender. This process is repeated for each associated block of data. Maintaining control of the trunk during data frame transmissions ensures that these frames are never involved in collisions, thus only relatively short frames will ever need retransmission due to collision on the trunk. The trunk is held during data frame transmission by the sending adapter, by transmitting synchronization bits during the fixed delay periods

following the transmission frames that make up the data frame sequence. The timing and duration of this sequence of frames is shown in Figure 2.8. It is important to note that in all of these sequence transmissions that during the delay periods, a transmitting adapter must always compete for trunk access in order to regain the trunk.

NSC adapters also support an alternate form of transmission scheme known as the burst mode. In this form of sequence transmission, an adapter will not relinquish the trunk until it completes an entire frame sequence transmission. According to literature available [FRAN82],[FRAN84] this mode is rarely used and will not be detailed in this work.

#### 2.2.2.2 Trunk Selection

Any adapter in a network can be connected to up to four trunks. Each trunk uses the same trunk access protocol and operates independently, i.e., each trunk has a separate interface board within an adapter. The interface listens for properly addressed incoming messages and is capable of generating rejection response frames if its adapter is reserved. An adapter, having a frame to transmit and contending for a trunk will scan the trunks in a specified manner until it senses a non-busy trunk. The adapter then waits until the trunk can be captured through the trunk access

protocol. If the trunk is busy with the adapter's frame transmission its search terminates; otherwise it continues. Trunks to be tried can be specified in a host-adapter message and a receiver's trunks to try may be specified by the transmitting adapter. A trunk is said to be **disabled** if it is not connected or was not specified as a trunk to try. A trunk is said to be **enabled** if it is connected or is specified as a trunk to try. An adapter will try a trunk by first determining whether it is enabled or disabled, if the trunk is disabled or busy it will try the next trunk. If the trunk is enabled then the adapter determines whether or not it is busy. The period of time required to try an enabled trunk is 5.5 microseconds, while the time required to try a disabled trunk is 2 microseconds. The ability to specify the trunks to try in the transmitter and receiver provides a means to dedicate trunks to specific types of traffic, e.g., short transmissions on one, long transmissions on another. Simulation studies indicate no benefit is derived from dedicating trunks for particular message types. The ability to specify trunks is more useful in multitruk networks that are not fully connected [FRAN84]. It is possible for an adapter connected to more than one trunk to receive messages simultaneously, when this happens the adapter will accept one and

reject the others. Communication between adapters on two different trunks, requires the services of an intermediary. One of the adapters will transmit to a device attached to an adapter common to both trunks. Once this device has received this message sequence it will then proceed to transmit the sequence to the intended receiver on the other trunk. Thus communication between adapters on different trunks consists of sending a message-with-data sequence twice.

#### 2.2.2.3 Virtual Circuit Establishment

An adapter reservation scheme (Figure 2.9) is used to establish a virtual connection between adapters desiring to communicate. When an adapter receives a message from its attached host, it will first reserve itself; that is, the adapter makes itself inaccessible to received transmissions from any other adapter with the exception of the adapter with which it is trying to communicate. After reserving itself, the sending adapter transmits a set reserve frame to the receiving adapter. If the receiving adapter is idle; that is, it is not reserved, then the receiving adapter will transmit a response frame indicating that the adapter has reserved itself to receive a transmission from the transmitting adapter. Following the reservation of the receiver, the frame sequence transmission proceeds as described in section 2.2.2.1. Both the transmitting and



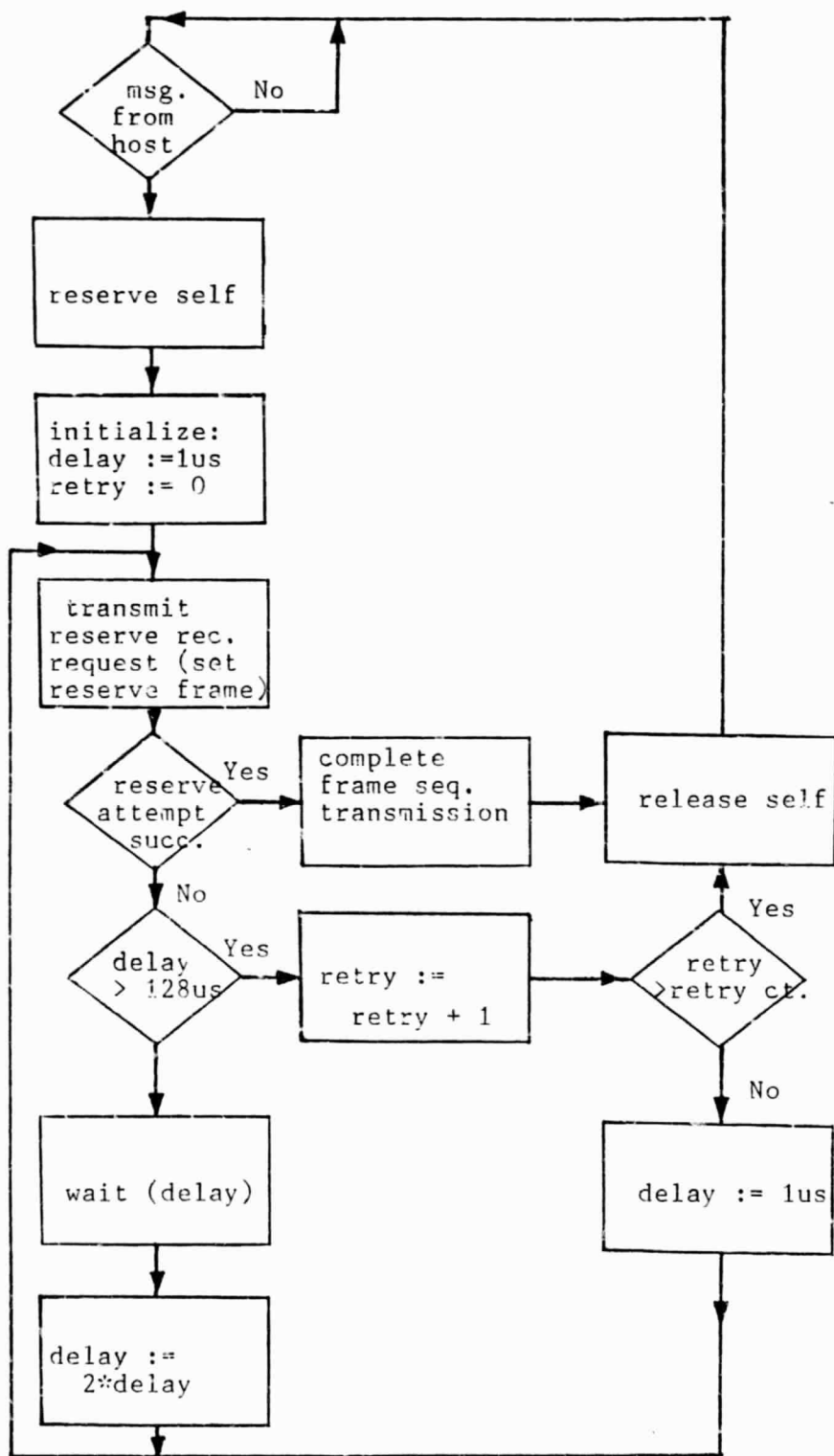


Figure 2.9 Adapter Reservation Scheme [FRAN82].

receiving adapters remain reserved during the entire message-only or message-with-data frame sequence transmission. After completing the frame sequence transmission, the transmitting adapter releases the receiving adapter with a clear flag A frame and then releases itself completing the termination of the connection; see Figures 2.6 and 2.8.

When a transmitting adapter sends a set reserve frame to a reserved adapter, the reserved adapter will respond with a reservation reject frame. The first time a sending adapter receives a reservation reject frame, the adapter will delay for a "binary exponential time" before making another reservation attempt. Following the first reservation rejection the adapter will delay 1 microsecond before making a second attempt. For each following reservation rejection, the adapter will delay an amount of time equal to twice the previous delay, up to 128 microseconds. When this value of delay (128 microseconds) is exceeded retry is advanced by one, the delay is reinitialized, and the sequence is repeated (Figure 2.9). This process will continue until either a successful reservation occurs or the adapter's retry count is exceeded. An adapter's retry count is based on its unit number, manually set by the user and is in the range of 55 to 250. If after retry count tries the adapter is unable to reserve the receiver, the

transmission is aborted and the sender returns to the idle state. The sending adapter remains reserved throughout the entire reservation attempt process. This reservation scheme with the binary exponential delays between transmissions, serves as congestion control on the network by keeping a sending adapter from monopolizing the network.

This retry scheme as described has the potential of causing adapter deadlock. This will occur if two adapters attempt to reserve each other nearly simultaneously. They will find each other reserved and go through the retry scheme until one or the other's retry count is exceeded and aborts the attempted transmission. To alleviate this problem, a back-off scheme is employed by communicating adapters. This back-off routine enables a sending adapter to determine the identity of the adapter that the rejecting adapter is attempting to reserve from the reject response. If the sending adapter determines that it and the rejecting adapter are attempting to reserve one another, then the sending adapter aborts its reservation attempt and releases itself. The slowness of this back-off mechanism can cause both adapters to abort their reservation attempts, preventing either adapter from communicating on the network. The time

required for this mechanism to respond is dependent on the adapter model and is approximately 50 microseconds.

A second form of deadlock which the back-off mechanism will not correct is called a reservation request loop. This occurs when three or more adapters attempt to reserve each other, i.e., adapter A attempts to reserve adapter B, while B attempts to reserve C, and C attempts to reserve A. In this case the adapters have no way of determining that this situation exists and each adapter will perform the reservation retry scheme as previously described. This deadlock will only be resolved when one of the adapter's retry count expires, causing the adapter to abort its reservation attempt and release itself. Serious degradation of trunk throughput may be predicted during this reservation request loop period [DONN79].

#### 2.2.2.4 Data Flow Control

Network adapter's are supplied with two 2K byte buffers (4K byte buffers optional). With two buffers one can be filled/emptied by transfer from/to the attached host, while the other buffer is emptied/filled by a network transmission/reception. In order to ensure that buffer capacity is not exceeded, a flow control mechanism is needed. Flow control is achieved in two ways. First, data frame length is limited to adapter buffer length. Second, an adapter sending a data frame

may not send another data frame until the receiving adapter specifically requests it. This ensures that an adapter will not receive data frames at a rate faster than an adapter may process them.

Additional techniques used by adapters to prevent them from becoming permanently blocked awaiting receipt of a response frame which will never arrive are described in the following. One of the techniques involved is the requirement that response frames begin their transmission during the fixed delay period. If an adapter does not receive a response to a transmission it will reschedule the transmission at a later time. To ensure that an adapter does not retransmit indefinitely, as would be the case if the receiver address were incorrect or the receiver was malfunctioning, a limit is placed on the number of retransmissions allowed. A set reserve frame will be transmitted 16 times on each trunk and then aborted if no response is received. All other frames will be transmitted 256 times before abort. For the case when the expected response is a non-response frame (clear flag 9 granting permission to transmit data) a "deadman timer" is used. In a transmitting adapter this time frame spans the time from when the host's transmit message is received until the last buffer is transmitted and acknowledged. In the receiving adapter

this time begins with the receipt of a set reserve frame and does not end until the receipt of the last data buffer. This time span ranges from .5 to 8 seconds, adjustable in .5 second increments. If all frame transmissions are not completed before this timer expires, the transmission is aborted [FRAN82].

### 2.3 Intra-Adapter Communication

A message transfer between attached hosts on the same adapter is termed an intra-adapter transfer and is carried out entirely local to the adapter. This type of data transfer occurs without utilizing the data trunk network. An important consequence of this type of transfer is that the adapter will appear reserved to the rest of the network. Obviously, if the occurrence of this type of transfer becomes predominate then network performance will suffer. If resources do not conflict, intra-adapter communication may occur concurrently with network traffic and cause no degradation of network performance.

### Chapter 3 HOSC System Description

As previously stated, HOSC is a distributed computer network employing many large mini-computers and NSC's HYPERchannel network. The primary task of HOSC is to provide NASA scientists and engineers with near real time acquisition and analysis of data during Space Shuttle operations. This information allows MSFC engineers and contractor personnel to act in a support capacity to other mission specialists at KSC and JSC. Some of the primary monitoring and support requirements of HOSC are pre-launch support for the Space Shuttle Main Engine (SSME), the External Tanks (ET), the Solid Rocket Boosters (SRB's), the Main Propulsion System (MPS), and the Range Safety System (RSS). Further, support is provided for mission experiments designed by MSFC personnel.

NASA has defined the mission of the Flight Operations Support Center at HOSC as follows:

During powered flight, the HOSC will receive only data which is in the LPS (Launch Processing System) at KSC. The Shuttle support team will be in the HOSC during this phase of the mission and will be the point of contact with the JSC Mission Evaluation Room (MER) for problem discussion and resolution as required and will be on call during orbital operations. The Space Lab and experiment support team will be located in the HOSC during orbital operations when applicable.

Following completion of the active Shuttle vehicle support activities, data is recalled as required for more detailed analysis, and initial preparation is made to provide support to post flight evaluation [NASA82].

HOSC is located in the west end of A-wing building 4663, at MSFC in Huntsville, Alabama. Figure 3.1 shows the functional components of one of many HOSC system configurations. The information contained in the following sections of Chapter 3, is from previous work published in connection with this same research effort [MAUL84].

### 3.1 Typical HOSC System Activities

The data processing activities at HOSC can be placed into two categories, routine daily activities and mission/launch activities. A summary of these activities by category and some details of typical data transfers are outlined in Table 3.1. While this table and the description that follows describe typical activities, these are not all the activities that HOSC is engaged in. There are some activities that are defined only for a current mission, i.e., experiments directed by HOSC mission specialists. Since these may change from mission to mission they are not included in the following description, but must be characterized and considered in the specific mission scenario required for the total system analysis.



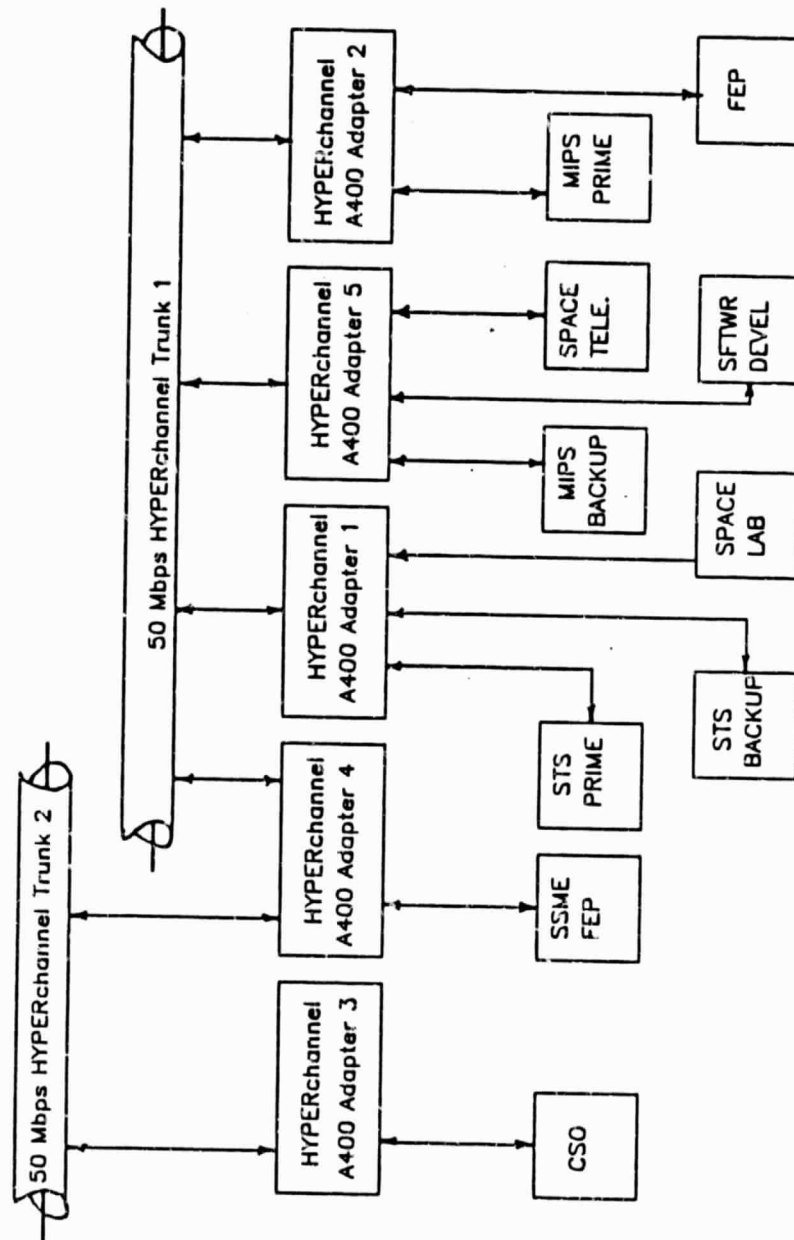


Figure 3.1 Typical HOSC Configuration.

TABLE 3.1 HOSC Data Transfers

## I. ROUTINE DAILY ACTIVITIES

### A. PCCC Activity

Resources Involved: MPS Primary (VAX 4)  
MPS Backup (VAX 1)

Quantity of Data: 150,000 512-byte blocks in two components. 6 8344-byte blocks and 100,000 512-byte blocks.

### B. ECIO Data Stream (Generated by PCCC)

Resources Involved: MPS Backup (VAX 1)  
Spacelab 8/32

Quantity of Data: 51.2 kilobyte per second stream concurrent with PCCC.

### C. IGDS/SIGMA Activities (Proposed)

Resources Involved: To be determined

Quantity of Data: Unknown.

## II. ROUTINE LAUNCH ACTIVITIES

### A. Routine Daily Activities (See Item I.)

### B. Main Engine Data

Resources Involved: STS Primary (PE 3244)  
MPS Backup (VAX 1)

Quantity of Data: 50 kilobit per second stream (Launch minus 8 hours until MECO)

### C. OD Data Stream

Resources Involved: FEP SSME (PE 3244)  
CSO Computer  
STS Primary (PE 3244)  
MPS Backup (VAX 1)

Quantity of Data: 192 kilobit per second stream into FEP and then to CSO with transfer of 40 percent to STS Primary and MPS Backup. (Launch minus 9 seconds until MECO)

### D. Engineering Display Changes

Resources Involved: STS Primary (PE 3244)  
STS Backup (PE 8/32)  
Spacelab 8/32 (PE 8/32)

Quantity of Data: Insignificant.

One activity not associated directly with the real-time responsibilities of the network and therefore a routine daily activity is PCCC simulation activity. The impact of PCCC activity on overall performance of the network stems from the requirement of continuous data transfers between network computers. This data is currently being transferred between the MPS primary computer (VAX 4) and the MPS backup computer (VAX 1). During each twenty-four-hour period, this activity requires the transfer of 150,000 512-byte blocks of data. This data is transferred in two components; six times each day, an 8344-byte block is transferred (50,000 bytes cumulative), with another 100,000 512-byte blocks transmitted randomly but distributed evenly throughout the day.

PCCC also generates a continual 51.2 kilobit per second data stream known as the Experiment Computer Input/Output (ECIO) data stream. This data stream is ongoing and concurrent with PCCC activity. ECIO data is transferred from the MPS Backup Computer (VAX 1) to the Spacelab 8/32 (PE 8/32c).

The routine components of the launch day data activities are the Main Engine Data Stream, the Operational Data (OD) Stream, and the Engineering Display Change requests. The Main Engine Data is collected and disseminated on launch day only. Data is

funneled through the network to the MPS Backup Computer (VAX 1) from the Shuttle Transport System (STS) Computer (PE 3244). From eight hours before launch until about twelve minutes after launch at Main Engine Cut Off (MECO), STS Primary accepts a continuous 50 kilobit per second data stream directly from the KSC Firing Room and transfers about 24 percent (12 kilobits per second) of the total stream to MPS Backup.

The OD Stream is a 192 kilobit per second data stream arriving at the Front End Processor Space Shuttle Main Engine (FEP SSME) Computer (PE 3244) on launch day concurrently with some of the Main Engine Data (launch minus 9 seconds until MECO). This data arrives from Goddard Space Flight Center in Maryland, and is transferred over the network to the CSO facility.

The Engineering Display Change activity is an almost insignificant addition to the total network traffic. This activity involves a transfer from STS Primary to STS Backup and Spacelab 8/32. This transfer consists of the name of each engineering console format in the support facility that is changed during the prelaunch and launch period (launch minus 9 seconds to MECO) [MAUL84].

### 3.2 HOSC System Components

The Huntsville Operations Support Center as a distributed computer facility uses various computer resources interconnected together. The basic components involved at HOSC are the computers, communications processors that receive data from wideband communications links (satellite and terrestrial) and the hardware required to interconnect these various resources. The interconnecting hardware, Network Systems Corporation's HYPERchannel network, has been previously described, and interconnects a variety of computer resources of different manufacture, i.e., Digital Equipment Corporation (DEC), Perkin-Elmer (PE), and UNIVAC. The bulk of the processing power for the network is performed by the DEC VAX and PE 3240 computers. A cursory look will be given to these two computers. These computers are examined for the sake of information only, since in the subsequent analysis all network users will be represented as fixed rate data generators.

The Digital Equipment Corporation's VAX series of computers supports a 32-bit word architecture that establishes a virtual address space of 4.3 billion bytes of user-addressable memory. Throughput of data in the system is optimized by using a 32-bit high speed data structure that ties together the central

processor, main memory, UNIBUS subsystem, MASSBUS subsystem and the DR780 high speed direct memory access subsystem. This high speed data structure is known as the Synchronous Backplane Interface (SBI) and a device linked to it is known as a NEXUS. Each NEXUS receives every SBI transfer; electronic logic in the NEXUS determines whether it is the designated receiver for the ongoing transfer. Data transfers can occur from CPU to memory, from I/O controller to memory subsystem, or from CPU to I/O controller, with maximum aggregate transfer rates of 13.3 megabytes per second. These transfer rates are limited by the following factors:

- o 200 nanoseconds/cycle = 5 million cycles per second
- o each cycle can carry an entire byte of data or address representing a memory request
- o one cycle is used to request eight bytes of data to be read or written, and two cycles are used to carry data at four bytes per cycle
- o 5 million cycles/second \* 4 bytes/cycle = 20 million bytes/second
- o  $20 * \frac{2}{3}$  (1 of every 3 cycles is an address) = 13.3 million bytes per second [DEC80]

As is shown in Figure 3.2 , a VAX computer may interface with more than one memory subsystem. In the case of a two-controller, interleaved memory

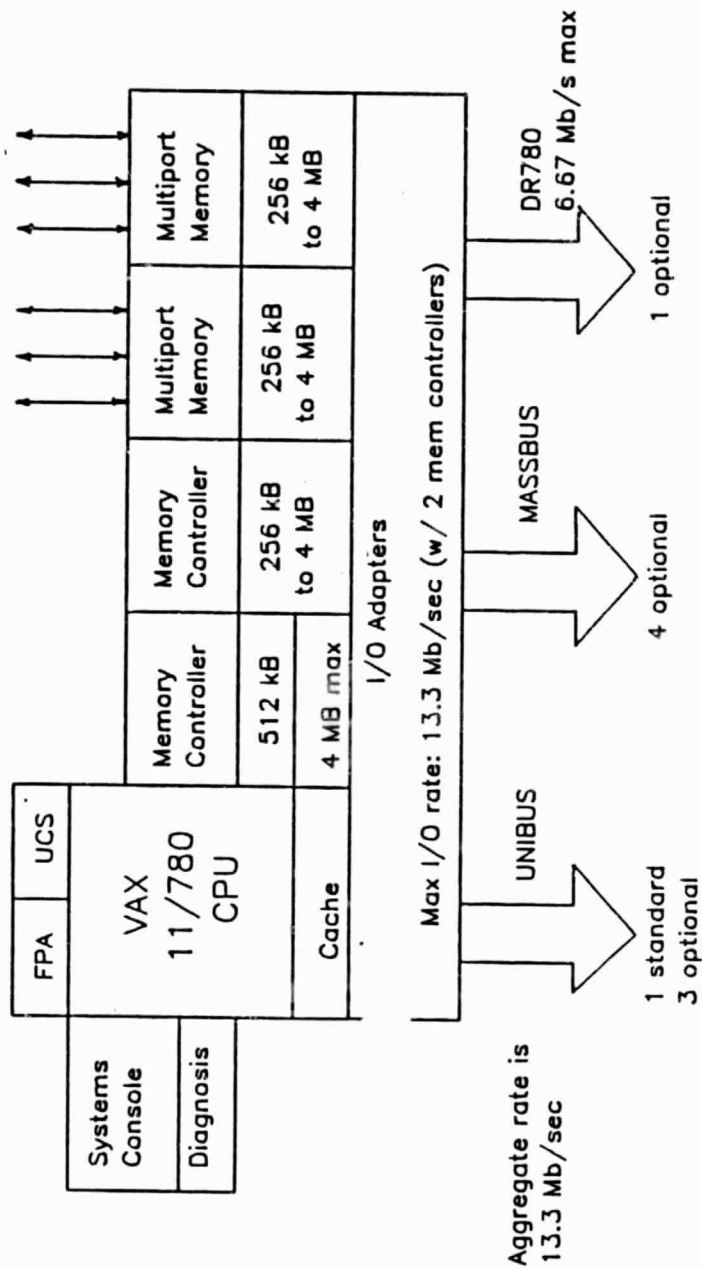


Figure 3.2 Block Diagram of VAX 11/780 Computer.

configuration, the computer would also have two NEXUS memory controllers on the SBI.

The UNIBUS Subsystem (UBUS) is a high speed, asynchronous data system that allows communication between peripheral hardware and the VAX computer. The VAX 11/780 is capable of supporting four UBUSes: one is standard, but three more are optional (Figure 3.3). The UBUS is connected to the SBI through a UBUS Adapter (UBA) which performs several important services that are transparent to the user. The UBA provides:

- o access to UBUS address space from the SBI
- o mapping of the UBUS addresses to SBI addresses for the direct memory access (DMA) transfers to the system memory
- o data transfer paths for UNIBUS device access to random SBI memory addresses and high speed transfer for devices that transfer to consecutive, increasing addresses
- o UNIBUS interrupt fielding
- o UNIBUS priority arbitration

The address-mapping function is especially important because the UBUS has only eighteen data lines providing an apparent memory-addressing capability of only 200 kilo-bytes. Through its address mapping abilities, the UBA provides the capability of mapping the UNIBUS addresses into the SBI addresses so that the



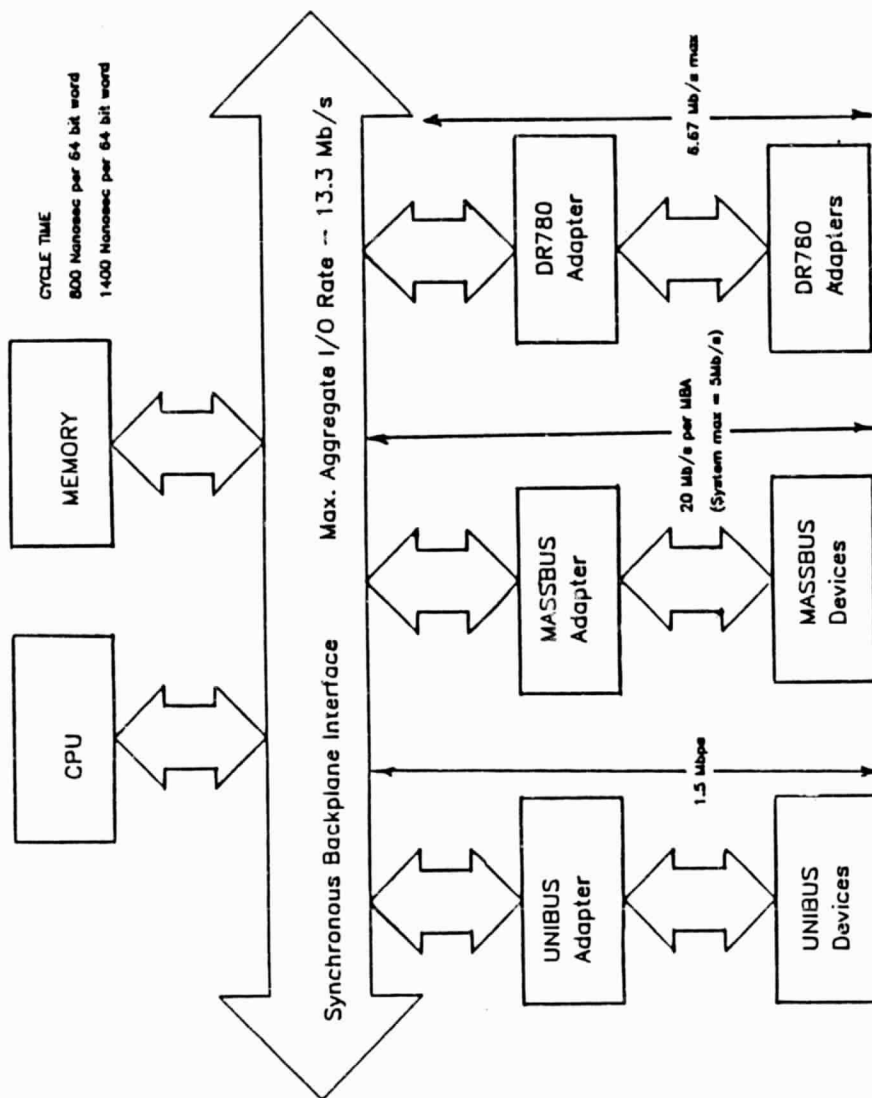


Figure 3.3 Bus Configuration of VAX 11/780.

full system memory of 16 array boards of 256 kilobytes each (4 gigabytes total) can be accessed.

The UBA accepts two forms of input from the UBUS: hardware-generated interrupts and direct memory access requests. Each device connected to the UBUS may use one of five priority levels for requesting bus service. A non-processor request (NPR), which is the highest priority request, may be used when the device requests an operation that does not require processor intervention, such as a direct memory access transfer to memory or to some other device. A bus request (BR) is thus generated when the device wishes to interrupt the UBA for service. Such service might be a CPU-directed data transfer or a flag indicating the existence of an error condition at the peripheral. Since there are only five priority levels and more than one device may be connected to a specific request level, if more than one device makes the same request, the device that is electrically closest to the UBA receives the highest priority.

The NPR request for direct memory access is a very important feature of the UBUS subsystem. These DMA transfers can be divided into two groups: random access of noncontiguous addresses and sequential access of sequentially increasing addresses. For random access, each UBUS transfer is made through the Direct Data Path

(DDP, one per UBUS) and is mapped into an SBI transfer. This procedure allows only one word of data to be transferred during a single SBI cycle. For devices capable of requesting sequential access services, use is made of the Buffered Data Path (BDP). Each UNIBUS provides fifteen such BDPs which store the data so that four UBUS transfers are performed for each SBI transfer.

The DDP must be used by devices not transferring to consecutively increasing addresses or by devices that mix read and write functions. The maximum throughput via the DDP is about 425 kilowords per second for write operations and about 316 kilowords per second for each read operation. These rates will decrease as other SBI activity increases [DEC80].

Maximum published throughput via the BDP is about 695 kilowords per seconds for both the read and write operations, but realistic throughput rates of only 1.5 megabits per second are actually expected with this figure degrading as other SBI activity increases. BDP transfers are restricted to block transfers with blocks of length greater than one byte. All transfers within the block must be to consecutive and increasing addresses and all transfers must be of the same function, either read or write.

The MASSBUS subsystem and the DR780 high performance, 32-bit parallel interface will not be described in this summary, since an understanding of their functional characteristics is not needed to determine their relative impacts on the HYPERchannel network. The influence of both may be felt indirectly, however, since activity on the MASSBUS or DR780 will translate to SBI activity which will affect DDP and BDP transfer rates as previously described.

The VAX CPU will also not be described in detail but several comments may be made about the CPU and its effects on system throughput. The CPU represents the most intensive traffic load on the memory subsystem and hence on the SBI. Obviously, if the processor is engaged in intensive computing, it will request data much more often than it will write data, and this memory access represents substantial SBI activity. Fortunately, the large cache memory of eight kilobytes available to the CPU is able to reduce the SBI traffic load considerably. In addition to the effects of the CPU on SBI activity, the SBI traffic from other sources may also affect the CPU efficiency. Published figures, [DEC80], indicate that in a system with two memory controllers the processor will be slowed by about four percent per averaged megabyte per second of I/O traffic, while the impact of a single memory controller

is to slow the processor by a factor varying from two to four. Table 3.2 summarizes the I/O characteristics of the DEC VAX 11/780 processing system.

The Perkin Elmer 3240 series of computers is also a high throughput machine with a 32-bit architecture. The HOSC currently uses two PE 3244 machines with primary responsibilities as front end processors receiving real-time data streams from the KSC firing room.

The 3244 memory subsystem is organized into banks, each capable of handling four megabytes of addressable memory. Total system memory ranges from 256 kilobytes in one bank to a full system complement of four 4-megabyte banks, for a maximum of 16 megabytes of addressable memory. All memory is connected to a common memory bus which consists of two unidirectional, asynchronous, 32-bit busses. One bus is dedicated to memory write functions and the other is dedicated to memory read functions (Figure 3.4).

Input/Output is accomplished using five external communication busses: one multiplexer bus for medium speed devices and a maximum of four high-speed Direct Memory Access (DMA) busses that each support eight high speed bidirectional ports. Each DMA port is controlled by a selector channel tied to the multiplexer bus that controls and terminates transfers through the CPU. Once

**TABLE 3.2 Summary of DEC VAX 11/780 I/O Characteristics**

<b>Processor:</b>	32-bit word architecture
<b>Main Memory:</b>	
Virtual address space:	4.3 billion bytes.
Cycle Times:	800 nanoseconds per 64 bit read. 1400 nanoseconds per 64 bit write.
<b>I/O UNIBUS Adapter</b>	
Maximum aggregate rate:	1.5 Mbyte/sec through BPD
Buffered Data Paths (BPD):	15 total, 8 byte buffer in each. 695 kilowords per second read and write. Used for fast data transfers.
Direct Data Path (DDP):	425 kilowords/sec for write and 316 kilowords per second for read. Used for transfers to nonconsecutive memory locations.

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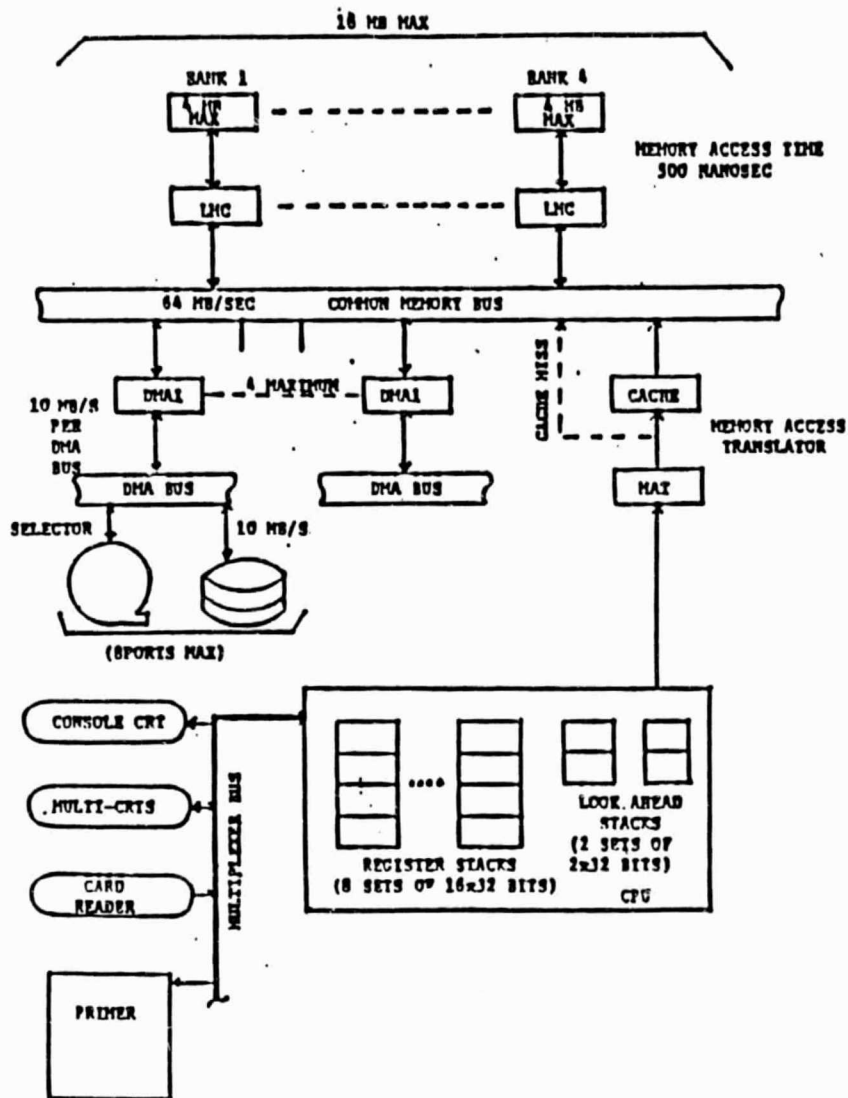


Figure 3.4 Block Diagram of PE 3244.

the channel is activated, the processor is released and is free to continue processing on an unrelated task. Published I/O transfer rates for the PE 3244 [MA bus indicate that transfer rates of up to 10 megabytes per second in the burst mode are possible for each DMA bus [PEC81]. The I/O characteristics of the PE 3240 series is summarized in Table 3.3 [MAUL84].



TABLE 3.3 Summary of Perkin Elmer 3240 I/O  
Characteristics

Processor:	32 bit/word.
Main Memory:	
Virtual Address Space:	16 Megabytes.
Cycle Time:	500 nanoseconds.
DMA Bus Data Transfer Rate	
Burst Mode:	10 Megabytes per second with a maximum of 4 DMA busses per system.

## Chapter 4

### Software Design Description

This chapter describes the development of the software used to model the HYPERchannel network. The intent of the simulation is to accurately model the characteristics of a HYPERchannel network. While, every possible function of the network is not characterized, the protocols which have the most impact on the network were included to the extent possible. The goal of the simulation is to provide a software tool to analyze the characteristics of present and future configurations of the network at HOSC.

#### 4.1 Software Functions

The simulation model as developed should perform some primary functions, among these are:

- 1) provide a relatively easy method of simulating the existing system and provide a means for modifying the simulation environment so that different configurations may be modeled.
- 2) provide an output which may be meaningfully converted to performance measures described in this Chapter and Chapter 5.
- 3) provide a user friendly interface at all levels of user interaction.

The software should be designed to be as portable as possible so that transferral from the development computer to other computer environments should be accomplished as easily as possible. Also, any future

enhancements of the algorithm as designed, should have the capability of being accomplished as easily as possible.

Finally, the development of this simulation as related to the ISO-OSI model for distributed computer processing (Appendix II), may be thought of, as having been developed between levels 5 and 6, the Session and Presentation levels.

#### **4.2 Design Constraints**

The primary design constraint placed on this simulation effort was that the simulation be as transportable as possible between computers of unspecified size and capabilities. Therefore, the language PASCAL was chosen due to its widespread availability and richness of data structures.

#### **4.3 Design Specifications**

This section deals with the imposed constraints and assumptions which the model uses to accomplish its simulation activity. These assumptions were made to keep the model both realistic and manageable.

##### **4.3.1 Simulation Assumptions**

In order to maintain viability and model validity certain assumptions were made. These assumptions are as follows:

- 1) Every time an adapter requests the trunk, the frame sequence sent is a message-with-data sequence. Therefore, message-only sequences are excluded.
- 2) Maximum number of trunks is two.
- 3) Model will reduce to a single trunk model.
- 4) Any single adapter may be attached to both trunks (dual trunk model) (1,2,...,N)
- 5) Trunk lengths are less than, or equal to 1000 feet, Belden 9248 cable data is used (propagation time).
- 6) Worst case fixed delay, priority delay, and end delay will be used, as given by [FRAN84].
- 7) In order for the model to resemble reality as closely as possible, measured transmission frame times will be used ([WATS82],[FRAN82]).
- 8) Intra-adapter communication is not allowed.
- 9) The wait flip-flop option is not implemented.

#### 4.3.2 Parameter Definition

As previously stated worst case values of fixed delay, priority delay, and end delay are used in the simulation. The expression used to evaluate the fixed delay on a given trunk is given by:

$$\text{Fixed delay} = 4 \text{ nsec} * (\text{trunk length}) + 2.08 \text{ usec} \quad (1)$$

where trunk length is given in feet. This value approximates, but is greater than, twice the end-to-end

propagation time for the trunk, plus the time required by the adapter to formulate and to begin transmitting a response. This value is the same for each adapter on a given trunk.

The highest priority adapter is assigned a priority delay of 0.48 usec. The priority delay for the remaining adapters on a given trunk is given by:

$$\begin{aligned} \text{Priority delay (K)} &= \text{Priority delay (K-1)} \\ &\quad + 4 \text{ nsec} * d + 1.6 \text{ usec}, \quad (2) \\ K &= 2, 3, \dots, L \end{aligned}$$

where K is the index of the adapter with priority K and d is the distance in feet between the adapter with priority K and the adapter with priority (K-1), L refers to the lowest priority adapter. The constant 1.6 usecs is added to alleviate problems with line reflections.

The end delay of the adapter with priority K is given by:

$$\begin{aligned} \text{End delay (K)} &= \text{Priority delay (L)} \\ &\quad + 4 \text{ nsec} * d + 1.6 \text{ usec}, \quad (3) \\ K &= 1, 2, \dots, L \end{aligned}$$

where L is the lowest priority adapter, and d is the distance, in feet, from the adapter with priority K to the adapter farthest from it [FRAN84].

These are the major parameters which need to be calculated for a given configuration of the HYPERchannel network. They are calculated for a given configuration when the simulation program is executed.

#### **4.4 Algorithm Description**

In this section an overall view of the activity of the simulation is detailed. Detailed descriptions of the individual modules used by the program are found in Appendix III.

##### **4.4.1 Overall Simulation Activity**

The simulation as developed is a discrete event simulation. The event that drives the model is an adapter's next scheduled transmit time. An adapter trying to transmit will attempt to obtain a trunk in three given time frames. An adapter may try to transmit while the trunk is busy, during the priority delay or scheduling period, or finally, in the contention period. If an adapter attempts to transmit while the trunk is busy its next transmit time is adjusted to its scheduling period time (priority delay). If an adapter attempts to transmit during the scheduling period one of two possibilities exist: 1) it attempts to transmit after fixed delay but before its priority delay event and 2) it attempts to transmit after its priority delay event but before the end delay event. In the first case, the adapter is allowed to transmit at its

priority delay event and in the second case, the adapter is forced to wait until its end delay event is signalled. This is in accordance with NSC's trunk access protocol. An adapter attempting to transmit during the contention period is allowed to do so provided that the trunk is sensed idle. Once the adapter has gained access to a trunk through the trunk access protocol as modeled, it will proceed to send its message sequence.

In Figure 4.1, a complete message-with-data sequence is shown. Appropriate timing and program flags (M1 through M6) are indicated. The algorithm shown in Figure 4.2, in flow diagram form, illustrates the overall activities of the simulation program. Using these two figures a basic description of the program flow may be performed. The first three blocks in Figure 4.2 perform initialization of program variables, definition of the network configuration, and prints a description of the network to the auxiliary file Auxout maintained by the program. Once trunk access has been granted (previously described) an adapter will attempt to send transmission frames and data frames. Program flags are used to indicate where in the message-with-data sequence the present transmitting adapter is located. The various update blocks (Case1 through Case7) update timing, bit counts, and flags.

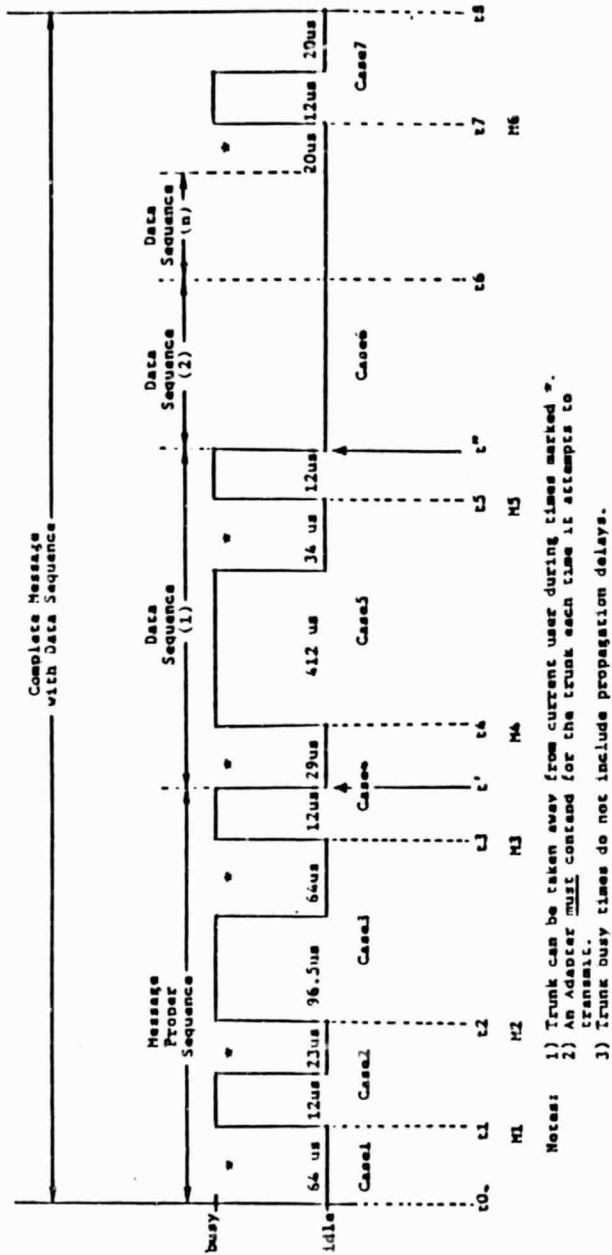


Figure 4.1 Message-with-Data Sequence for Simulation.



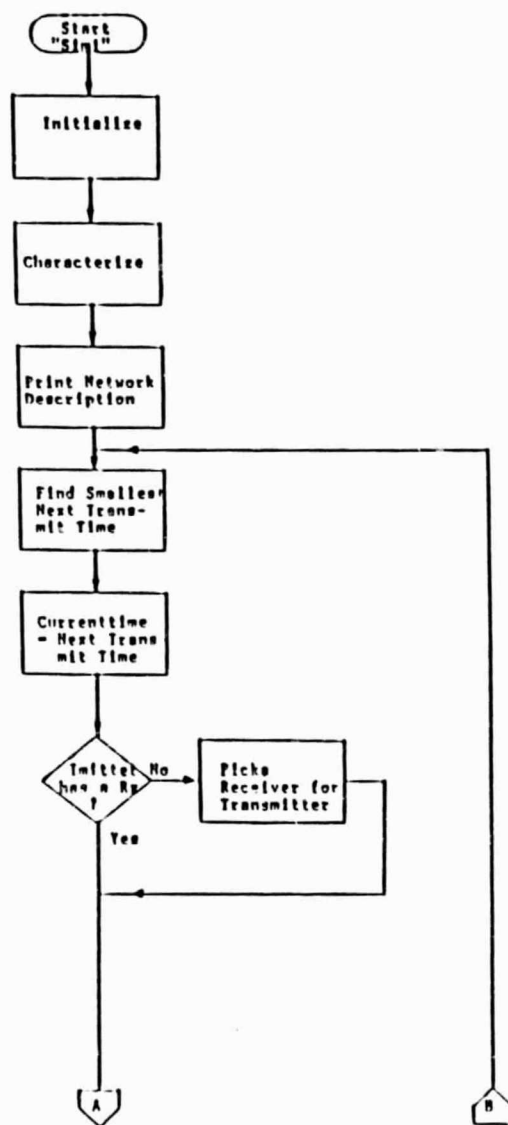


Figure 4.2 Flow Diagram of Simulation Activity.

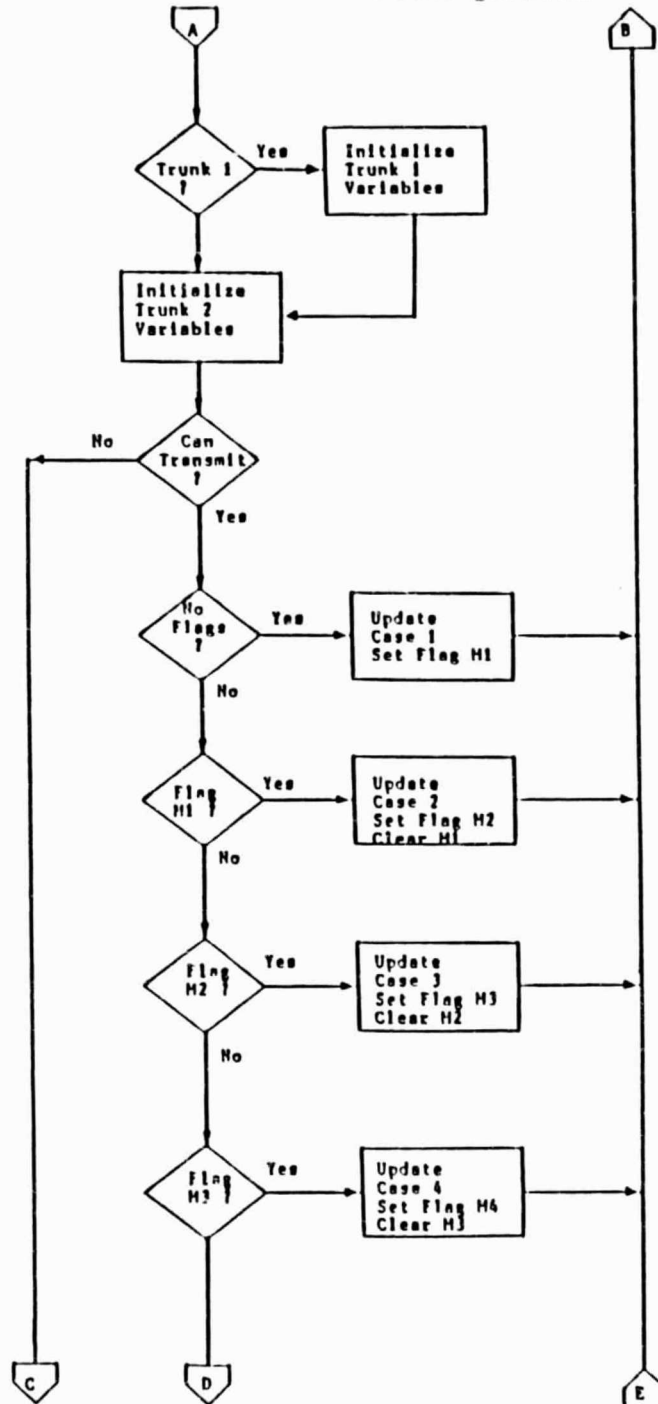


Figure 4.2 Continued.

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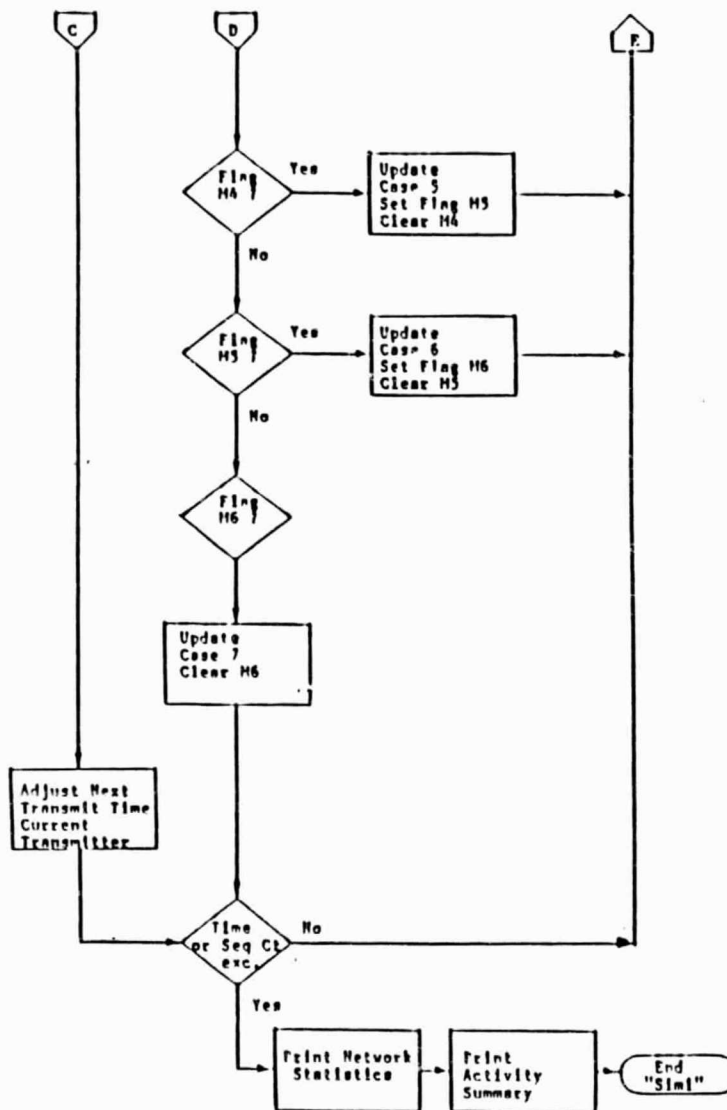


Figure 4.2 Continued.

Case2 incorporates the adapter reservation scheme (Figure 2.9). If a receiving adapter can be reserved for the transmitting adapter the message sequence transmission will continue, otherwise, the adapter will return to case2 each pass through the loop, until it reserves its receiver or aborts its transmission. The message proper frame is updated in case4. A message length of 64 bytes is assumed for convenience. Case5 updates the transmission segment in which a data block is sent. In case6, determination of whether or not another data sequence needs to be sent (based on the attached device's buffer size) is made. If another data block is required, then the period of time  $t' - t''$  will be repeated, this will continue as required. In case7, updates to message delay (the time difference between initial transmission time and the final transmission time), trunk sequence transmission tally, and adapter next transmission time are performed. The transmitting and receiving adapter's are released for other transmissions in case7 also. The simulation will continue until the user defined maximum time or the maximum number of message sequences is exceeded. The simulation will then print output statistics to an interactive terminal and an output file.

#### 4.4.2 Model Set-Up

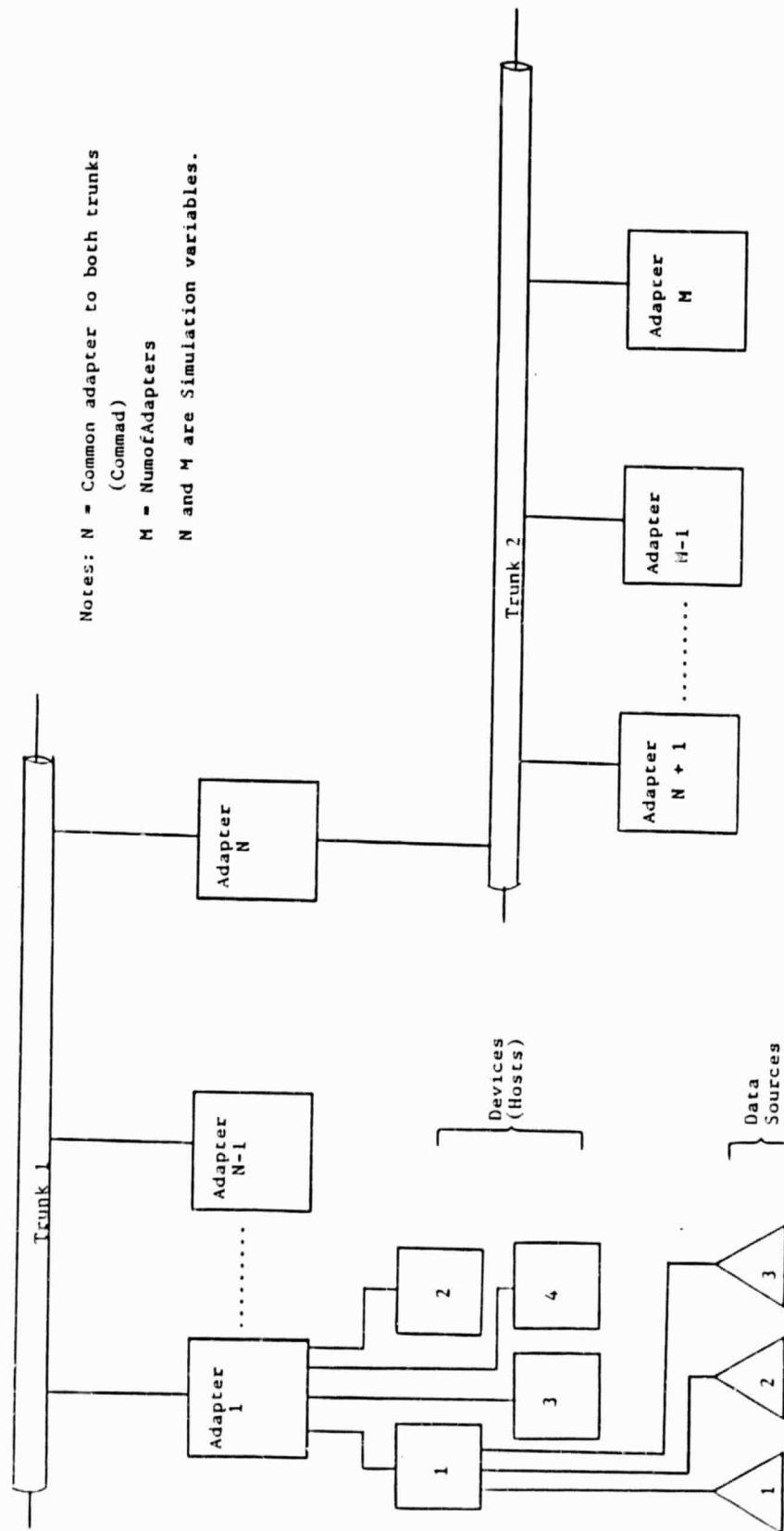
Figure 4.3 illustrates the basic set-up of the network configuration which the simulation program operates on. All configurations to be modeled should be set up according to this diagram. In the case of a single trunk configuration, adapters 1 through N are used.

The simulation (Sim1) uses this model configuration to properly identify and characterize the network adapter's, their attached devices, and data sources.

#### 4.5 System Files

There are three files associated with the simulation: program, Dfile, and Auxout files. The program file (Sim1) may be maintained as either source or object code since normal operation of the program requires no changes to the program file. The files Dfile and Auxout are maintained as standard ASCII text files. Dfile contains a description of the network, and is used by the program file for parameter values. Auxout contains a text description of the network and is used to store output statistics from a particular program execution.

At the beginning of a program execution, an interactive query allows the user to use the network configuration defined in the Dfile or define a new



Notes: N = Common adapter to both trunks  
(Commad)  
M = NumofAdapters  
N and M are Simulation variables.

Figure 4.3 Model Set-Up for Simulation.

configuration, which is then placed in this file. The auxiliary file Auxout, is a print formatted file and may be directed to a printer for a hard copy of a program execution's statistics. Additionally, Auxout is totally maintained by the program file and thus is transparent to the user until a print out of a simulation run is desired.

#### 4.6 Reported Statistics

The network statistics, as compiled by the model, are such that they allow the computation of measures which indicate network performance. These measures are defined as follows:

- o D: The delay that occurs from the time an adapter becomes ready to transmit a message sequence until it actually completes its transmission.
- o S: The throughput of the local network; reported as the total rate of data transmitted over the network.
- o U: The utilization of the network; this is given as normalized throughput.
- o G: Offered load; the total rate of data presented to the network.

where possible the statistics necessary to calculate these measures will be reported for the entire network, the individual trunks, and the individual adapters.

#### 4.7 Validation Criteria

While every attempt has been made to make this simulation as close to the real system as possible, software implementation of an electronic system has its limitations. This simulation effort has been aimed primarily at modeling the various protocols implemented by a HYPERchannel network. It has been shown that these protocols are the factors having the most impact on system performance [FRAN84], [WATS80], [DONN79], and so on. Therefore, the simulation was designed to model these parameters as closely as possible. The validity of this model rests on a clear understanding of the operation of HYPERchannel networks and the relationship of this operation on system performance.

Finally, it was not feasible or practical to establish a validation test bed at HOSC. This due largely to the requirements placed on the facility and its stated mission. Thus, the model validation was done empirically, based on knowledge of the HYPERchannel system and the components attached at HOSC.



## Chapter 5 Model Analysis and Conclusions

In this chapter some of the theoretical considerations involving HYPERchannel network performance measures will be developed. The results of exercising the model in various configurations (based on the HOSC system and components) will be presented. Finally, the conclusion section, will attempt to describe the results and their relation to operating conditions at HOSC.

### 5.1 Theoretical Performance Bounds

In Chapter 4, several statistics were discussed as being important indicators of network performance. These were identified as S, U, and D. S defined as throughput, is the rate of data flow on the network. U or utilization, is normalized throughput, this being the fraction of network capacity being utilized, and finally, D or delay, is the delay between the time an adapter requests the trunk and the time at which it completes a transmission. In order for the experimental values to have meaning, some theoretical determination of these statistics is needed so that comparisons may be made. In order to determine theoretically these values, the network factors which most affect HSLN performance must be known. The factors which affect

this performance, independent of the attached equipment are:

- o Bandwidth
- o Propagation delay
- o Number of bits per frame
- o Local network protocol
- o Offered load
- o Number of stations [STALL84]

The first three of these factors determine a parameter  $a$ , from which the network utilization  $U$ , and throughput  $S$  may be determined.

Since a local area network is distinguished from long haul networks and multiprocessor systems by the bandwidth ( $B$ ) and distances ( $d$ ) involved. The product of these two terms ( $B * d$ ) can be used to characterize the network. The transmission length of the medium may be determined by dividing this quantity by the propagation velocity ( $U$ ) of the medium. This quantity may be calculated as follows:

$$\text{Transmission Length} = \frac{B * d}{U}$$

Network Systems Corporation suggests a value of 40 percent of the speed of light be used for propagation velocity when attempting to establish network performance. Using the value of 50 Megabits per second for  $B$ , assuming  $d$  to be 1000 feet, and using a

value of  $1.2 \times 10^8$  meters/sec for propagation velocity, the theoretical transmission length of a 1000 foot HYPERchannel network is 127 bits.

The ratio of transmission bit length, to the length of a typical frame (L) is the dimensionless quantity  $\underline{a}$ . Thus,

$$\underline{a} = \frac{\text{transmission length of trunk}}{\text{typical frame length (bits)}}$$

or

$$\underline{a} = \frac{Bd}{UL}$$

Since  $d/V$  is the worst case propagation time on the medium it may be replaced with the HYPERchannel Fixed Delay. Recalling from Chapter 4 that Fixed Delay may be calculated as

$$\text{Fixed Delay} = 4 \text{ nsec} * (\text{trunk length}) + 2.08 \text{ usec},$$

the parameter  $\underline{a}$  may be calculated as

$$\underline{a} = \frac{B}{L} * (\text{Fixed Delay})$$

Thus for a HYPERchannel trunk of length 1000 feet,  $\underline{a}$  is determined to be 0.0109. Typical values of  $\underline{a}$  for a HSLN range from 0.01 to over 1. An intuitive discussion of the meaning of the parameter  $\underline{a}$  is found in William Stallings's Local Networks. This parameter is used to

provide an upper bound on the utilization of the network, Stallings also points out that this hypothesis appears to be supported by experimental evidence; a part of this discussion follows:

....Consider a perfectly efficient access mechanism that allows only one transmission at a time. As soon as one transmission is over, another node begins transmitting. Furthermore, the transmission is pure data--no overhead bits.... what is the maximum possible utilization of the network? It can be expressed as the ratio of total throughput of the system to the capacity or bandwidth:

$$\begin{aligned}
 U &= \frac{\text{throughput}}{B} \\
 &= \frac{L/(\text{Propagation} + \text{transmission time})}{B} \\
 &= \frac{L/(D/V + L/B)}{B} \\
 &= \frac{1}{1 + a}
 \end{aligned}$$

So, utilization varies inversely with a [STALL84].

Table 5.1 shows an example using a to predict the theoretical bounds on a network similar to the system at HQSC. Unfortunately, this method does not account for the access protocol of the network. Furthermore, it assumes that the maximum propagation time is incurred on each transmission and that only one transmission may occur at a time. Despite these shortcomings, upper

Table 5.1 Theoretical Bounds on a HYPERchannel  
Trunk of Length 1000 Feet.

$$\text{Fixed Delay} = 6.08 \text{ usec}$$

$$\text{Bit Length} = 127.0325 \text{ bits}$$

$$\underline{a} = 0.0109$$

$$U = \frac{1}{1 + \underline{a}} = 0.9892$$

$$S = U * B = 49.46 \text{ Mbits/sec}$$

For an arbitrary period of time,  $t$ , the total bits transferred are:

$$\text{Total Bits} = S * t$$

$$\text{for } t = 40 \text{ seconds}$$

$$\text{Total Bits} = 1978 \text{ Megabits}$$

bounds on throughput and utilization may be calculated using these techniques.

Another derivation of utilization which takes into consideration the effects of the protocol on the network performance, based on the work of Robert Metcalfe and David Boggs [METC76] is considered. Their work is based on the Ethernet system which is a local area network operating under a CSMA/CD medium access protocol with characteristics similar to HYPERchannel.

Assume that there are  $N$  active nodes on the network, each having identical data generating characteristics. Furthermore, after a station has transmitted its packet, another station becomes ready to transmit its packet, so that  $N$  also represents the total offered load on the network. Stallings in his amplification of [METC76] notes that time on the network may be divided into two components: transmission interval (time required to transmit a complete packet over the medium) and a contention interval (sequence of slots with a collision or no transmission). Throughput then, becomes the ratio of time transmitting to the total time.

Recall that  $a$  may be written as

$$a = \frac{\text{propagation time}}{\text{transmission time}}$$

where the propagation time is the worst case value of time to transmit a frame over the medium, and transmission time is the time required to get a complete frame onto the medium. If transmission time is normalized to one, then  $a$  becomes propagation time. The minimum length of the transmission slot must be chosen to allow for the detection of a collision and is equal to twice the end-to-end propagation time ( $1/2a$ ).

Following Stalling's approach for the development of the equations describing throughput and utilization, the average length of the contention interval is determined by first computing  $A$ , the probability that exactly one station attempts a transmission in a slot and acquires access to the medium. This is the binomial probability that any one station attempts to transmit and the others do not,

$$A = \binom{N}{1} p^1 (1 - p)^{N-1}$$

$$= Np(1 - p)^{N-1}$$

which is the probability that the desired occurrence (acquisition of the trunk) will occur in  $N$  independent trials. Since maximum throughput and utilization are the quantities of interest, maximizing  $A$  will require that  $p = 1/N$  so that,

$$A = (1 - 1/N)N - 1$$

The estimated mean length of contention interval,  $w$ , in slots is,

$$\begin{aligned} E[w] &= \sum_{i=1}^{\infty} i * \text{Pr}[i \text{ slots in row with a collision} \\ &\quad \text{or no transmission followed by a} \\ &\quad \text{slot with no transmission}] \\ &= \sum_{i=1}^{\infty} i(1 - A)^i A \end{aligned}$$

which converges to,

$$E[w] = \frac{1 - A}{A} \quad [\text{STALL84}].$$

The maximum value of utilization may now be determined, which is the length of a transmission interval as a proportion of a cycle consisting of a transmission and a contention interval

$$\begin{aligned} U &= \frac{\text{transmission time}}{\text{total time}} \\ &= \frac{\text{transmission time}}{\text{transmission time} + \text{contention time}} \\ &= \frac{1/2a}{1/2a + (1 - A)/A} \\ &= \frac{1}{1 + 2a \frac{1 - A}{A}} \end{aligned}$$



For the 1000 foot HYPERchannel network previously described, assuming  $N = 4$ ,  $U = 0.971$  and  $S$  is 48.55 Megabits per second which corresponds nicely with the results obtained using only  $a$  (Table 5.1).

The calculation of the parameter  $D$  or message delay is not so obvious. It appears empirically, that  $D$  increases without bound as the network approaches saturation. As the number of nodes increases, so do the number of access requests, the number of collisions, the number of retransmissions and also the time delay a node experiences before access is obtained, so  $D$ , does appear to increase without bound.

## 5.2 Presentation of Simulation Results

The previous section presented analytical techniques useful for predicting the peak, or upper limits of a HYPERchannel network's performance. While this is useful for predicting top end performance, it does not provide any useful information about a particular configuration of the network.

The purpose of this simulation effort is to provide the engineers and scientists at HOSC with a software tool which will provide information on network performance in a variety of configurations. This section presents results from this model for the network descriptions shown in Figures 5.1 and 5.4. Detailed descriptions of these configurations, along

with simulation results are given in section 5.2.1 and the results for a dual trunk configuration are given in section 5.2.2.

#### 5.2.1 Single Trunk HOSC Results

The single trunk configuration, as shown in Figure 5.1, and defined in terms of the model in Appendix IV, was considered. Table 5.3 contains a listing of the relative probabilities that a given transmitter will attempt to transmit to a given receiver. This is used by the simulation to establish the virtual connection between devices for communication. In order to gauge the performance of this configuration over a wide range of input loading, the topology of the network as defined was kept constant. The offered load to the network was varied by increasing the data source generation rates to the devices shown.

Table 5.2 illustrates the method for computing system performance measures from simulation statistics. Tables 5.4 and 5.5, contain data points calculated from simulation runs, with each data point representing a simulation run. These data points were plotted as shown in Figures 5.2 and 5.3.

Table 5.2 Calculation of Parameters using  
Simulation Statistics.

$$S \text{ (throughput)} = \frac{\text{Total Bits Transmitted}}{\text{Simulation Time}}$$

$$U \text{ (utilization)} = \frac{S}{\text{Bandwidth}}$$

$$= \frac{S \text{ (bits)}}{50 \text{ Mbits per second}}$$

$$D \text{ (delay)} = \frac{\text{Avg. Message Delay Device 1} + \text{Avg. Message Delay Device 2} + \dots + \text{Avg. Message Delay Device n}}{n}$$

The above expression for delay is used in the case where transmitting devices have finite Average Message Delays. For the case where a transmitting Device attempts to transmit messages but has an Average Message Delay equal to zero (Average Message Delay = 0, and Abort count > 0) it is assumed, that Message Delay, or Delay, for the Network exceeded simulation time.

Offered Load is compiled by the simulation and output as one of its statistics.

Table 5.3 Relative Probabilities for Transmitter/  
Receiver Pairs for Figure 5.1.

Transmitter/Receiver	Probability
111-311	0.7
111-321	0.3
211-431	1.0
221-421	1.0
311-211	0.01
311-221	0.01
321-211	0.01
321-221	0.01
331-421	1.0

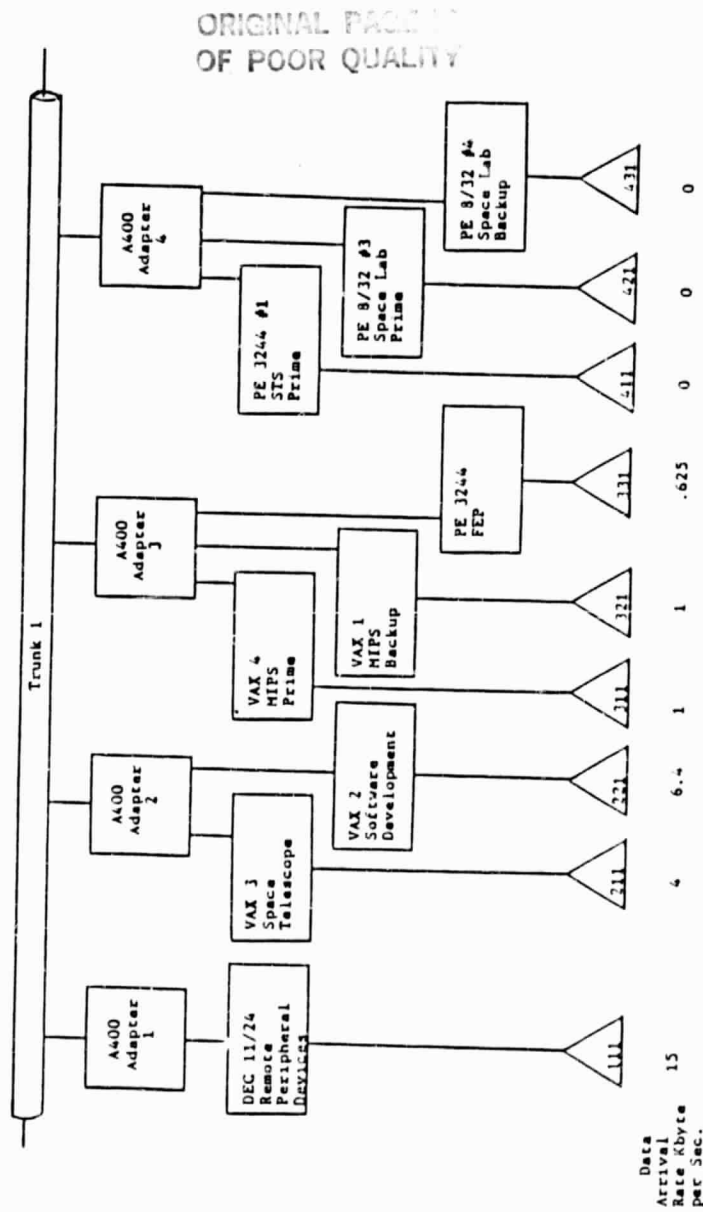


Figure 5.1 Single Trunk Simulation Set-Up.

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Table 5.4 Data Points for Figure 5.2

S Mbytes/sec	U	G Mbytes	Average D secs
.0008092	.0001295	.0234998	.0009933
.0024680	.0003949	.0470083	.0021883
.0040020	.0006403	.0705255	.0019500
.0067190	.0010751	.1121140	.0017833
.0142275	.0022764	.2242640	.0016166
.0290956	.0046553	.4486710	.0015533
.0431299	.0069008	.6733410	.0016950
.0586719	.0093875	.8984520	.0016283
.0730755	.0116921	1.1224500	.0015116
.1421105	.0227377	2.2420000	.0018583
.2118972	.0339036	4.4840000	.0042466
.3202813	.0512450	6.7297000	.3875766
.5137168	.0821946	8.9692300	.0064750
.5548880	.0887821	11.2103000	.0042916
.9360150	.1497624	22.4200000	>40
1.5409865	.2465578	44.8401000	>40
2.3634718	.3781550	67.2603000	>40
2.3250275	.3720044	89.6800000	.4622500
3.4732500	.5557200	224.2000000	>40
3.6444500	.5831120	448.4000000	>40
4.5387500	.7261400	672.6000000	>40
4.6086250	.7373800	896.8000000	>40
4.6531500	.7445040	1121.0000000	>40
4.7345000	.7575000	2242.0000000	>40
4.3516500	.6962640	4340.0000000	>40
4.8016750	.7682680	6726.0000000	>40
4.8004000	.7680640	8968.0000000	>40
4.7978500	.7676560	11210.0000000	>40

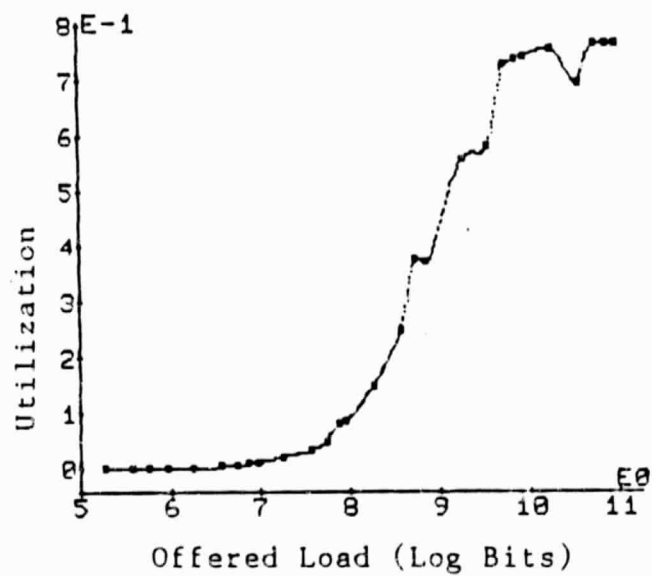


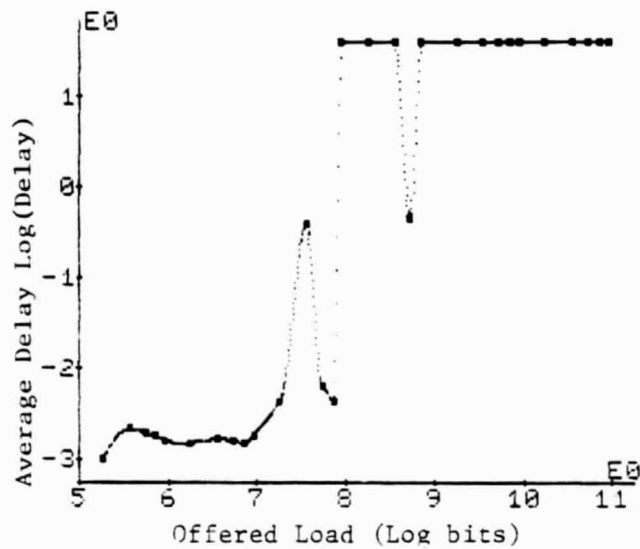
Figure 5.2 Utilization versus Offered Load  
for Single Trunk Simulation.

Table 5.5 Data Points for Figure 5.3.

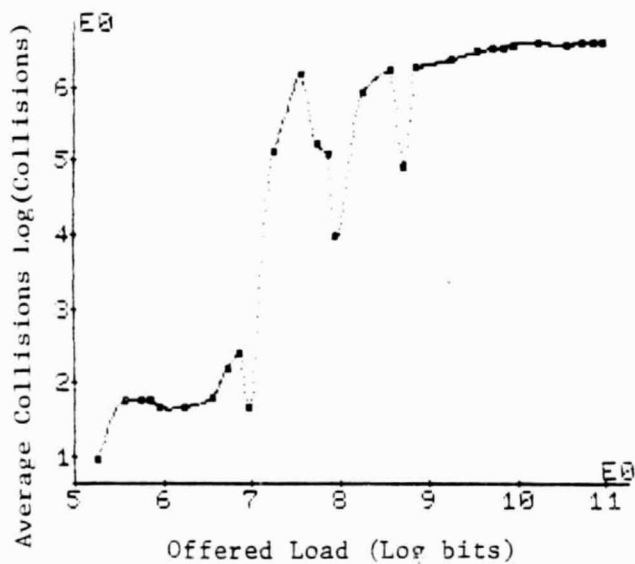
Control Bits Mbits	Data Bits Mbits	G Bits Mbits
.1005832	.177536	.1879984
.3076200	.520456	.3760664
.4885992	.854160	.5642040
.6720912	1.163416	.7210600
.7758192	1.374581	.8969120
1.6394960	2.914616	1.7941120
3.3552960	5.960952	3.5893680
5.0973920	8.719360	5.3867280
6.8325440	11.977040	7.1876160
8.4246400	14.989760	8.9796000
16.4381200	28.992240	17.9360000
27.1168800	40.690160	35.8720000
43.6347200	58.911760	53.8376000
62.5479200	101.864000	71.7538400
74.7621600	102.807200	89.6824000
134.9088000	164.616000	179.3600000
204.0576000	289.070400	358.7208000
347.8608000	408.488000	538.0824000
353.9296000	390.079200	717.4400000
539.0768000	572.364800	1793.6000000
685.7088000	480.517600	3587.2000000
582.9048000	869.376000	5380.8000000
564.0320000	910.728000	7174.4000000
564.3920000	924.616000	8968.0000000
543.6464000	971.392000	17936.0000000
624.7024000	767.824800	34720.0000000
527.8368000	1008.696000	53808.0000000
528.1136000	1008.008000	71744.0000000
528.7168000	1006.600000	89680.0000000



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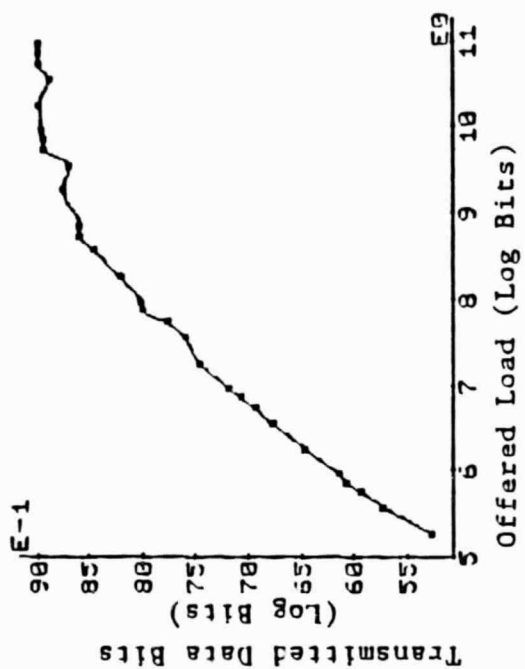


(a)

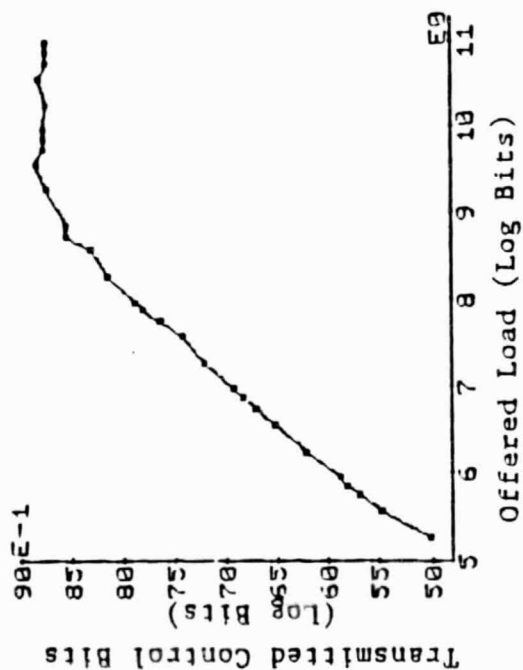


(b)

Figure 5.3 Plot of Transmitted Control and Data Bits  
versus Offered Load for Single Trunk Simulation.



(d)



(c)

Figure 5.3 Plot of Transmitted Control and Data Bits versus Offered Load for Single Trunk Simulation.

The system configuration and data flow rates indicated in figure 5.1 are a typical loading of the main trunk of the HOSC system. The total offered load (G) for the system as depicted in figure 5.1 is computed as follows (G the offered load is the total number of data bits offered to the channel):

DEVICE	DATA ARRIVAL RATE
111	15 kbytes/sec = 120 Kbps
211	4 kbytes/sec = 32 Kbps
221	6.4 kbytes/sec = 51.2 Kbps
311	1 kbytes/sec = 8 Kbps
321	1 kbytes/sec = 8 Kbps
331	.625 kbytes/sec = 5 Kbps
411	0
421	0
431	0

TOTAL OFFERED LOAD = 224.2 kbps.

In a 40 second period a total of 8.976 Mbits or 6.953 (Log bits) would be offered for transmission across the HYPERchannel™ network. Referring to figure 5.2 the utilization of the HYPERchannel trunk for this offered load is approximately 2%. The throughput rate is thus  $(.02) * (50 \text{ Mbits per second}) = 1 \text{ Mbps}$ . Obviously the system is nowhere

near its upper limit in data throughput rate, trunk utilization and hence not in offered load.

The approximate number of total bits transmitted to send a 2 kbyte block of data may be estimated from figure 2.8 using Table 2.2 as a reference. From figure 2.8 it is apparent that 7 transmission frame format fields, 9 response frame fields, and 2 response frames with data format fields are transmitted to accomplish the transmission of 2 kbytes of data. This amounts to an absolute minimum transmission of 19600 bits total for 16000 bits of data or absolute minimum overhead of 22.5%. For longer data blocks the overhead is a smaller percentage and may be calculated by the relationship (assuming no collisions):

ABSOLUTE MINIMUM TOTAL BITS SENT

PER 2 KBYTES OF DATA       $= 19600 + (N-1)18600$

where                       $N =$  the number of 2 kbytes of data.

The reduction in transmission overhead for multiple transmission of data segments of 2 kbytes of data is not significant in number of bits transmitted but the timing and number of times the channel is free for contention is reduced by a significant amount. It will be observed from the

simulation runs that an average overhead of 50% for low offered load and 100% for high offered load is the case. This overhead increase is due to the non-integer multiples of 2 kbytes of data to be sent and to collisions.

Figure 5.3 depicts the average delay and number of collisions versus offered load. The average delay is an aggregate delay number and a large delay is indicative that at least one device is experiencing a large delay. Thus it may indicate that only one device is unable to transmit but all the remaining devices may be transmitting satisfactorily. However it is an indicator that things are beginning to sour on the overall network performance.

Likewise the number of collisions is an aggregate sum and indicates the relative number of retry transmission attempts the system is experiencing. Since the HYPERchannel is not a pure contention system (such as ETHERNET) the increase of collisions does not necessarily indicate accompanying data loss or absolute inability of an adapter to communicate. Again it is an indicator that things are not so well on the overall network.

From the results of figure 5.3 it is apparent that as the offered load increases past about 7.5 (31.62 Mbits for 40 seconds or 790 kbits per second) the system is beginning to experience traffic congestion. The system's trunk utilization, figure 5.2, is seen to start a rise at this point (7.5) of offered load and it may be observed that at an offered load of about 9.5 (3162 Mbits for 40 seconds or 79 Mbits per second) the trunk utilization is entering saturation. At this point it is safe to say that some devices are just not able to transmit all their data. Somewhere in between these two offered loads is a point that would do well to be identified as the maximum useful offered load condition. Using the rule of thumb for normal maximum operating offered load for pure contention systems (ETHERNET is an example of a pure contention system) the maximum operating offered load would be set to approximately  $1/2e$  or 18.35% of the channel bandwidth. For slotted contention systems this rule of thumb figure is approximately  $1/e$  or 36.7%. The HYPERchannel is a hybrid priority/contention system with prioritized time slotting and it is reasonable to expect to load the system to the 36.7% trunk utilization. Inspecting

the graph of trunk utilization versus offered load, figure 5.2, it is observed that the offered load for a utilization figure of 36.7% is approximately 8.5 (log bits) or a 7.9 Mbps aggregate rate (316 Mbits in a 40 second).

Inspection of the graphs for the transmitted control bits and the transmitted data bits versus offered load, figure 5.3, also illustrate that at 8.5 offered load the control bits and data bit curves start to enter saturation. Thus it is reasonable to state that the maximum operating offered load (in pure aggregate rate data bits) should be 8.5. This is an aggregate rate of offered data of 7.9 Mbps or 15.8% of the channel bandwidth of 50 Mbits. Remember that an absolute minimum of 22.5% overhead is needed at low collision rates and thus 7.9 Mbps of offered data plus 22.5% overhead is approximately 9.6775 Mbps or 19.35% of the channel bandwidth. (This assumes all data blocks are integral 2 Kbytes in size).

A further comment of the figure 5.3c and 5.3 d is in order. The offered data to the channel, G, (see Table 5.5) is only the actual data to be transmitted. The actual number of data and control bits required (as evidenced from the simulation

runs), which when added together equal the channel throughput  $S$ , will not equal  $G$  but be greater than  $G$ .

It should be observed that for low offered load the actual transmitted bits on the channel amounts to 2.54 times the offered load and at high offered load this figure decreases to about 2 times the offered load until saturation takes place. This apparent increase in efficiency is misleading since the prioritized time slotting mode of operation replaces the contention portion of the channel algorithm and stagnation of the throughput ( $U*B$ ) takes place.

Thus the 7.9 Mbps offered aggregate load corresponds to about 16 Mbps to 18 Mbps actual channel offered total load or 36% of the channel bandwidth.

FROM THIS DISCUSSION AND THE SIMULATION RESULTS COUPLED WITH THE ANALYTICAL RESULTS

IT IS RECOMMENDED THAT THE TOTAL AGGREGATE OFFERED DATA TO THE HYPERchannel SHOULD BE HELD TO 8 Mbps OR LESS. IN FACT DUE TO THE UNCERTAINTY OF ESTIMATING AGGREGATE DATA RATES A MAXIMUM OF 4 Mbps WOULD SEEM PRUDENT.



### 5.2.2 Dual Trunk HOSC Results

The dual trunk configuration as shown in Figure 5.4 and detailed in Appendix V, was considered. Once again, the relative probabilities for transmitter/receiver pairs in this configuration are contained in Table 5.6. In order to compare the effect of the dual trunk configuration with the previous results, the configuration of trunk 2 in Figure 5.4 was defined as the single trunk configuration previously considered. The topology of this configuration was held constant and the offered load varied, the resulting data points are contained in Tables 5.7, 5.8, and 5.9. These data points were plotted as shown in Figures 5.5, 5.6, and 5.7.

In a scenario that has been judged to be a normal environment for the HOSC dual trunk system, the transmissions from trunk 1 to trunk 2 have aggregate data rate of 10 kbytes/sec. The device on trunk 1 always transmits across the trunks to trunk 2. The cross traffic from trunk 2 to trunk 1 has a lower data rate and a lower probability of request for transmission. Thus the majority of

Table 5.6 Relative Probabilities for Transmitter/  
Receiver Pairs for Figure 5.4.

Transmitter/Receiver	Probability
111-521	1.0
211-411	0.7
211-421	0.3
311-531	1.0
321-521	1.0
321-111	0.3
411-311	0.01
411-321	0.01
421-311	0.01
421-321	0.01
431-521	1.0

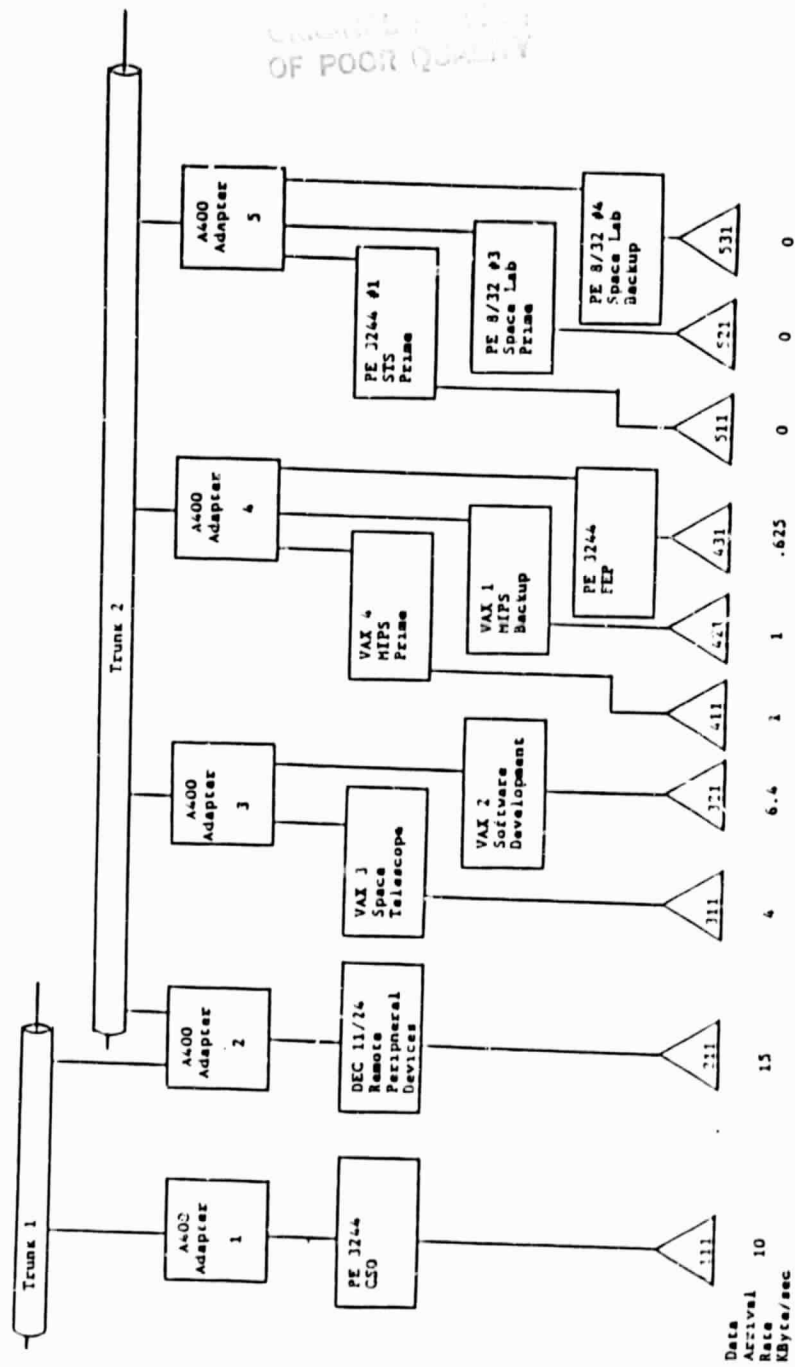


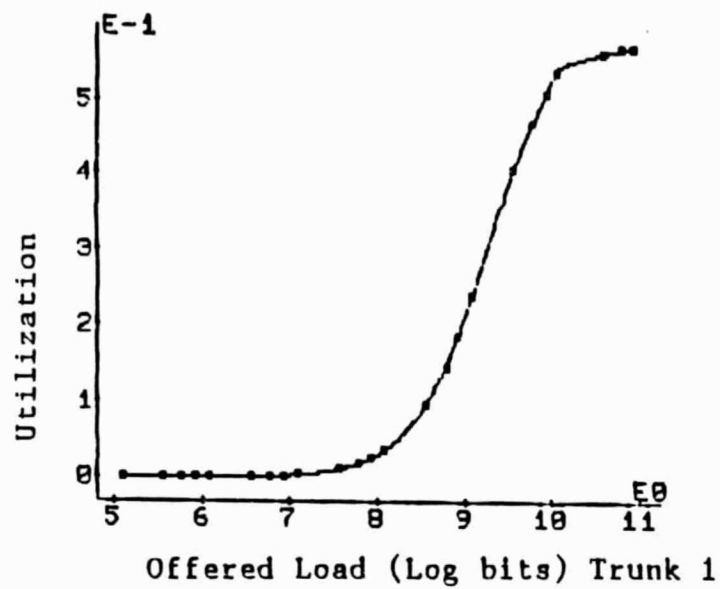
Figure 5.4 Dual Trunk Simulation Set-Up.

Table 5.7 Data Points for Figure 5.5 (Trunk 1)

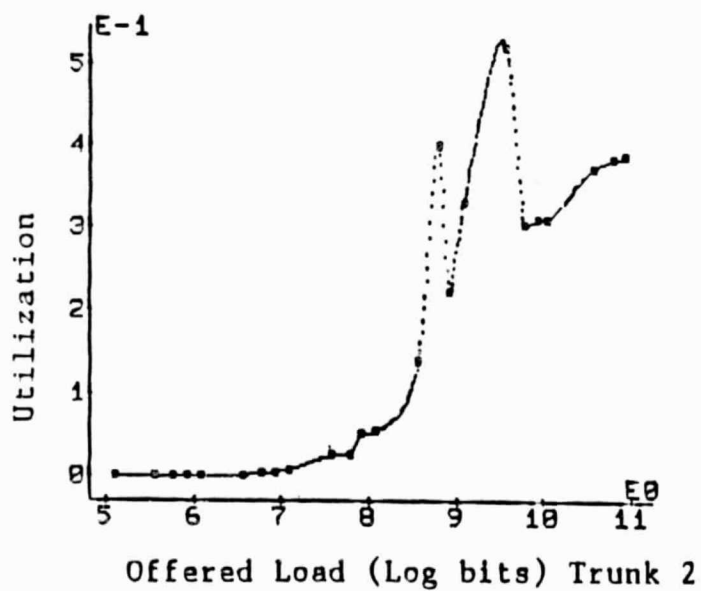
S Mbytes/sec	U	G Mbytes	Average D secs
.00017973	.000028758	.0155758	.0006650
.00065895	.000105433	.0467330	.0018928
.00116560	.000186500	.0760532	.0018800
.00161704	.000258726	.1090710	.0015842
.00239248	.000382797	.1521190	.0014942
.00711533	.001138454	.4564050	.0013442
.01189340	.001902940	.7610820	.0013142
.01665555	.002664880	1.0658600	.0013000
.02376770	.003802830	1.5233900	.0013000
.07053307	.011285292	4.5644800	.0013228
.11621025	.018593600	7.6050000	.0064371
.16076790	.025722800	10.6496000	.0014928
.22569486	.036111111	15.2116000	.0067786
.60678250	.097085200	45.6300000	.0288557
.91607500	.146572000	76.0500000	.0977300
1.17207750	.187532400	106.4700000	>40
1.50327750	.240524400	152.1000000	.7125557
2.52247200	.403590000	456.3000000	>40
2.93269750	.469231600	760.5000000	>40
3.15442500	.504700000	1064.7000000	>40
3.34350000	.534960000	1377.0000000	>40
3.49356500	.558970000	4563.0000000	>40
3.52475250	.563960400	7605.0000000	>40
3.54453500	.567125600	10647.0000000	>40

Table 5.8 Data Points for Figure 5.5 (Trunk 2).

S Mbytes/sec	U	G Mbyte	Average D sec
.00017973	.000028758	.0155758	.0006650
.00142330	.000227728	.0467330	.0018928
.00204550	.000327280	.0760532	.0018800
.00321635	.000514616	.1090710	.0015842
.00478900	.000766240	.1521190	.0014942
.01557770	.002492400	.4564050	.0013442
.02641426	.001902940	.7610820	.0013142
.03715009	.005944016	1.0658600	.0013000
.05333650	.008533800	1.5233900	.0013000
.16056906	.025691050	4.5644800	.0013228
.16651150	.026641800	7.6050000	.0064371
.32703950	.052326322	10.6496000	.0014928
.34178971	.054686000	15.2116000	.0067786
.86553250	.138485200	45.6300000	.0288557
2.49451500	.399122400	73.0500000	.0977300
1.38427372	.221483800	106.4700000	>40
2.05963550	.329541600	152.1000000	.7125557
3.24608750	.519374000	456.3000000	>40
1.88915240	.302260000	760.5000000	>40
1.92437440	.307899000	1064.7000000	>40
1.93925400	.310280000	1377.0000000	>40
2.31418420	.370269000	4563.0000000	>40
2.38785975	.382057500	7605.0000000	>40
2.40758250	.385200000	10647.0000000	>40



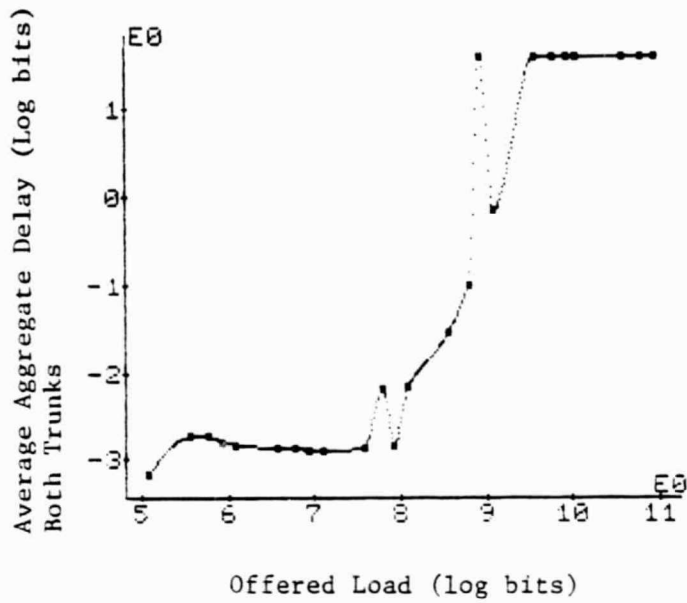
(a)



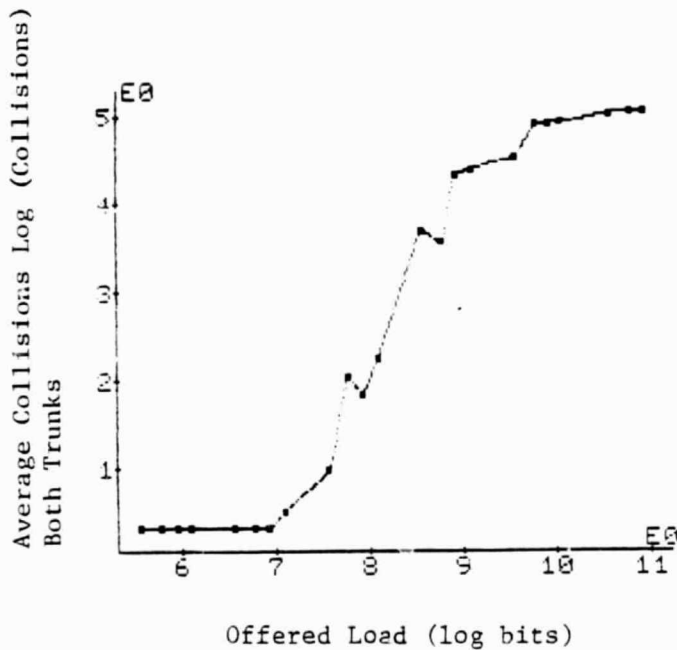
(b)

Figure 5.5 Plot of Utilization versus Offered Load for Dual Trunk Simulation.

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(c)



(d)

Figure 5.5 Plot of Utilization versus Offered Load for Dual Trunk Simulation.

Table 5.9 Data Points for Figures 5.6 and 5.7.

Trunk 1		Trunk 2		G
Control Mbits	Data Mbits	Control Mbits	Data Mbits	
.327870	.026112	.327870	.026112	.12460
.120219	.095744	.229786	.236680	.37386
.207651	.165376	.339076	.315528	.60842
.295083	.235008	.528275	.526096	.87256
.426231	.339456	.761190	.771480	1.21695
1.267768	1.009664	2.416856	2.569176	3.65124
2.120224	1.688576	4.083456	4.375576	6.08865
2.972688	2.367488	5.728200	6.172760	8.52688
4.240456	3.377152	8.220800	8.873680	12.18712
12.568320	10.009600	24.684128	26.717520	36.51584
20.699520	16.485360	44.027040	9.256640	60.84000
28.644880	22.813200	59.468240	45.209520	85.19680
40.207760	32.022000	93.209600	16.174320	121.69280
108.088000	86.082400	193.222400	83.748000	365.04000
163.210400	129.933600	411.237600	38.700720	608.40000
208.792000	166.272800	440.861600	2.105992	851.76000
274.172000	206.876800	631.889600	27.193760	1216.80000
449.335200	357.856000	896.320000	142.428000	3650.40000
522.411200	416.052000	607.649600	.032768	6084.00000
561.916800	447.499200	615.689600	.110208	8517.60000
595.596800	474.324800	620.444800	.116488	11016.00000
640.745600	457.195200	717.393600	23.145360	36504.00000
613.976000	453.948000	733.200800	30.914320	60840.00000
679.876000	454.375200	732.420800	38.005600	85176.00000



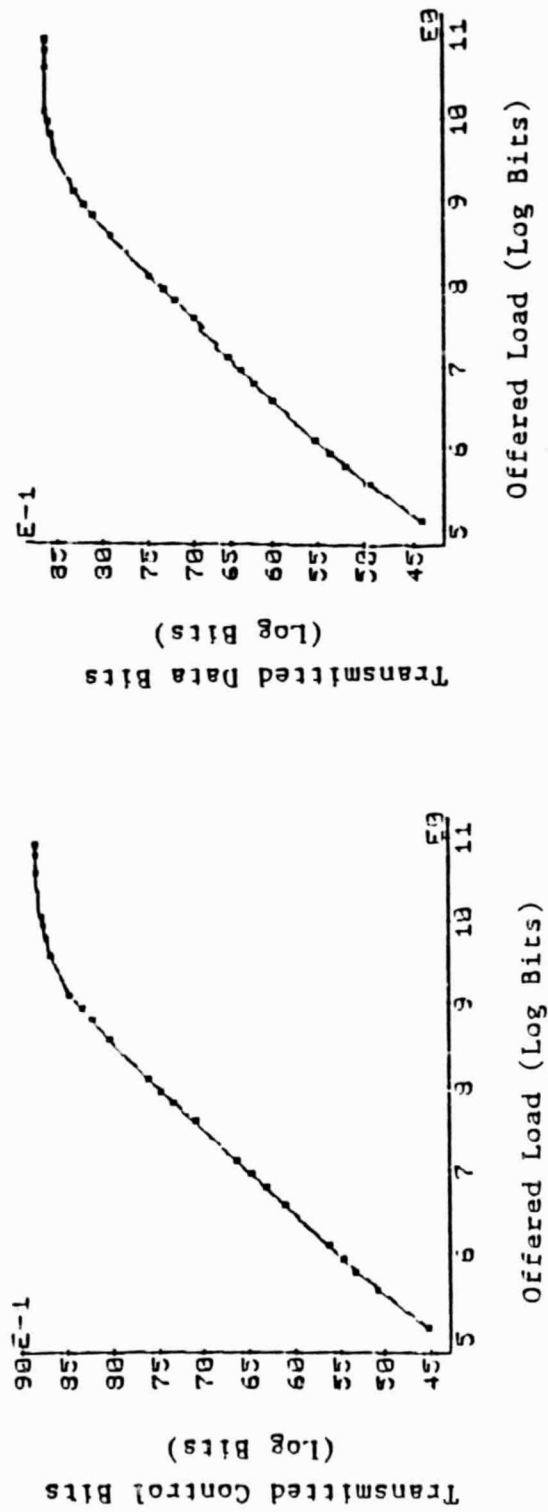


Figure 5.6 Plot of Transmitted Control and Data Bits  
versus Offered Load for Dual Trunk (Trunk 1)  
Simulation.

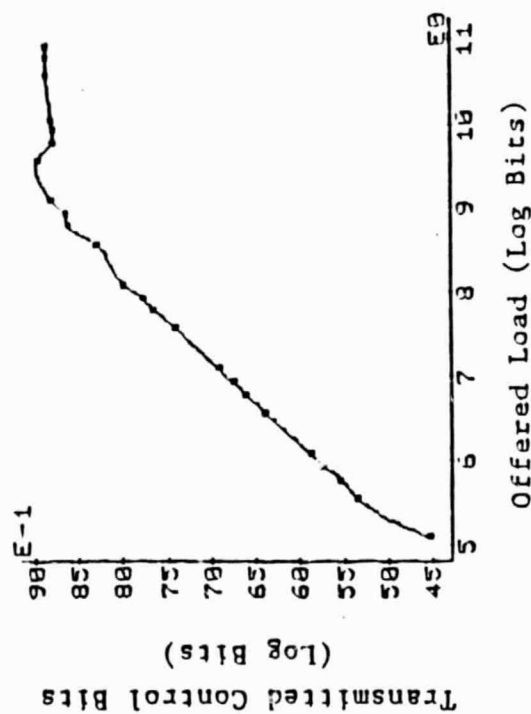
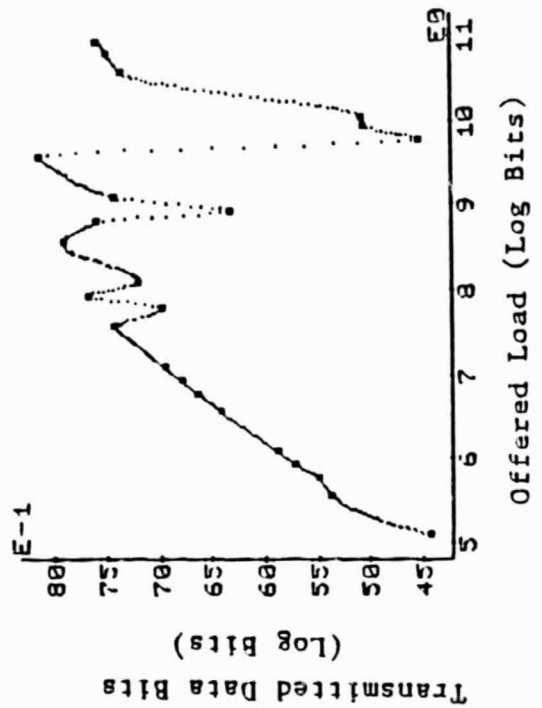


Figure 5.7 Plot of Transmitted Control and Data Bits versus Offered Load for Dual Trunk (Trunk 2) Simulation.

the cross trunk transmissions occur from trunk 1 to trunk 2. This is envisioned as the worst case condition for cross trunk traffic since the destination trunk is the busiest trunk.

Looking at the curves from figures 5.5, 5.6 and 5.7 it may be observed that for trunk 1 the operational parameters under increasing offered load are very similar to that for the single trunk secenario, the exception being the lowered trunk utilization before saturation is encountered. Again the maximum offered load operationg point is seen to occur for about 8.5 offered load and hence as before the trunk 1 aggregate offered load should be held to 8 Mbps or less.

The situation is not as good for trunk 2. The cross trunk traffic hampers the normal traffic flow for trunk 2 and it is apparent from the simulation curves that the maximum aggregate offered data load should be held to less than 8 or 2.5 Mbps. This is considerably less than that for the single trunk simulation and clearly demonstrates the effect of heavy cross trunk communication requirements.

From figure 3.4 the aggregate offered data load of the two trunks may be calculated. This

was judged to represent a typical operating load for the dual trunk HOSC system.

DEVICE	DATA ARRIVAL RATE
111	10 kbytes/sec = 80 kbps
<hr/>	
TRUNK 1 TOTAL OFFERED LOAD =	80 kbps
211	15 kbytes/sec = 120 kbps
311	4 kbytes/sec = 32 kbps
321	6.4 kbytes/sec = 51.2 kbps
411	1 kbytes/sec = 8 kbps
421	1 kbytes/sec = 8 kbps
431	1 kbytes/sec = 8 kbps
511	0
521	0
531	0
<hr/>	
TRUNK 2 TOTAL OFFERED LOAD =	224.2 kbps.

The aggregate offered data load for trunk 1 is 80 kbps (6.505 log bits) and for trunk 2 is 224.2 kbps (6.952 log bits). These offered aggregate data rates are less than the desired maximum by a considerable amount and room for growth exists. There is an allowable factor of 100 for trunk 1 and an allowable factor of 10 for trunk 2 growth rates. Keeping in mind that this aggregate data load for

trunk 2 is the same as for the single trunk simulation configuration of figure 5.1 it is easily discerned that the cross trunk traffic while amounting to a 35% increase in trunk 2 traffic lowers the maximum operating offered load potential of trunk 2 by a factor of almost 4 (down from 8 Mbps to 2.5 Mbps). Furthermore the curve of figure 5.5 illustrates that the utilization of trunk 1 saturates at 55% as opposed to the 75% point for the single trunk case.

FOR DUAL CONFIGURATIONS IT SHOULD BE NOTED THAT THE MAXIMUM AGGREGATE OPERATING LOAD POTENTIAL OF THE TRUNKS IS LOWERED BY A CONSIDERABLE AMOUNT. THIS ARISES FROM THE NECESSITY OF DUAL RESERVATION OF BOTH TRUNK ADAPTERS. THE CROSS TRUNK TRAFFIC LOWERS THE MAXIMUM OPERATING UTILIZATION POTENTIAL TO APPROXIMATELY 75% OF THAT FOR THE SINGLE TRUNK.

FURTHERMORE CARE SHOULD BE TAKEN IN ASSIGNING DEVICES TO THE TRUNK ON WHICH THEY ARE MOST ACTIVE.

### 5.3 Analysis and Conclusions

The goal of this work was to develop a software tool, with particular emphasis on NSC's HYPERchannel network, to aid the engineers and scientists at the HOSC, to perform system analysis. This study began with a description of the HYPERchannel and the various protocols implemented by the network. The relationship of these protocols to system performance was discussed. The system components which make up the HOSC were examined, these components are examined for information purposes, in that the attributes of these devices were used to define the test configurations presented in section 5.2. The configurations chosen for testing by the simulation, are based on the system shown in Figure 3.1. The results of this testing are presented in section 5.2 of this work.

The data, which appear in Section 5.2, are plotted in all cases versus the Log (base 10) of offered load, where offered load is expressed in bits. So that an offered load of 7 on any plot is the inverse Log (base 10) of 7 which is equal to  $1 \times 10^7$  bits. In Figures (5.2 and 5.5) utilization is plotted versus offered load. Utilization is a dimensionless figure ranging from 0 to 1. In Figures (5.3, 5.6, and 5.7) the Log (base 10) of transmitted control and data bits are plotted versus offered load. As before a value of 7 on

the offered load axis represents  $1 \times 10^7$  bits. Whether this is data or control bits, is indicated on the axis of its respective plot. Finally, the simulation time used, 40 seconds, was the same for all simulation runs.

The results obtained from the single trunk configuration of the model are found in Figures 5.2 and 5.3. The results as plotted in Figure 5.2 and tabulated in Table 5.3, compare favorably with results obtained by other researchers [FRAN82], [FRAN84], and [WATS80]. While numerical results differ due to different topologies being modeled, overall performance of the network is essentially the same. The overall performance of this network, and that reported elsewhere, appears to approach some relatively constant level (saturation) as offered load increases. A slightly different presentation of these results are plotted in Figure 5.3 and tabulated in Table 5.5. This data is presented as transmitted control and data bits versus offered load. These plots represent the actual amount of data and control bits being transmitted by the network versus offered load. Control bits are those bits transmitted by an adapter to perform network functions and are considered overhead loading. Data bits transmitted, are those bits offered to the network by attached devices for transfer over the network. Offered load represents the total amount of data

presented to the network for transmission over the network. Thus, as offered load increases, the amount of data bits transmitted should increase. Since network services are requested, network functions increase, thereby increasing the amount of network messages relating to these functions. This will cause a corresponding increase in the amount of control bits being transmitted over the network. The plots in Figure 5.3, both exhibit nearly linear properties until a certain point (offered load approximately equal to 9) is reached, after which the data and control bits transmitted remain nearly constant.

An offered load of 9 on these plots, represents an aggregate offered load of 3.125 Mbytes/sec being presented to the network for transmission. This is equivalent to an off network source requesting network services every 0.04 usec. According to published figures [FRAN82], [FRAN84], and [WATS82], an adapter requesting the trunk, transmitting its data, and then releasing itself and its receiving adapter will require a minimum of 940 usec to send one message-with-data sequence containing one 2 Kbyte data block. If the off network sources' data rates are such that network services are requested faster than the network can process these requests, then data loss will occur. At this point the network is entering saturation. This is



reflected in the plots of data bits transmitted versus offered load. After offered load exceeds the point where offered load is approximately 9, any further increase in the offered load does not produce a corresponding increase in the amount of data and control bits transmitted. This indicates that the network is saturated and can not transmit any greater amount of data or control bits.

The normal offered load to the network, based on observations of the system described in Chapter 3, and detailed in Appendix IV, appears to be approximately 6.95 (Offered Load). This figure results from summation of the data rates applied to the network, multiplied by simulation time, and then performing a Log (base 10) operation on the result. Thus this network is, according to simulation results, operating below its potential by a factor of approximately 100. This indicates that expansion of this configuration would be possible to some extent.

In order to examine the effects of a second trunk added to a network, the configuration shown in Figure 5.4, and detailed in Appendix V, was modeled. This configuration is similar to the single trunk configuration in that the topology of trunk 2 (Figure 5.4) is the same as that shown in Figure 5.1. In order to observe the effects on trunk 2 due to another trunk

having access to it, the probability of a transmission to trunk 2 from trunk 1 was set higher than the probability of the reverse operation. It should be apparent, that a dual trunk network in which each trunk has need of only sporadic use of the other, would have noticeably better performance than the configuration presented in this work. The results of modeling this configuration are plotted in Figures 5.5 through 5.7, and are tabulated in Tables 5.7 through 5.9. Examination of these results shows that trunk 1 is relatively unaffected, although utilization is lower. Utilization in this case is approximately constant at a value of 0.55 for increasing offered load. This figure is approximately 25% less than the comparable value for a single trunk network, this is due largely to the topology of the network. On trunk 1 there are two adapters, which communicate exclusively with each other. There is a larger number of adapters on trunk 2; which affects the common adapter to both trunks, in that, multi-trunk operation is slower. This slowness of the multi-trunk operation may be attributed to the common adapter having to compete for a busier trunk to complete its' transmission. Thus, the common adapter will be reserved for longer periods of time, directly affecting throughput, and consequently utilization, on both trunks. Performance on trunk 1 of this topology,

with the exception of lower utilization, is roughly the same as that of a single trunk network, as expected. However, the results for trunk 2 are drastically reduced from that of a single trunk configuration. An examination of Figures 5.2 and 5.5, show that utilization of the trunk is very nearly the same for an offered load of approximately 5 to a load of very nearly 8. After an offered load of 8 is reached, the dual trunk configuration's utilization is drastically reduced. In Figure 5.6, the control and data bits transmitted over trunk 1 are plotted. These curves exhibit behavior similar to that of the single trunk model discussed previously. This is not the case for the control and data bits transmitted over trunk 2 (Figure 5.7). Both of these plots exhibit linear behavior to a certain extent, but while the control bits transmitted are only slightly affected, the transmitted data is drastically altered at the same point that utilization breaks down. Based on the description of this network contained in Appendix V, the normal offered load is approximately 7.08. As shown in the plotted data, this topology has very limited range in regard to offered load, which makes it vulnerable to performance degradation due to load variation.

Thus, a single trunk system exhibits greater potential for expansion than the dual trunk topology modeled. Rather than allow a dual trunk system of this nature, it would be better (Performance related) to place the additional device seeking communication with another trunk, at a high rate, physically on the trunk it requests the most.

The validity of this simulation is based on the understanding of the system and the structure of the model. While it would be better to establish validity by comparison with actual configurations and their measured performance, the feasibility of establishing a test bed for this purpose is remote, due largely to the intensive mission requirements at the HOSC.

Finally, the author believes that the stated research goals have been reached. However, in this model, as in all things there is considerable room for improvement. Future expansion of the model might be made, to include intra-adapter message transfers, and more than one adapter to more than one trunk. This would serve to lend more accuracy and sophistication to the present model. The current model appears to possess reasonable accuracy and validity, with the stated conditions under which it was developed.

## APPENDIX I

### Software Source Listing

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TITLE:  
A SOFTWARE MODEL OF NETWORK SYSTEMS CORPORATION'S HYPERCHANNEL  
NETWORK. A MODEL OF THE HUNTSVILLE OPERATIONS SUPPORT  
CENTER.

AUTHOR:  
DENNIS L. MASSEY

MISSISSIPPI STATE UNIVERSITY  
MAY, 1985

ABSTRACT:

NETWORK SYSTEMS CORPORATION'S HYPERCHANNEL NETWORK IS A  
BASEBAND, 50 MEGABIT PER SECOND, HIGH SPEED LOCAL AREA NETWORK.  
HYPERCHANNEL UTILIZES A CARRIER SENSE MULTIPLE ACCESS (CSMA)  
DATA TRUNK ACCESS PROTOCOL, WITH PRIORITIZED STAGGERED DELAYS.  
THIS NETWORK HAS THE CAPABILITY OF INTERCONNECTING VARIOUS  
COMPUTER RESOURCES OF DIFFERING MANUFACTURE, INTO A SINGLE  
EFFICIENT COMPUTING FACILITY.

THIS NETWORK IS CURRENTLY IN USE AT THE HUNTSVILLE OPERATIONS  
SUPPORT CENTER (HOSC). HOSC AS A DISTRIBUTED COMPUTING SYSTEM,  
IS RESPONSIBLE FOR DATA ACQUISITION AND ANALYSIS DURING NATIONAL  
AERONAUTICS AND SPACE ADMINISTRATION'S (NASA) SPACE SHUTTLE  
OPERATIONS. HOSC ALSO PROVIDES COMPUTING SERVICES FOR MARSHALL  
SPACE FLIGHT CENTER'S (MFC) NON-MISSION ACTIVITIES, AS MISSION  
AND NON-MISSION ACTIVITIES CHANGE, SO DO THE SUPPORT FUNCTIONS OF  
HOSC CHANGE, DEMONSTRATING THE NEED FOR SOME METHOD OF SIMULATING  
ACTIVITY AT HOSC IN VARIOUS CONFIGURATIONS.

THE SIMULATION DEVELOPED IN THIS WORK PRIMARILY MODELS MSC'S  
HYPERCHANNEL NETWORK, SINCE THIS NETWORK BASICALLY DETERMINES  
HOSC'S EFFICIENCY IN ACCOMPLISHING ITS MISSION. THE MODEL SIMULATES  
THE ACTIVITY OF A STEADY-STATE NETWORK, REPORTING STATISTICS SUCH  
AS, TRANSMITTED BITS, COLLISION STATISTICS, FRAME SEQUENCES TRANS-  
MITTED, AND AVERAGE MESSAGE DELAY. THESE STATISTICS MAY BE USED TO  
EVALUATE SUCH PERFORMANCE INDICATORS AS THROUGHPUT, UTILIZATION,  
AND DELAY. THUS, THE OVERALL PERFORMANCE OF THE NETWORK MAY BE  
EVALUATED, AS WELL AS PREDICTING POSSIBLE OVERLOAD CONDITIONS.

PROGRAM SIM1 (INPUT, OUTPUT, DFILE (LFN=17), AUXOUT (LFN=16), OUT (LFN=18));

[ ..... ]  
[ DATA DECLARATIONS ]  
[ ..... ]

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54 CONST
55   MAXNUMSOURCES = 32;
56   MAXNUMADAPTERS = 9;
57   PROPAGATION = 1.32E-09; (* PROP. DELAY NS/FT *)
58   TRUNKRATE = 50.CE*06; (* TRUNK TX RATE IN BITS/ SECS. *)
59   ONE = 1;
60   ZERO = 0;
61   MAXNUMTRUNKS = 2; (* MAXNUMBER TRUNKS IN NETWORK *)
62
63 TYPE
64   POINTER = ^LIST;
65   LIST = RECORD
66     ID : INTEGER;
67     PROS : REAL;
68     NEXT : POINTER
69   END; (* LINKED RECORD *)
70
71
72
73
74
75
76
77 SOURCEDESCRPTIONS = RECORD
78   ID: PACKED ARRAY [1..24] OF CHAR;
79   DNUM : INTEGER; (* DEVICE NUMBER *)
80   DEST : INTEGER; (* ID OF DESTINATION WHEN TX *)
81   IDEST : INTEGER; (* INTERMEDIATE DESTINATION WHEN TRUNK-TRUNK TX *)
82   FRONTX : INTEGER; (* TRANSMITTER WHEN RECEIVING *)
83   BUFFERSIZE: REAL; (* NUMBER OF BITS ACCUMULATED FROM A OFF-NET SOURCE BEFORE THE DEVICE REQUESTS A TRUNK TRANSMISSION *)
84   DISTFROMA1: REAL; [ DISTANCE FROM ADAPTER 1 ]
85   DISTFRTA1 : REAL; (* USED IN DUAL TRUNK, FOR 2ND TRUNK *)
86   TFERRATE: REAL; (* DEVICE TO ADAPTER I/O RATE *)
87   NEXTTX: REAL; (* TIME UNTIL NEXT TRANSMISSION *)
88
89   TXINTRVL: REAL; [ TIME BETWEEN TX REQUESTS BASED ON AGGREGATE SOURCE TRANS. RATES FROM OFFNET SOURCES ]
90
91   SEQCT : INTEGER;
92   WAITCT: INTEGER; [ DEVICE WAITS TALLY ]
93   COLCT: INTEGER; [ DEVICE COLLISION TALLY ]
94   RSECT : INTEGER; (* DEVICE RECEPTION TALLY *)
95   ABORTCT : INTEGER; [ DEVICE ABORT TALLY ]
96   BUSYTIME : REAL;
97   WAITTIME: REAL; [ TIME DEVICE SPENT IN WAIT DELAYS ]
98   COLLTIME: REAL; [ TIME DEVICE SPENT IN COLL. WAITS ]
99   GENRATE: REAL; [ AVG NUMBER OF BYTES/SEC ]
100   M1 : BOOLEAN;
101   M2 : BOOLEAN;
102
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104
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109 M3 : BOOLEAN; (* MESSAGE FLAGS *)
110 M4 : BOOLEAN;
111 M5 : BOOLEAN;
112 M6 : BOOLEAN;
113 M8 : BOOLEAN; (* USED FOR 2 TRUNK OPS *)
114 BLKSENT : REAL;
115 TBLK : REAL;
116 DATABLKCT : REAL;
117 INITIALTX : REAL; (* INITIAL TX TIME *)
118 FINALTX : REAL; (* FINAL TX TIME *)
119 MESSEDELAY : REAL; (* SUM OF FINALTX - INITIALTX *)
120 FIRST : POINTER;
121 END;
122
123 DEVICERECORDS = RECORD
124 ID: PACKED ARRAY [1..24] OF CHAR;
125 OPEN: BOOLEAN; [ TRUE IF DEVICE ATTACHED TO PORT ]
126 NUMFSOURCES: INTEGER;
127 SOURCE: ARRAY [1..MAXNUMSOURCES] OF SOURCEDESCRIPTIONS;
128 TFERRATE: REAL; [ I/O PORT TRANSFER RATE FROM DEV TO ADAPT
129 IN BYTES/SEC ]
130 LOADTIME: REAL; [ INVERSE OF TFER_RATE = TIME FOR DEV TO
131 LOAD ADAPT BUFFER ]
132 SFLAG: ARRAY [1..3] OF BOOLEAN;
133
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161
162
163
END;

ADAPTERRECORDS = RECORD
DEVICE: ARRAY [1..4] OF DEVICERECORDS;
DISTFROMA1: REAL; [ DISTANCE IN FEET FROM ADAPTER 1 ]
DISTFRTA1 : REAL;
PRIDELAY : REAL; [ NUMBER OF SECONDS OF ASSIGNED WAIT
TIME IN EVENT OF WAIT DURING
TRANSMISSION ]
ENDIDELAY : REAL;
FIXIDELAY : REAL; (*END TO END TX TIME ON TRUNK 1 *)
TOTIDELAY : REAL; (* TOTAL DELAY PERIOD FOR TRUNK 1 *)
DELAY : REAL; (* DELAY USED IN RESERVATION SCHEME *)
RETRYCT : INTEGER; (* BASED ON ADAPTER UNIT NUMBER
RANGES FROM 0-65, UNIQUE FOR EACH
ADAPTER (RESERVATION SCHEME) *)
RETRY : INTEGER;
PRI2DELAY : REAL; (* PRIORITY DELAY FOR TRUNK 2 *)
END2DELAY : REAL; (* END DELAY FOR TRUNK2 *)
FIX2DELAY : REAL; (* FIXED DELAY FOR TRUNK2 *)
TOT2DELAY : REAL; (* TOTAL DELAY FOR TRUNK2 *)
FINALDEST : INTEGER; (* USED BY COMMON ADAPTER *)

```



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164 P1 : INTEGER; (* INTEGER VALUE OF PRIORITY DELAY ON
165 TRUNK 1 *)
166 P2 : INTEGER; (* INTEGER VALUE OF PRIORITY DELAY ON
167 TRUNK 2 *)
168 DFLAG : ARRAY [1..4] OF BOOLEAN;
169
170
171
172 END;
173
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219 C PERFORMS BEGINNING OF RUN VARIABLE INITIALIZATIONS AND ]
220 C SETS UP SIMULATION RUN PARAMETERS. ]
221 C ]
222 C ]
223 C INVOKED BY: PROGRAM MOD3C ]
224 C CALLS TO : NO OTHER ROUTINES ]
225 C ]
226 C GLOBAL VARIABLES AFFECTED:U,WAIT_TALLY,COLLISION_TALLY,]
227 C TOTAL_ATTEMPTS,LCT,PCT,TIME_ACTIVE,BITS_TX, ]
228 C MAX_TIME,PRINT_ALL,INPUT_MODE. ]
229 C ]
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274      END;
275      END;
276
277      FOR COND1 := CASE1 TO CASE7 DO CONDITION(COND1) := COND1;
278      PRINTALL := TRUE;
279      DNUM := 0;
280      U := 16227; [ U IS SEED FOR RNG ]
281      WAITALLY := 0.0;
282      COLLTALLY := 0;
283      TOTALABORTS := 0;
284      LCT := 0;
285      PCT := 0;
286      TIMEACTIVE := 0.0;
287      BITSTX := 0.0;
288      TRUNKS := FALSE;
289      MAXTIME := 00.0;
290      MAXSENTX := 00000000;
291      PRIDELAY := 0.0;
292      TOTALDELAY := 0.0;
293      FIXEDDELAY := 0.0;
294      ENDDelay := 0.0;
295      TRIACTIVE := 0.0;
296      TRZACTIVE := 0.0;
297      TRK1 := FALSE;
298      RESERVED := FALSE;
299      SEQ1ALLY := 0;
300      SEQ2ALLY := 0;
301      SEQ3ALLY := 0;
302      TOTALATTEMPTS := 0;
303      TRK2ALLY := 0;
304      TRK2ALLY := 0;
305      CONT1BITS := 0.0;
306      DATA1BITS := 0.0;
307      CONT2BITS := 0.0;
308      DATA2BITS := 0.0;
309      T1 := 0.0;
310      T2 := 0.0;
311      T3 := 0.0;
312      T4 := 0.0;
313      OFFLOAD := 0.0;
314
315      REWRITE(OUT);
316
317      WRITELN;
318
319      WRITELN(' IS THERE MORE THAN ONE TRUNK ? Y/N OR N/Y');
320      REPEAT READ(RESPEC1) UNTIL RESPEC1 <> ' '; READLN;
321      IF (RESPEC1 = 'Y') OR (RESPEC1 = 'N') THEN
322          TRUNKS := TRUE
323      ELSE
324          TRUNKS := FALSE;
325
326
327
328

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329 WRITELN( 'IDENTIFICATION HEADING FOR RUN:');
330 WRITELN( ' ');
331 READLN( ' ');
332 WRITELN( ' ');
333 WRITELN( ' ');
334 WRITELN( ' ');
335 WRITELN( ' ');
336 WRITELN( ' ');
337 READLN( ' ');
338 WRITELN( ' ');
339 WRITELN( ' ');
340 WRITELN( ' ');
341 READLN( ' ');
342 WRITELN( ' ');
343 WRITELN( ' ');
344 WRITELN( ' ');
345 WRITELN( ' ');
346 READLN( ' ');
347 IU := U;
348 WRITELN( ' ');
349 WRITELN( ' ');
350 WRITELN( ' ');
351 WRITELN( ' ');
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379 WRITELN( ' ');
380 WRITELN( ' ');
381 WRITELN( ' ');
382 WRITELN( ' ');
383 WRITELN( ' ');

```



```

439 WITH ADAPTER[I] DO
440 BEGIN
441   WRITELN(DFILE, DISTFROMA1);
442   WRITELN(DFILE, PRIYDELAY);
443   WRITELN(DFILE, ENYDELAY);
444   WRITELN(DFILE, RETRYCT);
445   IF ( TRUNKS ) AND ( I = COMRAD ) THEN
446     BEGIN
447       WRITELN(DFILE, DISTFRTA1);
448       WRITELN(DFILE, PRI2DELAY);
449       WRITELN(DFILE, END2DELAY);
450     END;
451   C BEGIN INDIVIDUAL DEVICE DESCRIPTIONS ]
452   FOR J := 1 TO 4 DO
453     BEGIN
454       WITH ADAPTER[I].DEVICE[J] DO
455         BEGIN
456           WRITELN(DFILE, OPEN);
457           IF NOT (OPEN) THEN
458             BEGIN
459               WRITELN(DFILE, ID);
460               WRITELN(DFILE, TFERRATE);
461               WRITELN(DFILE, NUMOFSSOURCES);
462               FOR K := 1 TO NUMOFSSOURCES DO
463                 WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
464                   BEGIN
465                     WRITELN(DFILE, DNUM);
466                     WRITELN(DFILE, ID);
467                     WRITELN(DFILE, GENRATE);
468                     WRITELN(DFILE, BUFFERSIZE);
469                     WRITELN(DFILE, DATABLKCT);
470                     WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
471                       BEGIN
472                         C := FIRST;
473                         WHILE C <> NIL DO
474                           BEGIN
475                             WRITELN(DFILE, C^.ID);
476                             WRITELN(DFILE, C^.PROB);
477                             C := C^.NEXT;
478                           END;
479                         WRITELN(DFILE, 0);
480                       END;
481                     END;
482                   END; [ FOR K:=1 TO NUM OF SOURCES ]
483                 END; [ IF NOT(OPEN) ]
484               END; [ WITH ADAPTER(I).DEVICE(I) ]
485             END; [ FOR J=1 TO 4 ]
486           END; [ WITH ADAPTER(I) ]
487         END; [ FOR I=1 TO NUM OF ADAPTERS ]
488       END;
489     END;
490   END;
491 END;
492 END;
493

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ORIGINAL FILE  
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494 IF TRUNKS THEN
495 BEGIN
496   FOR I := ( COMAD + 1 ) TO NUMOFADAPTERS DO
497     BEGIN
498       WITH ADAPTER[I] DO
499         BEGIN
500           WRITELN(OFIL, DISTRTA1 );
501           WRITELN(OFIL, PRI2DELAY );
502           WRITELN(OFIL, END2DELAY );
503           WRITELN(OFIL, RETRYCT );
504           FOR J := 1 TO 4 DO
505             BEGIN
506               WITH ADAPTER[I].DEVICE[J] DO
507                 BEGIN
508                   WRITELN(OFIL, OPEN);
509                   IF NOT(OPEN) THEN
510                     BEGIN
511                       WRITELN(OFIL, ID );
512                       WRITELN(OFIL, TFERRATE );
513                       WRITELN(OFIL, NUMOF SOURCES );
514                     FOR K := 1 TO NUMOF SOURCES DO
515                       WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
516                         BEGIN
517                           WRITELN(OFIL, DNUM );
518                           WRITELN(OFIL, ID );
519                           WRITELN(OFIL, GENRATE );
520                           WRITELN(OFIL, BUFFERSIZE );
521                           WRITELN(OFIL, DATABLKCT );
522                           WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
523                             BEGIN
524                               C := FIRST;
525                               WHILE C <> NIL DO
526                                 BEGIN
527                                   WRITELN(OFIL, C^.ID);
528                                   WRITELN(OFIL, C^.PROB);
529                                   C := C^.NEXT;
530                                 END;
531                               WRITELN (OFIL, 0 );
532                             END;
533                           END;
534                         END;
535                       END;
536                     END;
537                   END;
538                 END;
539             END;
540           END;
541         END; [ PROCEDURE REWRITE ]
542       END;
543     END;
544   END;
545 END;
546
547
548

```

```

549 BEGIN [ PROCEDURE CHARACTERIZE NETWORK ]
550
551 C      BEGIN DESCRIPTION OF NETWORK BY DESCRIBING ADAPTERS  ]
552
553 CASE INPUTMODE OF
554
555 INTERACTIVE:
556 BEGIN
557
558 WRITELN('.....');
559 WRITELN('.....');
560 WRITELN('.....');
561 WRITELN('.....');
562 WRITELN('.....');
563 WRITELN('.....');
564 WRITELN('.....');
565 WRITELN('.....');
566 WRITELN('.....');
567 WRITELN('.....');
568 WRITELN('.....');
569 WRITELN('.....');
570 WRITELN('.....');
571 WRITELN('.....');
572
573 IF NOT( TRUNKS ) THEN
574   NUMOFTRUNKS := 1
575 ELSE
576   NUMOFTRUNKS := 2;
577
578 WRITELN('LENGTH OF TRUNKS IN FEET (USED FOR END DELAY)');
579 FOR I := 1 TO NUMOFTRUNKS DO
580   BEGIN
581     WRITELN('TRUNK ', I, ' ');
582     READLN( TRUNKLENGTH[I]);
583     END;
584
585 WRITELN('NUMBER OF ADAPTERS IN NETWORK');
586 WRITELN( NUMOFADAPTERS);
587
588 IF TRUNKS THEN
589   BEGIN
590     WRITELN('WHICH ADAPTER IS COMMON TO BOTH TRUNKS ?');
591     READLN ( COMAD );
592     END;
593
594 IF NOT( TRUNKS ) THEN
595   COMAD := NUMOFADAPTERS;
596
597
598
599
600
601 FOR I := 1 TO COMAD DO
602   WITH ADAPTER[I] DO
603

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```

604 BEGIN
605   WRITELN;
606   WRITELN('ADAPTER #', I, 2, ':');
607   WRITELN;
608   WRITELN(' ', I, 2,
609     'DISTANCE IN FT FROM PRIORITY 1 ADAPTER ON TRUNK 1 : ');
610   READLN (DISTFROM1);
611
612   WRITELN;
613   WRITELN(' ', I, 2,
614     'ADAPTER PRIORITY: GIVE IN INTEGER FORM, IE. N= 1,2,...');
615   WRITELN(' ', I, 2, 'THIS IS USED TO CALCULATE PRIORITY DELAY ');
616   READLN( P1);
617   FIXDELAY := TRUNKLENGTHM[I] * 4.0E-09 + 2.08E-06;
618   WRITELN;
619   WRITELN;
620   WRITELN(' ', I, 2,
621     'ADAPTER RETRY COUNT : THIS MUST BE A UNIQUE NUMBER');
622   WRITELN(' ', I, 2, 'FOR EACH ADAPTER IN THE RANGE 0 TO 64');
623   READLN ( RETRYCT );
624   WRITELN;
625
626   IF ( TRUNKS ) AND ( I = COMMD ) THEN
627     BEGIN
628       WRITELN;
629       WRITELN(' ', I, 2,
630         'DISTANCE IN FT FROM PRIORITY 1 ADAPTER ON TRUNK 2 : ');
631       READLN( DISTFRTA1 );
632       WRITELN;
633       WRITELN(' ', I, 2,
634         'ADAPTER PRIORITY: GIVE IN INTEGER FORM, IE. 1,2,...');
635       WRITELN(' ', I, 2, 'THIS IS USED TO CALCULATE PRIORITY DELAY');
636       READLN ( P2 );
637       WRITELN;
638       FIX2DELAY := TRUNKLENGTHM[2] * 4.0E-09 + 2.08E-06;
639       WRITELN(' ', I, 2, 'THE ADAPTER COMMON TO BOTH TRUNKS');
640       WRITELN(' ', I, 2, 'MUST HAVE AT LEAST ONE ATTACHED ');
641       WRITELN(' ', I, 2, 'DEVICE WITH AN ACTIVE DATA SOURCE');
642       END;
643
644   [ BEGIN INDIVIDUAL DEVICE DESCRIPTIONS ]
645
646   FOR J := 1 TO 4 DO
647     BEGIN
648       WITH ADAPTER[I], DEVICE[J] DO
649         BEGIN
650           OPEN := TRUE;
651           WRITELN;
652           WRITELN(' ', I, 2, 'ADAPTER ', I, 2, ' DEVICE ', J, 2,
653             ' DESCRIPTION');
654           WRITELN(' ', I, 2, 'DEVICE STATUS: 0) OPEN 1) CLOSED ');
655           REPEAT READ( RESP[I]) UNTIL RESP[I] <> ' '; READLN;
656           IF ( RESP[I] = '0') OR ( RESP[I] = '1') THEN OPEN := FALSE;
657           IF NOT (OPEN) THEN
658             BEGIN
659

```

```

659 WRITELN( ' ': 4, 'DEVICE ID (<=24 CHAR)');
660 READLN( ID);
661
662 WRITELN( ' ': 4,
663         'DEVICE TO ADAPTER I/O RATE (BYTES/S):');
664 READLN( TFERRATE);
665 TFERRATE := TFERRATE * 8;
666 LOADTIME := 1.0 / TFERRATE;
667
668 WRITELN( ' ': 4,
669         'NUMBER OF DATA SOURCES IN DEVICE ', J: 1);
670 READLN( NUMOFSOURCES);
671
672 FOR K := 1 TO NUMOFSOURCES DO
673     WITH ADAPTERC[J],DEVICEC[J],SOURCEC[K] DO
674     BEGIN
675         DISTFROMA1 := ADAPTERC[J].DISTFROMA1;
676         IF ( I = COMAD ) AND (I=UNKS) THEN
677             DISTFRTA1 := ADAPTERC[J].DISTFRTA1;
678         WRITELN;
679         WRITELN( ' ': 5, 'DATA SOURCE ', K:1, ' ID');
680         READLN( ID );
681
682         DNUM := I * 100 + J * 10 + K;
683         WRITELN;
684         WRITELN( ' ': 5, 'SOURCEC', K: 1,
685                 ' DATA GEN RATE (BYTES/S)');
686         READLN( GENRATE);
687         GENRATE := GENRATE * 8;
688         WRITELN( ' ': 5, 'BUFFER SIZE IN BYTES:');
689         READLN( BUFFERSIZE);
690         BUFFERSIZE := BUFFERSIZE * 8;
691         DATBLACT := BUFFERSIZE / 1024;
692         TFERRATE := ADAPTERC[J].DEVICEC[J].TFERRATE;
693         OFFLOAD := OFFLOAD + GENRATE;
694         IF GENRATE > 0.0 THEN
695             TXINTRVL := BUFFERSIZE / GENRATE
696         ELSE
697             TXINTRVL := 1E7;
698
699         NEXTX := TXINTRVL;
700
701     WITH ADAPTERC[J],DEVICEC[J],SOURCEC[K] DO
702     BEGIN
703         WRITELN( ' ': 2,
704                 'A LIST OF POSSIBLE RECEIVERS AND THE PROBABILITY');
705         WRITELN( ' ': 2, 'OF ADAPTER', I:1, J, 'DEVICE', J:1,
706                 ' ', SOURCEC[K:2, 'J' TRANSMITTING ');
707         WRITELN( ' ': 2, 'TO THEM WILL NOW BE MADE. ');
708         WRITELN;
709         WRITELN( ' ': 2,
710                 'ID OF THE RECEIVER WILL BE A 3 DIGIT CODE BASED');
711         WRITELN( ' ': 2,
712                 'ON THE ADAPTER#, DEVICE#, AND SOURCE# ');
713

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714 WRITELN('12',
715 'THE PROBABILITY MUST BE GIVEN AS A REAL NUMBER');
716 WRITELN('12',
717 'LESS THAN OR EQUAL TO 1. ENTER 0 FOR ID TO ');
718 WRITELN('12','COMPLETE THE LIST. ');
719
720 CURRENT := FIRST;
721 (*NEW(CURRENT)); FIRST := CURRENT;*)
722 WRITELN('RECEIVER ID CODE ? ( 0 TO END LIST)');
723 READLN(A);
724 WRITELN;
725 IF (A = 0) THEN
726 BEGIN
727   CURRENT := NIL;
728   C := CURRENT;
729   FIRST := CURRENT;
730 END
731 ELSE
732 BEGIN
733   WRITELN('PROBABILITY ?');
734   READLN(B);
735   CURRENT^.ID := A;
736   CURRENT^.PROB := B;
737   C := CURRENT;
738 END;
739
740 WHILE C <> NIL DO
741 BEGIN
742   NEW(PTR);
743   WRITELN('RECEIVER ID ?');
744   READLN(A);
745   IF (A = 0) THEN
746 BEGIN
747   CURRENT^.NEXT := NIL;
748   DISPOSE(PTR);
749   C := NIL;
750 END
751 ELSE
752 BEGIN
753   WRITELN('PROBABILITY ?');
754   READLN(B);
755   WRITELN;
756   PTR^.ID := A;
757   PTR^.PROB := B;
758   CURRENT^.NEXT := PTR;
759   CURRENT := PTR;
760   C := PTR;
761 END;
762 END;
763
764 END; [ FOR K ]
765 END; [ IF NOT(OPEN) ]
766 END; [ WITH ADAPTER() ]
767
768 END; [ ?FOR J=1 TO 4 ]

```

```

769      END; [ FOR I=1 TO NUM OF ADAPTERS ]
770      END;
771      TEMP := 0.0;
772      TEMP1 := 0.0;
773      A := 0;
774      FOR I := 1 TO COMAD DO
775          BEGIN
776              A := ADAPTERC[I].P1;
777              SORTC[I] := I;
778          END;
779
780      FOR I := 1 TO COMAD DO
781          WITH ADAPTERC[I] DO
782              BEGIN
783                  IF I = 1 THEN
784                      ADAPTERC[SORTC[I]].PRI1DELAY := 0.48E-06
785                  ELSE
786                      ADAPTERC[SORTC[I]].PRI1DELAY := ADAPTERC[SORTC[I-1]].PRI1DELAY +
787                      ABS(ADAPTERC[SORTC[I]].DISTFROM1 -
788                      ADAPTERC[SORTC[I-1]].DISTFROM1) * 4.0E-09 + 1.6E-06;
789                  END;
790
791      FOR I := 1 TO COMAD DO
792          BEGIN
793              TEMP := ADAPTERC[I].DISTFROM1;
794              FOR J := 1 TO COMAD DO
795                  IF TEMP <= ADAPTERC[J].DISTFROM1 THEN
796                      TEMP := ADAPTERC[J].DISTFROM1;
797              END;
798
799      WITH ADAPTERC[I] DO
800          BEGIN
801              ADAPTERC[I].END1DELAY := ADAPTERC[SORTC[COMAD]].PRI1DELAY +
802              TEMP * 4.0E-09 + 1.6E-06;
803              TEMP1 := ADAPTERC[I].END1DELAY;
804              IF TEMP1 <= ADAPTERC[I].END1DELAY THEN
805                  TEMP1 := ADAPTERC[I].END1DELAY;
806          END;
807
808      FOR I := 1 TO COMAD DO
809          WITH ADAPTERC[I] DO
810              BEGIN
811                  ADAPTERC[I].END1DELAY := TEMP1;
812                  ADAPTERC[I].TOT1DELAY := FIX1DELAY + TEMP1;
813              END;
814
815      IF TRUNKS THEN
816          BEGIN
817              FOR I := (COMAD + 1) TO NUMOFADAPTERS DO
818                  WITH ADAPTERC[I] DO
819                      BEGIN
820                          WRITELN;
821                          WRITELN('ADAPTER #', I: 2, ':');
822                          WRITELN;
823

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824 WRITELN(' ',2,
825 'DISTANCE IN FT FROM PRIORITY 1 ADAPTER OF TRUNK 2 : ');
826 READLN( DISTRTA1);
827
828 WRITELN;
829 WRITELN(' ',2,
830 'ADAPTER PRIORITY : GIVE IN INTEGER FORM, IE. N= 1,2,3,4);
831 WRITELN(' ',2, 'THIS IS USED TO CALCULATE PRIORITY DELAY');
832 READLN( P2);
833 FIXZDELAY := TRUNKLENGTH[2] * 4.0E-09 + 2.00E-06;
834 WRITELN;
835 WRITELN;
836 WRITELN(' ',2,
837 'ADAPTER RETRY COUNT : THIS MUST BE A UNIQUE NUMBER');
838 WRITELN(' ',25,'FOR EACH ADAPTER IN THE RANGE OF 0 TO 64');
839 READLN( RETRYCT );
840 WRITELN;
841 FOR J := 1 TO 4 DO
842 BEGIN
843 WITH ADAPTERC[J].DEVICEC[J] DO
844 BEGIN
845 OPEN := TRUE;
846 WRITELN;
847 WRITELN(' ',2,'ADAPTER ',J:2,' DEVICE ',J:2,
848 'DESCRIPTION ');
849 WRITELN(' ',4,'DEVICE STATUS: OPEN OR CLOSED ');
850 REPEAT READ (RESPC[J]) UNTIL RESPC[J] <> ' '; READLN;
851 IF (RESPC[J] = 'C') OR (RESPC[J] = 'C') THEN
852 OPEN := FALSE;
853 IF NOT(OPEN) THEN
854 BEGIN
855 WRITELN(' ',4,'DEVICE ID (<=24 CHAR)');
856 READLN( ID );
857
858 WRITELN(' ',4,
859 'DEVICE TO ADAPTER I/O RATE (BYTES/SEC):');
860 READLN (TFERRATE);
861 TFERRATE := TFERRATE * 8;
862 LOADTIME := 1.0/TFERRATE;
863
864 WRITELN(' ',4,
865 'NUMBER OF DATA SOURCES IN DEVICE ',J:1);
866 READLN( NUMOFsources );
867
868 FOR K := 1 TO NUMOFsources DO
869 WITH ADAPTERC[J].DEVICEC[J].SOURCEC[K] DO
870 BEGIN
871 DISTRTA1 := ADAPTERC[J].DISTRTA1;
872 WRITELN;
873 WRITELN(' ',5,'DATA SOURCE', K:1, ' ID');
874 READLN( ID );
875 DNUM := I * 100 + J * 10 + K;
876 WRITELN;
877 WRITELN(' ',5,'SOURCEC',K:1,
878 'J DATA GEN RATE (BYTES/SEC)');

```

```

879 READLN( GENRATE );
880 GENRATE := GENRATE * 8;
881 WRITELN( '5, BUFFER SIZE IN BYTES:');
882 READLN( BUFFERSIZE );
883 BUFFERSIZE := BUFFERSIZE * 8;
884 DATALECT := BUFFERSIZE / 16384;
885 TFERRATE := ADAPTER[I].DEVICE[J].TFERRATE;
886 OFFLOAD := OFFLOAD + GENRATE;
887 IF GENRATE > 0.0 THEN
888   TXINTRVL := BUFFERSIZE / GENRATE
889 ELSE
890   TXINTRVL := 1E7;
891
892 NEXTJ := TXINTRVL;
893
894 WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
895 BEGIN
896   WRITELN( '2,
897   'AS BEFORE A LIST OF RECEIVERS, PROBABILITY ');
898   WRITELN( '2,
899   'WILL BE MADE. USE 0 FOR ID TO FINISH LIST');
900   A := 0;
901   B := C.O;
902   CURRENT := FIRST;
903   WRITELN( 'RECEIVER ID CODE ? ( 0 TO END LIST)');
904   READLN( A );
905   WRITELN;
906   IF A = 0 THEN
907     BEGIN
908       CURRENT := NIL;
909       C := CURRENT;
910       FIRST := CURRENT;
911     END
912   ELSE
913     BEGIN
914       WRITELN( 'PROBABILITY ?');
915       READLN( B );
916       CURRENT^.ID := A;
917       CURRENT^.PROB := B;
918       C := CURRENT;
919     END;
920   WHILE C <> NIL DO
921     BEGIN
922       NEW( PTR );
923       WRITELN( 'RECEIVER ID ? ( 0 TO END LIST)');
924       READLN( A );
925       IF A = 0 THEN
926         BEGIN
927           CURRENT^.NEXT := NIL;
928           C := NIL; DISPOSE( PTR );
929         END
930       ELSE
931         BEGIN
932           WRITELN;
933           WRITELN( 'PROBABILITY ?');

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934 READLN( B );
935 PTR-ID := A;
936 PTR-PROB := B;
937 CURRENT-NEXT := PTR;
938 CURRENT := PTR;
939 C := PTR;
940 END;
941 END;
942 END;
943 END;
944 END;
945 END;
946 END;
947 END;
948 END;
949 END;
950 IF TRUNKS THEN
951 BEGIN
952 A := 0;
953 FOR I := COMHAD TO NUMOFADAPTERS DO
954 BEGIN
955 A := ADAPTER[I].P2 + ( COMHAD - 1 );
956 SORT1[A] := I;
957 END;
958 END;
959 FOR I := COMHAD TO NUMOFADAPTERS DO
960 WITH ADAPTER[I] DO
961 BEGIN
962 IF ( I = COMHAD ) THEN
963 ADAPTER[SORT1[I]].PRI2DELAY := 0.48E-06
964 ELSE
965 ADAPTER[SORT1[I]].PRI2DELAY := ADAPTER[SORT1[I-1]].PRI2DELAY +
966 ABS(ADAPTER[SORT1[I]].DISTFRTA1 -
967 ADAPTER[SORT1[I-1]].DISTFRTA1) * 4.0E-09 + 1.6E-06;
968 END;
969 TEMP := 0.0;
970 TEMP1 := 0.0;
971 FOR I := COMHAD TO NUMOFADAPTERS DO
972 BEGIN
973 TEMP := ADAPTER[I].DISTFRTA1;
974 FOR J := COMHAD TO NUMOFADAPTERS DO
975 IF TEMP <= ADAPTER[J].DISTFRTA1 THEN
976 TEMP := ADAPTER[J].DISTFRTA1;
977 WITH ADAPTER[I] DO
978 BEGIN
979 ADAPTER[I].END2DELAY := ADAPTER[SORT1[ NUMOFADAPTERS ] ].PRI2DELAY
980 + 4.0E-09 * TEMP + 1.6E-06;
981 TEMP1 := ADAPTER[I].END2DELAY;
982 IF TEMP1 <= ADAPTER[I].END2DELAY THEN
983 TEMP1 := ADAPTER[I].END2DELAY;
984 END;
985 END;
986 END;
987 END;
988

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OF POOR QUALITY

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999 FOR I := COMAD TO NUMCFADAPTERS DO
990 BEGIN
991     ADAPTERC[J].END2DELAY := TEMP1;
992     ADAPTERC[J].TOT2DELAY := TEMP1 + ADAPTERC[J].FIX2DELAY;
993 END;
994
995 END;
996
997
998 RE-WRITEDFILE;
999 END; [ INTERACTIVE CASE ]
1000
1001 FILEINPUT;
1002 BEGIN
1003     (*OPEN(DFILE,'DESCRIP',OLD)?*)
1004     RESET(DFILE);
1005
1006 READLN(DFILE, NUMOFTRUNKS);
1007 FOR I := 1 TO NUMOFTRUNKS DO READLN(DFILE, TRUNKLENGTH[I]);
1008
1009 READLN(DFILE, NUMCFADAPTERS);
1010 READLN(DFILE, COMAD);
1011 FOR I := 1 TO COMAD DO
1012 BEGIN
1013     WITH ADAPTERC[J] DO
1014 BEGIN
1015     READLN(DFILE, DISTFROM1);
1016     READLN(DFILE, PRI1DELAY);
1017     READLN(DFILE, END1DELAY);
1018     FIX1DELAY := TRUNKLENGTH[1] * 4.0E-09 + 2.08E-06;
1019     TOT1DELAY := FIX1DELAY + END1DELAY;
1020     READLN(DFILE, RETRYCT);
1021     IF ( TRUNKS ) AND ( I = COMAD ) THEN
1022 BEGIN
1023     READLN(DFILE, DISTFRT1);
1024     READLN(DFILE, PRI2DELAY);
1025     READLN(DFILE, END2DELAY);
1026     FIX2DELAY := TRUNKLENGTH[2] * 4.0E-09 + 2.08E-06;
1027     TOT2DELAY := FIX2DELAY + END2DELAY;
1028 END;
1029
1030 [ BEGIN INDIVIDUAL DEVICE DESCRIPTIONS ]
1031
1032 FOR J := 1 TO 4 DO
1033 BEGIN
1034     WITH ADAPTERC[J],DEVICEC[J] DO
1035 BEGIN
1036     REPEAT
1037     READ(DFILE, RESP[1])
1038     UNTIL RESP[1] <> ' '; READLN(DFILE);
1039     IF (RESP[1] = 'F') OR (RESP[1] = 'f') THEN
1040 OPEN := FALSE
1041     ELSE
1042 OPEN := TRUE;
1043 IF NOT OPEN THEN

```



ORIGINAL IN  
OF POOR QUALITY

```

1044 BEGIN
1045 READLN(DFILE, ID);
1046
1047 READLN(DFILE, TFERRATE);
1048 IF TFERRATE <> 0.0 THEN
1049   LOADTIME := 1.0 / TFERRATE
1050 ELSE
1051   LOADTIME := 0.0;
1052
1053 READLN(DFILE, NUMOFSOURCES);
1054
1055 FOR K := 1 TO NUMOFSOURCES DO
1056   WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
1057     BEGIN
1058       OPEN := FALSE;
1059       DISTFROM1 := ADAPTER[I].DISTFROM1;
1060       IF (I = COMMA) AND (TRUNKS) THEN
1061         DISTFROM1 := ADAPTER[I].DISTFROM1;
1062       READLN(DFILE, DNUM);
1063       READLN(DFILE, ID);
1064       READLN(DFILE, GENRATE);
1065       READLN(DFILE, BUFFERIZE);
1066       READLN(DFILE, DATABLKCT);
1067       TFERRATE := ADAPTER[I].DEVICE[J].TFERRATE;
1068       OFFLOAD := OFFLOAD + GENRATE;
1069       IF GENRATE > 0.0 THEN
1070         TXINTRVL := BUFFERIZE / GENRATE
1071       ELSE
1072         TXINTRVL := 1E7;
1073
1074       NEXTX := TXINTRVL;
1075       WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
1076         BEGIN
1077           CURRENT := FIRST;
1078           READLN(DFILE, A);
1079           IF A = 0 THEN
1080             BEGIN
1081               CURRENT := NIL;
1082               FIRST := CURRENT;
1083             END
1084           ELSE
1085             BEGIN
1086               READLN(DFILE, B);
1087               CURRENT.ID := A;
1088               CURRENT.PROB := B;
1089               WHILE A <> 0 DO
1090                 BEGIN
1091                   NEW(PTR);
1092                   READLN(DFILE, A);
1093                   IF A = 0 THEN
1094                     BEGIN
1095                       CURRENT.NEXT := NIL;
1096                       DISPOSE (PTR);
1097                     END
1098                   END
1099

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ORIGINAL TO 102  
OF POOR QUALITY

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1099 ELSE
1100 BEGIN
1101 READLN(DFILE, B);
1102 PTR^ID := A;
1103 PTR^PROG := B;
1104 CURRENT^NEXT := PTR;
1105 CURRENT := PTR;
1106 END;
1107 END;
1108 END;
1109 END;
1110 END; [ FOR K:=1 TO NUM OF SOURCES ]
1111 END; [ IF NOT(OPEN) ]
1112 END; [ WITH ADAPTER().DEVICE() ]
1113 END; [ FOR J=1 TO 4 ]
1114 END; [ WITH ADAPTER() ]
1115 END; [ FOR I=1 TO NUM OF ADAPTERS ]
1116
1117 IF TRUNKS THEN
1118 BEGIN
1119 FOR I := (COMPAD + 1) TO NUMOFADAPTERS DO
1120 BEGIN
1121 WITH ADAPTER[I] DO
1122 BEGIN
1123 READLN(DFILE, DISTRTA1);
1124 READLN(DFILE, PRIZDELAY);
1125 READLN(DFILE, ENDZDELAY);
1126 FIXZDELAY := TRUNKLENGTHI2 * 4.0E-09 + 2.08E-06;
1127 TOTZDELAY := FIXZDELAY + ENDZDELAY;
1128 READLN(DFILE, RETRYCT);
1129
1130 (* BEGIN INDIVIDUAL DEVICE DESCRIPTIONS *)
1131 FOR J := 1 TO 4 DO
1132 BEGIN
1133 WITH ADAPTER[I].DEVICE[J] DO
1134 BEGIN
1135 REPEAT
1136 READ (DFILE, RESP[I]) UNTIL
1137 RESP[I] <> ' '; READLN(DFILE);
1138 IF (RESP[I] = 'P') OR (RESP[I] = 'F') THEN
1139 OPEN := FALSE
1140 ELSE
1141 OPEN := TRUE;
1142 IF NOT(OPEN) THEN
1143 BEGIN
1144 READLN(DFILE, ID);
1145 READLN(DFILE, TFERRATE);
1146 IF TFERRATE <> 0.0 THEN
1147 LOADTIME := 1.0 / TFERRATE
1148 ELSE
1149 LOADTIME := 0.0;
1150 READLN(DFILE, NUMOF SOURCES);
1151 FOR K := 1 TO NUMOF SOURCES DO
1152 WITH ADAPTER[I].DEVICE[J].SOURCECK DO
1153

```

```

1154 BEGIN
1155   DISTFRTA1 := ADAPTERC[I].DISTFRTA1;
1156   READLN(DFILE, DNUN);
1157   READLN(DFILE, ID);
1158   READLN(DFILE, GENRATE);
1159   READLN(DFILE, BUFFER SIZE);
1160   TFERRATE := ADAPTERC[I].DEVICEC[I].TFERRATE;
1161   READLN(DFILE, DATA BKCT);
1162   OFFLOAD := OFFLOAD + GENRATE;
1163   IF GENRATE > 0.0 THEN
1164     TXINTRVL := BUFFER SIZE / GENRATE
1165   ELSE
1166     TXINTRVL := 1.0E7;
1167   NEXTX := TXINTRVL;
1168   WITH ADAPTERC[I].DEVICEC[I].SOURCEC[K] DO
1169     BEGIN
1170       CURRENT := FIRST;
1171       READLN(DFILE, A);
1172       IF A = 0 THEN
1173         BEGIN
1174           CURRENT := NIL;
1175           FIRST := CURRENT;
1176         END
1177       ELSE
1178         BEGIN
1179           READLN(DFILE, B);
1180           CURRENT^.ID := A;
1181           CURRENT^.PROB := B;
1182           WHILE A <> 0 DO
1183             BEGIN
1184               NEW( PTR );
1185               READLN(DFILE, A);
1186               IF A = 0 THEN
1187                 BEGIN
1188                   CURRENT^.NEXT := NIL;
1189                   DISPOSE(PTR);
1190                 END
1191               ELSE
1192                 BEGIN
1193                   READLN(DFILE, B);
1194                   PTR^.ID := A;
1195                   PTR^.PROB := B;
1196                   CURRENT^.NEXT := PTR;
1197                   CURRENT := PTR;
1198                 END;
1199             END;
1200           END;
1201         END;
1202       END;
1203     END;
1204   END;
1205 END;
1206 END;
1207 END;
1208 END;
1209

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```

1209      END;
1210      END;
1211      END; [ FILE_INPUT CASE ]
1212
1213      END; [ CASE ]
1214
1215      END; [ PROCEDURE CHARACTERIZE NETWORK ]
1216
1217
1218
1219
1220
1221
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1260
1261
1262
1263

[.....]
[.....]

PROCEDURE PRINTNETDESCRIPTION;
[.....]
[.....]
[.....]
[.....]

VAR
  I, L, J, K, KK, LL, S : INTEGER;
BEGIN [ PROCEDURE PRINT DESCRIPTION ]

  (*OPEN(AUXOUT,'AUXOUT',OLD);*)
  REWRITE(AUXOUT);
  FOR I := 1 TO COMAD DO
    BEGIN
      Writeln(AUXOUT);
      Writeln(AUXOUT, ' : 10,
      .....');
      Writeln(AUXOUT, ' : 10,
      .....');
      Writeln(AUXOUT);
      Writeln(AUXOUT, ' : 10, '
      Writeln(AUXOUT, ' : 31, 'ADAPTER #', I: 3);
      Writeln(AUXOUT);
      Writeln(AUXOUT, ' : 10,
      .....');
      Writeln(AUXOUT, ' : 10,
      .....');

    WITH ADAPTER[I] DO
      BEGIN
        Writeln(AUXOUT);
        Writeln(AUXOUT);
        Writeln(AUXOUT, 'ADAPTER #', I: 2, ':');
        J := 1;
        Writeln(AUXOUT);

        Writeln(AUXOUT, ' : 4, 'PRIORITY DELAY ON TRUNK 1 : ');

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1264	1265	1266	1267	1268	1269	1270	1271	1272	1273	1274	1275	1276	1277	1278	1279	1280	1281	1282	1283	1284	1285	1286	1287	1288	1289	1290	1291	1292	1293	1294	1295	1296	1297	1298	1299	1300	1301	1302	1303	1304	1305	1306	1307	1308	1309	1310	1311	1312	1313	1314	1315	1316	1317	1318	1319	1320	1321	1322	1323	1324	1325	1326	1327	1328	1329	1330	1331	1332	1333	1334	1335	1336	1337	1338	1339	1340	1341	1342	1343	1344	1345	1346	1347	1348	1349	1350	1351	1352	1353	1354	1355	1356	1357	1358	1359	1360	1361	1362	1363	1364	1365	1366	1367	1368	1369	1370	1371	1372	1373	1374	1375	1376	1377	1378	1379	1380	1381	1382	1383	1384	1385	1386	1387	1388	1389	1390	1391	1392	1393	1394	1395	1396	1397	1398	1399	1400	1401	1402	1403	1404	1405	1406	1407	1408	1409	1410	1411	1412	1413	1414	1415	1416	1417	1418	1419	1420	1421	1422	1423	1424	1425	1426	1427	1428	1429	1430	1431	1432	1433	1434	1435	1436	1437	1438	1439	1440	1441	1442	1443	1444	1445	1446	1447	1448	1449	1450	1451	1452	1453	1454	1455	1456	1457	1458	1459	1460	1461	1462	1463	1464	1465	1466	1467	1468	1469	1470	1471	1472	1473	1474	1475	1476	1477	1478	1479	1480	1481	1482	1483	1484	1485	1486	1487	1488	1489	1490	1491	1492	1493	1494	1495	1496	1497	1498	1499	1500
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1319 WRITE(AUXOUT, ' : 34, 'SOURCE #', K: 2,
1320 ' DATA GENERATION RATE: ');
1321 WRITELN(AUXOUT, SOURCECK[3].GENRATE / 8: 9: 2, ' BYTES');
1322 WRITELN(AUXOUT, ' : 34, 'TRUNK TRANSMISSION INTERVAL: ',
1323 'TXINTVL: 7: 4, ' SEC');
1324
1325 WRITELN(AUXOUT, ' : 34, 'DATA BLOCK COUNT : ', DATABLKCT);
1326
1327 WRITE (AUXOUT, 'POSSIBLE RECEIVERS AND THEIR',
1328 ' RESPECTIVE PROBABILITIES FOR: ' , DMUN: 3);
1329
1330 WRITELN(AUXOUT);
1331 WITH ADAPTER[I].DEVICE[J].SOURCECK DO
1332 BEGIN
1333 C := FIRST;
1334 WHILE C <> NIL DO
1335 BEGIN
1336 WRITE (AUXOUT, 'RECEIVER ID: ', C.ID: 3);
1337 WRITELN(AUXOUT, ' : 20, 'PROBABILITY: ', C.PROB: 5 );
1338 C := C.NEXT;
1339 END;
1340 END;
1341 END; [ FOR K:=1 TO NUM OF SOURCES ]
1342 END; [ IF NOT(OPEN) ]
1343 END; [ WITH ADAPTER().DEVICE() ]
1344 END; [ FOR J=1 TO 4 ]
1345 END; [ WITH ADAPTER() ]
1346 FOR S := 1 TO 5 DO WRITELN(AUXOUT);
1347 END; [ FOR I ]
1348
1349 IF TRUNKS THEN
1350 BEGIN
1351 FOR I := ( COMAD + 1 ) TO NUMCFADAPTERS DO
1352 BEGIN
1353 WRITELN(AUXOUT);
1354 ' : 10,
1355 '.....
1356 WRITELN(AUXOUT, ' : 10,
1357 '.....
1358 WRITELN(AUXOUT);
1359 WRITELN(AUXOUT, ' : 10, ' NETWORK DESCRIPTION';
1360 WRITELN(AUXOUT, ' : 31, 'ADAPTER # ', I: 3 );
1361 WRITELN(AUXOUT);
1362 WRITELN(AUXOUT, ' : 10,
1363 '.....
1364 WRITELN(AUXOUT, ' : 10,
1365 '.....
1366
1367 WITH ADAPTER[I] DO
1368 BEGIN
1369 WRITELN(AUXOUT);
1370 WRITELN(AUXOUT);
1371 WRITELN(AUXOUT, 'ADAPTER # ', I: 2, ' : ');
1372 J := 1;
1373

```

```

WRITE(AUXOUT,' :14, 'PRIORITY DELAY ON TRUNK 2 : ');
WRITE(AUXOUT,' PRIZDELAY: 9: 7, 'SECS');
WRITE(AUXOUT,' :14, 'FIXED DELAY ON TRUNK 2 : ');
WRITE(AUXOUT,' FX2DELAY: 9: 7, 'SECS');
WRITE(AUXOUT,' :14, 'TOTAL DELAY ON TRUNK 2 : ');
WRITE(AUXOUT,' TOT2DELAY: 9: 7, 'SECS');
WRITE(AUXOUT,' :14, 'ADAPTER RETRY COUNT : ');
WRITE(AUXOUT,' RETRYCT: 3);

FOR J := 1 TO 4 DO
  BEGIN
    WITH ADAPTER[I].DEVICEC[J] DO
      BEGIN
        WRITE(AUXOUT);
        WRITE (AUXOUT,' :14, 'DEVICE ',J:2);
        WRITE (AUXOUT,' :12, 'STATUS : ');
        IF OPEN THEN
          BEGIN
            WRITE(AUXOUT,' 'OPEN');
          END
        ELSE
          BEGIN
            WRITE (AUXOUT,' 'CLOSED');
            IF NOT(OPEN) THEN
              BEGIN
                WRITE (AUXOUT,' :12, 'ID ');
                WRITE (AUXOUT,' :132, 'I/O BUS TRANSFER RA
                WRITE(AUXOUT,' TPERATE / 8:12:2, ' BYTES/
                WRITE(AUXOUT,' :132, 'LOAD TIME: ', LOADT
                  ' SEC');
                WRITE (AUXOUT,' :132, 'NUMBER OF DATA SOUR
                WRITE(AUXOUT,' NUMDSOURCES: 3);
                FOR K := 1 TO NUMOFDSOURCES DO
                  BEGIN
                    WITH ADAPTER[I].DEVICEC[J].SOURCEC[K] DO
                      BEGIN
                        WRITE(AUXOUT,' :132, 'ID');
                        WRITE(AUXOUT,' :136, 'DEVICE NUMBER ',
                        WRITE (AUXOUT,' :134, 'BUFFER SIZE: ');
                        WRITE(AUXOUT,' BUFFER SIZE / 8:9, 'BYTE
                        WRITE (AUXOUT,' :136, 'SOURCE W', K:2,
                        'DATA GENERATION RATE:
                        WRITE(AUXOUT,' SOURCEC[K].G-RATE / 8:
                        WRITE(AUXOUT,' :136, 'TRUNK TRANSMISSI
                        TXINTVL: 7: 4, 'SECS');
                        WRITE(AUXOUT,'POSSIBLE RECEIVERS AND T
                        'RESPECTIVE PROBABILITIES FOR:
                        WITH ADAPTERC[I].DEVICEC[J].SOURCEC[K] DO
                          BEGIN
                            C := FIRST;

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1429      WHILE C <> NIL DO
1430      BEGIN
1431          WRITE (AUXOUT,'RECEIVER ID: ',C^.ID:3);
1432          Writeln(AUXOUT,' ',20,'PROBABILITY: ',
1433              C^.PROB: 5 );
1434          C := C^.NEXT;
1435      END;
1436      END;
1437      END;
1438      END;
1439      END;
1440      END;
1441      END;
1442      FOR S := 1 TO 5 DO Writeln(AUXOUT);
1443      END;
1444      END;
1445      END; [ PROCEDURE PRINT DESCRIPTION ]
1446      (*****
1447      (*
1448      (*
1449      FUNCTION UNIFORM(VAR SEED: INTEGER): REAL;
1450      (*
1451      (* CALCULATES A PSEUDORANDOM NUMBER IN THE
1452      (* RANGE OF 0 < NUM < 1.
1453      (*
1454      (*
1455      (*****
1456      CONST
1457          L = 29;
1458          C = 217;
1459          M = 1024;
1460      BEGIN
1461          SEED := ((SEED * L) + C) MOD M;
1462          UNIFORM := SEED / M;
1463      END;
1464      (*****
1465      (*****
1466      (*****
1467      (*****
1468      (*****
1469      (*****
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1483      (*****

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1484 BEGIN
1485
1486     RESERVED := FALSE;
1487     PROB := UNIFORM(U);
1488
1489     TWITTER-NEXTTX := 1000.0;
1490     FOR I := 1 TO NUMOFADAPTERS DO
1491         FOR J := 1 TO 4 DO
1492             WITH ADAPTER[I].DEVICE[J] DO
1493                 IF NOT OPEN THEN
1494                     FOR K := 1 TO NUMOF SOURCES DO
1495                         WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
1496                             IF NEXTTX < TWITTER-NEXTTX THEN
1497                                 TWITTER := ADAPTER[I].DEVICE[J].SOURCE[K];
1498
1499     TA := TWITTER-DNUM DIV 100;
1500     TD := (TWITTER-DNUM MOD 100) DIV 10;
1501     TS := TWITTER-DNUM MOD 10;
1502
1503     WITH ADAPTER[TA] DO
1504         WITH TWITTER DO
1505             BEGIN
1506                 FOR L := 1 TO 4 DO
1507                     IF ((FLAG[L]) AND (L <> TD)) OR (FRONTX <> 0) THEN
1508                         RESERVED := TRUE;
1509                     END;
1510                 WITH ADAPTER[TA] DO
1511                     WITH ADAPTER[TA].DEVICE[TD] DO
1512                         WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
1513                             IF RESERVED THEN
1514                                 BEGIN
1515                                     NEXTTX := NEXTTX + (PROB * 10.0E-05);
1516                                     WAITTIME := WAITTIME + (PROB * 10.0E-05);
1517                                     WAITCT := WAITCT + 1;
1518                                     WAITTALLY := WAITTALLY + 1;
1519                                 END;
1520                             END;
1521                             (* FIND NEXT TRANSMITTER *)
1522                         END;
1523
1524     (*****
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1539 VAR
1540 I, J, K      : INTEGER;
1541 FOUND: BOOLEAN;
1542 PROB: REAL;
1543
1544 BEGIN C PROCEDURE TO PICK A RECEIVER ]
1545
1546     PROB := 0.0;
1547     FOUND := FALSE;
1548
1549     WHILE NOT FOUND DO
1550     BEGIN
1551         PROB := UNIFORM(U);
1552         WITH ADAPTER[TA].DEVICE[CTD].SOURCE[CTS] DO
1553             BEGIN
1554                 C := FIRST;
1555                 WHILE C <> NIL DO
1556                     IF C^.PROB > PROB THEN
1557                         BEGIN
1558                             FCUND := TRUE;
1559                             DEST := C^.ID;
1560                             C := NIL;
1561                         END
1562                     ELSE
1563                         C := C^.NEXT;
1564                 END;
1565             END;
1566
1567         WITH ADAPTER[TA].DEVICE[CTD].SOURCE[CTS] DO
1568             BEGIN
1569                 IF TA < COMAD THEN
1570                     IF (DEST DIV 100) > COMAD THEN
1571                         IDEST := COMAD
1572                     ELSE
1573                         IDEST := 0;
1574
1575                 IF TA > COMAD THEN
1576                     IF (DEST DIV 100) < COMAD THEN
1577                         IDEST := COMAD
1578                     ELSE
1579                         IDEST := 0;
1580
1581                 END;
1582                 END; (* PICKA *)
1583
1584             (*****
1585             FUNCTION ACOLLISION : BOOLEAN;
1586
1587             (*
1588             DETERMINES WHETHER OR NOT A COLLISION HAS
1589             OCCURRED ON THE TRUNK UNDER CONSIDERATION.
1590             *)
1591             (*****
1592             VAR
1593             I, J, K      : INTEGER;
1594             TEMP
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1594 BEGIN
1595   TEMP := 0.0;
1596   TIMEDIFF := 0.0;
1597   ACOLLISION := FALSE;
1598
1599   IF TRK1 THEN
1600     BEGIN
1601       FOR I := 1 TO CMAD DO
1602         FOR J := 1 TO 4 DO
1603           WITH ADAPTER[I].DEVICE[J] DO
1604             IF NOT (OPEN) THEN
1605               FOR K := 1 TO NUMOF SOURCES DO
1606                 WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
1607                   BEGIN
1608                     IF TWITTER.DNUM DIV 100 <> I THEN
1609                       IF (M1) OR (M2) OR (M3) OR (M4) OR (M5) OR (M6) THEN
1610                         BEGIN
1611                           TEMP := ABS( TWITTER.DISTFROMA1 - DISTFROMA1 );
1612                           TIMEDIFF := 2 * (TEMP * PROPAGATION);
1613                           IF ABS( TWITTER.NEXTTX - NEXTTX ) <= TIMEDIFF THEN
1614                             WITH ADAPTER[I] DO
1615                               WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
1616                                 BEGIN
1617                                   ACOLLISION := TRUE;
1618                                   COLLECTALL := COLLECTALL + 1;
1619                                   COLLECT := COLLECT + 1;
1620                                   COLLECT := COLLECT + 1;
1621                                   NEXTTX := NEXTTX + FIX1DELAY + PRI2DELAY;
1622                                 END;
1623                               END;
1624                             END;
1625                           END;
1626                         END;
1627                       END;
1628                     END;
1629                   END;
1630                 END;
1631               END;
1632             END;
1633           END;
1634         END;
1635       END;
1636     END;
1637   END;
1638
1639   FOR I := CMAD TO NUMOFADAPTERS DO
1640     FOR J := 1 TO 4 DO
1641       WITH ADAPTER[I].DEVICE[J] DO
1642         IF NOT (OPEN) THEN
1643           FOR K := 1 TO NUMOF SOURCES DO
1644             WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
1645               BEGIN
1646                 IF TWITTER.DNUM DIV 100 <> I THEN
1647                   IF (M1) OR (M2) OR (M3) OR (M4) OR (M5) OR (M6) THEN
1648                     BEGIN
1649                       TEMP := ABS( TWITTER.DISTFROMA1 - DISTFROMA1 );
1650                       TIMEDIFF := 2 * (TEMP * PROPAGATION);
1651                       IF ABS( TWITTER.NEXTTX - NEXTTX ) <= TIMEDIFF THEN
1652                         WITH ADAPTER[I] DO
1653                           WITH ADAPTER[I].DEVICE[J].SOURCE[K] DO
1654                             BEGIN
1655                               ACOLLISION := TRUE;
1656                               COLLECTALL := COLLECTALL + 1;
1657                               COLLECT := COLLECT + 1;
1658                               COLLECT := COLLECT + 1;
1659                               NEXTTX := NEXTTX + FIX2DELAY + PRI2DELAY;
1660                             END;
1661                           END;
1662                         END;
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3362   END;
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3365   END;
3366 END;
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1649      END;
1650      END;
1651      END;
1652      END;
1653      END; (* COLLISION *)
1654      (*****
1655      (*
1656      PROCEDURE UPDATE(COND : CLOCKCOND);
1657      (*
1658      (* THERE ARE SEVEN CASES CONTAINED IN THIS
1659      (* PROCEDURE. EACH ONE IS RESPONSIBLE FOR UP-
1660      (* DATING AN ADAPTER'S VARIOUS STATISTICS CON-
1661      (* CERNING MESSAGE SEQUENCE TRANSMISSION. EACH
1662      (* CASE OPERATES ON AN ADAPTER'S NEXT TRANSMIT
1663      (* TIME AND IN TURN ON OVERALL SIMULATION TIME.
1664      (*
1665      (*****
1666      VAR
1667      RA, RD, RS, I, J, K, L, KK, TA, TS, TD : INTEGER;
1668      A, FOUND : BOOLEAN;
1669      TEMPR, TEMP, TIME, PROB, BITS, BLKCT : REAL;
1670
1671      BEGIN
1672      TIME := 0.0;
1673      KK := 0;
1674      TEMPR := 0.0;
1675      TEMP := 0.0;
1676      PROB := 0.0;
1677      BITS := 0.0;
1678      BLKCT := 0.0;
1679      A := FALSE;
1680      FOUND := FALSE;
1681
1682      TA := TMITTER.DNUM DIV 100;
1683      TD := (TMITTER.DNUM MOD 100) DIV 10;
1684      TS := TMITTER.DNUM MOD 10;
1685
1686      CASE COND OF
1687      CASE1:
1688
1689          BEGIN
1690              WITH ADAPTER[TA] DO
1691              WITH ADAPTER[TA].DEVICE[TD] DO
1692              WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
1693              BEGIN
1694                  DFLAG[TD] := TRUE;
1695                  SFLAG[TS] := TRUE;
1696                  DELAY := 1.0E-06;
1697                  RETRY := 0;
1698                  INITIALTX := NEXTTX;
1699                  M1 := TRUE;
1700                  NEXTTX := NEXTTX + 64.0E-06;
1701                  TOTALATTEMPTS := TOTALATTEMPTS + 1;
1702
1703                  END; (* CASE1 *)

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OF POOR QUALITY

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END;

CASE2:
  BEGIN
    WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
      BEGIN
        IF NOT ACOLLISION THEN
          BEGIN
            WHILE NOT FOUND DO
              BEGIN
                PROB := UNIFORM(U);
                WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
                  BEGIN
                    IF IDEST = COMMAND THEN
                      BEGIN
                        FOR J := 1 TO 4 DO
                          WITH ADAPTER[COMMAND].DEVICE[J] DO
                            IF NOT OPEN THEN
                              BEGIN
                                FOR K := 1 TO NUMOF SOURCES DO
                                  WITH ADAPTER[COMMAND].DEVICE[J].SOURCE[K] DO
                                    BEGIN
                                      IF PROB < 0.5 THEN
                                        BEGIN
                                          ADAPTER[TA].DEVICE[TD].SOURCE[TS].IDEST := DNUM;
                                          FOUND := TRUE;
                                        END;
                                      END;
                                    END
                                  ELSE
                                    FOUND := TRUE;
                                END;
                              END
                            END
                          END
                        END
                      END;
                    END;
                  END;
                END;
              END;
            END;
          END;
        END;
      END;
    END;
  END;

IF IDEST <> 0 THEN
  BEGIN
    TRK2ATTEMPT := TRK2ATTEMPT + 1;
    RA := IDEST DIV 100;
    RD := (IDEST MOD 100) DIV 10;
    RS := IDEST MOD 10;
    WITH ADAPTER[CRA] DO
      BEGIN
        FOR L := 1 TO 4 DO
          IF DFLAG[L] THEN
            A := TRUE;
          END;
        END;
      END;
    ELSE
      BEGIN
        RA := IDEST DIV 100;
        RD := (IDEST MOD 100) DIV 10;
        RS := IDEST MOD 10;
      END;
    END;
  END;

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```

1759 WITH ADAPTER[RA] DO
1760 BEGIN
1761   FOR L := 1 TO 4 DO
1762     IF DFLAG[L] THEN
1763       A := TRUE;
1764     END;
1765   END;
1766 END;
1767
1768 IF NOT A THEN
1769 BEGIN
1770   WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
1771     WITH ADAPTER[RA].DEVICE[RD] DO
1772       WITH ADAPTER[RA] DO
1773         BEGIN
1774           DFLAG[RD] := TRUE;
1775           SFLAG[RS] := TRUE;
1776           FROMTX := TWITTER.DNUM;
1777           IF TRK1 THEN
1778             TEMPR := DISTFROMA1
1779           ELSE
1780             TEMPR := DISTFRTA1;
1781           END;
1782         END;
1783       WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
1784         WITH ADAPTER[TA] DO
1785           BEGIN
1786             IF TRK1 THEN
1787               TEMP := ABS(DISTFROMA1 - TEMPR)
1788             ELSE
1789               TEMP := ABS(DISTFRTA1 - TEMPR);
1790             CARUP := NEXTTX;
1791             CARDOWN := NEXTTX + 12.0E-06 + 2 * (TEMP * PROPAGATION);
1792             NEXTTX := NEXTTX + (CARDOWN - CARUP) + 23.0E-06;
1793             M2 := TRUE;
1794             M1 := FALSE;
1795           END;
1796           IF TRK1 THEN
1797             BEGIN
1798               TRIACTIVE := TRIACTIVE + (CARDOWN - CARUP);
1799               BUSYTIME := BUSYTIME + (CARDOWN - CARUP);
1800               CONT1BITS := CONT1BITS + 600;
1801             END;
1802           ELSE
1803             BEGIN
1804               TR2ACTIVE := TR2ACTIVE + (CARDOWN - CARUP);
1805               BUSYTIME := BUSYTIME + (CARDOWN - CARUP);
1806               CONT2BITS := CONT2BITS + 600;
1807             END;
1808           END;
1809         IF IDEST <> 0 THEN
1810           ^^ := IDEST;
1811         WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
1812
1813

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OF POOR QUALITY.

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1814 BEGIN
1815   BUSYTIME := BUSYTIME + (CARDWN - CARUP);
1816   IF KK <> 0 THEN
1817     DEST := TWITTER.DEST;
1818   END;
1819 END;
1820 ELSE
1821   END
1822 BEGIN
1823   WITH ADAPTER[RA].DEVICE[RD].SOURCECRS] DO
1824     IF TRK1 THEN
1825       TEMPR := DISTFROMA1
1826     ELSE
1827       TEMPR := DISTFRTA1;
1828     END
1829 WITH ADAPTER[TA] DO
1830   WITH ADAPTER[TA].DEVICE[TD] DO
1831   WITH ADAPTER[TA].DEVICE[TD].SOURCECRS] DO
1832   BEGIN
1833     IF TRK1 THEN
1834       TEMP := ABS(TEMPR - DISTFROMA1)
1835     ELSE
1836       TEMP := ABS(TEMPR - DISTFRTA1);
1837     END
1838 CARUP := NEXTTX;
1839 CARDWN := NEXTTX + 12.0E-06 + 2 * (TEMP * PROPAGATION);
1840 IF DELAY < 128.0E-06 THEN
1841   BEGIN
1842     NEXTTX := NEXTTX + DELAY + (CARDWN - CARUP);
1843     DELAY := 2 * DELAY;
1844   END
1845 ELSE
1846   BEGIN
1847     RETRY := RETRY + 1;
1848     IF RETRY > RETRYCT THEN
1849       BEGIN
1850         M1 := FALSE;
1851         M2 := FALSE;
1852         FINALTX := NEXTTX;
1853         MESSDELAY := (FINALTX - INITIALTX) + MESSDELAY;
1854         ABORTCT := ABORTCT + 1;
1855         TOTALABORTS := TOTALABORTS + 1;
1856         DFLAG[TD] := FALSE;
1857         SFLAG[TS] := FALSE;
1858         NEXTTX := NEXTTX + TXINTRVL;
1859         DEST := 0;
1860         IDEST := 0;
1861       END
1862     ELSE
1863       DELAY := 1.0E-06;
1864     END;
1865   END;
1866 END;
1867 : 903

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1869 IF TRK1 THEN
1870 BEGIN
1871   TRIACTIVE := TRIACTIVE + (CARDWN - CARUP);
1872   BUSYTIME := BUSYTIME + (CARDWN - CARUP);
1873   CONT1BITS := CONT1BITS + 600;
1874 END
1875 ELSE
1876 BEGIN
1877   TR2ACTIVE := TR2ACTIVE + (CARDWN - CARUP);
1878   BUSYTIME := BUSYTIME + (CARDWN - CARUP);
1879   CONT2BITS := CONT2BITS + 600;
1880 END;
1881 WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
1882   BUSYTIME := BUSYTIME + (CARDWN - CARUP);
1883 END;
1884 END;
1885 END
1886 ELSE
1887 BEGIN
1888   CARUP := NEXTTX;
1889   CARDWN := NEXTTX + TIMEDIF;
1890   NEXTTX := NEXTTX + FIXEDDELAY + PRIDELAY;
1891   COLLECT := COLLECT + 1;
1892   COLTIME := COLTIME + TIMEDIF;
1893 END;
1894 END;
1895 END;
1896 END; (* CASE 2 *)
1897
1898 CASE3:
1899
1900 BEGIN
1901   WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
1902     BEGIN
1903       IF NOT ACCLISION THEN
1904         BEGIN
1905           IF IDEST <> 0 THEN
1906             BEGIN
1907               RA := IDEST DIV 100;
1908               RD := (IDEST MOD 100) DIV 10;
1909               RS := IDEST MOD 10;
1910             END
1911           ELSE
1912             BEGIN
1913               RA := DEST DIV 100;
1914               RD := (DEST MOD 100) DIV 10;
1915               RS := DEST MOD 10;
1916             END
1917           WRITELN(OUT, RA, RD, RS);
1918         END;
1919       WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
1920         IF TRK1 THEN
1921           TEMPR := DISTFROMA1
1922         END
1923

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1924 ELSE
1925   TEMPR := DISTFRTA1;
1926   IF TRK1 THEN
1927     TEMP := ABS(TEMPR - DISTFROMA1)
1928   ELSE
1929     TEMP := ABS(TEMPR - DISTFRTA1);
1930
1931   CARUP := NEXTTX;
1932   CARDOWN := NEXTTX + 96.5E-06 + 8 * (TEMP * PROPAGATION);
1933
1934   IF TRK1 THEN
1935     BEGIN
1936       CONT2BITS := CONT1BITS + 4313;
1937       DATA1BITS := DATA1BITS + 512;
1938       TRIACTIVE := TRIACTIVE + (CARDOWN - CARUP)
1939     END
1940   ELSE
1941     BEGIN
1942       CONT2BITS := CONT2BITS + 4313;
1943       DATA2BITS := DATA2BITS + 512;
1944       TR2ACTIVE := TR2ACTIVE + (CARDOWN - CARUP);
1945     END;
1946     BUSYTIME := BUSYTIME + (CARDOWN - CARUP);
1947
1948     WITH ADAPTER[CRA].DEVICE[RD].SOURCE[RS] DO
1949       BUSYTIME := BUSYTIME + (CARDOWN - CARUP);
1950
1951     M2 := FALSE;
1952     M3 := TRUE;
1953     NEXTX := NEXTTX + (CARDOWN - CARUP) + 64.0E-06;
1954   END
1955 ELSE
1956   BEGIN
1957     CARUP := NEXTTX;
1958     CARDOWN := NEXTTX + TIMEDIFF;
1959     NEXTTX := NEXTTX + FIXEDDELAY + PRIDELAY;
1960     COLLECT := COLLECT + 1;
1961     COLTIME := COLTIME + TIMEDIFF;
1962   END;
1963 END;
1964 END; (* CASE 3 *)
1965
1966 CASE4:
1967 BEGIN
1968   WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
1969     BEGIN
1970       IF NOT COLLISION THEN
1971         BEGIN
1972           IF IDEST <> 0 THEN
1973             BEGIN
1974               RA := IDEST DIV 100;
1975               RD := (IDEST MOD 100) DIV 10;
1976               RS := IDEST MOD 10;
1977             END
1978           END

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OF POOR QUALITY

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1790 ELSE
1791 BEGIN
1792   RA := DEST DIV 100;
1793   RD := (DEST MOD 100) DIV 10;
1794   RS := DEST MOD 10;
1795 END;
1796 WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
1797 IF TRK1 THEN
1798   TEMPR := DISTFROMA1
1799 ELSE
1800   TEMPR := ABS(TEMPR - DISTFRTA1);
1801 CARUP := NEXTTX;
1802 CARDWN := NEXTTX + 12.0E-06 + 2 * (TEMPR * PROPAGATION);
1803 IF TRK1 THEN
1804 BEGIN
1805   CONTBITS := CONTBITS + 600;
1806   TRIACTIVE := TRIACTIVE + (CARDWN - CARUP)
1807 END
1808 ELSE
1809 BEGIN
1810   CONTBITS := CONTBITS + 600;
1811   TRIACTIVE := TRIACTIVE + (CARDWN - CARUP);
1812 END;
1813 WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
1814   BUSYTIME := BUSYTIME + (CARDWN - CARUP);
1815 M3 := FALSE;
1816 M4 := TRUE;
1817 NEXTTX := NEXTTX + (CARDWN - CARUP) + 29.0E-06;
1818 END
1819 ELSE
1820 BEGIN
1821   CARUP := NEXTTX;
1822   CARDWN := NEXTTX + TIMEDIFF;
1823   NEXTTX := NEXTTX + FIXEDDELAY + PRIDELAY;
1824   COLLECT := COLLECT + 1;
1825   COLTIME := COLTIME + TIMEDIFF;
1826 END;
1827 END;
1828 END; (* CASE 4 *)
1829
1830 CASES:
1831 BEGIN
1832   WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
1833 BEGIN

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ORIGINAL TABLE  
OF POOR QUALITY

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2034 IF NOT ACCLISION THEN
2035 BEGIN
2036 IF (IDEST = 0) AND (NB) THEN
2037   BLKCT := TBLK
2038 ELSE
2039   BLKCT := DATA BLKCT;
2040
2041 IF (BLKCT <= 1) AND (BLKCT > BLKSENT) THEN
2042 BEGIN
2043   TIME := 54.12E-06 + ((BLKCT * 16384) / 50.0E+06);
2044   BLKSENT := BLKSENT + 1;
2045   BITS := BLKCT * 16384;
2046 END
2047 ELSE
2048 BEGIN
2049 IF (BLKCT > 1) AND (BLKCT > (BLKSENT + 1)) THEN
2050 BEGIN
2051   TIME := 412.0E-06;
2052   BLKSENT := BLKSENT + 1;
2053   BITS := 16384;
2054 END
2055 ELSE
2056 BEGIN
2057   PROG := BLKCT - (BLKSENT - 1);
2058   TIME := 54.12E-06 + ((PROG * 16384) / 50.0E+06);
2059   BITS := PROG * 16384;
2060   BLKSENT := BLKSENT + PROG;
2061 END;
2062 END;
2063 IF IDEST <> 0 THEN
2064 BEGIN
2065   RA := IDEST DIV 100;
2066   RD := (IDEST MOD 100) DIV 10;
2067   RS := IDEST MOD 10;
2068 END
2069 ELSE
2070 BEGIN
2071   RA := DEST DIV 100;
2072   RD := (DEST MOD 100) DIV 10;
2073   RS := DEST MOD 10;
2074 END;
2075 WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
2076 IF TRKT THEN
2077   TEMPR := DISTFROMA1
2078 ELSE
2079   TEMPR := DISTFRTA1;
2080
2081 IF TRK1 THEN
2082   TEMP := ABS(TEMPR - DISTFROMA1)
2083 ELSE
2084   TEMP := ABS(TEMPR - DISTFRTA1);
2085
2086 CARUP := NEXTIX;
2087 CARDWN := NEXTIX + TIME + 6 * (TEMP * PROPAGATION);
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IF TRK1 THEN
  BEGIN
    CONT1BITS := CONT1BITS + 4216;
    DATA1BITS := DATA1BITS + BITS;
    TRIACTIVE := TRIACTIVE + (CARDWN - CARUP)
  END
ELSE
  BEGIN
    CONT2BITS := CONT2BITS + 4216;
    DATA2BITS := DATA2BITS + BITS;
    TR2ACTIVE := TR2ACTIVE + (CARDWN - CARUP);
  END;

  BUSYTIME := BUSYTIME + (CARDWN - CARUP);
  WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
    BUSYTIME := BUSYTIME + (CARDWN - CARUP);

  M4 := FALSE;
  M5 := TRUE;
  NEXTTX := NEXTTX + (CARDWN - CARUP) + 34.0E-06;
END
ELSE
  BEGIN
    CARUP := NEXTTX;
    CARDWN := NEXTTX + TIMEDIFF;
    NEXTTX := NEXTTX + FIXEDDELAY + PRIDELAY;
    COLCT := COLCT + 1;
    COLLTIME := COLLTIME + TIMEDIFF;
  END;
END;
END;
END; (* CASE 5 *)

CASE6:
  BEGIN
    WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
      BEGIN
        IF NOT ACCLLISION THEN
          BEGIN
            IF (IDEST = 0) AND (MB) THEN
              BLKCT := TBLK
            ELSE
              BLKCT := DATA[BLKCT];
            IF IDEST <> C THEN
              BEGIN
                RA := IDEST DIV 100;
                RD := (IDEST MOD 100) DIV 10;
                RS := IDEST MOD 10;
              END
            END
          END
        END
      END
    END
  END

```

```

2144 ELSE
2145 BEGIN
2146 RA := DEST DIV 100;
2147 PD := (DEST MOD 100) DIV 10;
2148 RS := DEST MOD 10;
2149 END;
2150
2151 WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
2152 IF TRK1 THEN
2153 TEMPR := DISTFROMA1
2154 ELSE
2155 TEMPR := DISTFRTA1;
2156
2157 IF TRK1 THEN
2158 TEMP := ABS(TEMPR - DISTFROMA1)
2159 ELSE
2160 TEMP := ABS(TEMPR - DISTFRTA1);
2161
2162 CARUP := NEXTTX;
2163 CARDWN := NEXTTX + 12.CE-06 + 2 * (TEMP * PROPAGATION);
2164
2165 IF TRK1 THEN
2166 BEGIN
2167 CONT1BITS := CONT1BITS + 600;
2168 TRIACTIVE := TRIACTIVE + (CARDWN - CARUP)
2169 END
2170 ELSE
2171 BEGIN
2172 CONT2BITS := CONT2BITS + 600;
2173 TRIACTIVE := TRIACTIVE + (CARDWN - CARUP);
2174 END;
2175
2176 BUSYTIME := BUSYTIME + (CARDWN - CARUP);
2177 WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
2178 BUSYTIME := BUSYTIME + (CARDWN - CARUP);
2179 IF BLKSENT >= BLACT THEN
2180 BEGIN
2181 M5 := FALSE;
2182 M6 := TRUE;
2183 NEXTTX := NEXTTX + (CARDWN - CARUP) + 20.0E-06;
2184 END
2185 ELSE
2186 BEGIN
2187 M4 := TRUE;
2188 M5 := FALSE;
2189 NEXTTX := NEXTTX + (CARDWN - CARUP) + 20.0E-06;
2190 END;
2191 END
2192 ELSE
2193 BEGIN
2194 CARUP := NEXTTX;
2195 CARDWN := NEXTTX + TIMEDIFF;
2196 NEXTTX := NEXTTX + FIXEDDELAY + PRIDELEY;
2197 COLLECT := COLLECT + 1;
2198 COLLINE := COLLINE + TIMEDIFF;
2199

```

```

2199      END;
2200      END;
2201      END; (* CASE 6 *)
2202
2203
2204
2205
2206
2207
2208
2209
2210
2211
2212
2213
2214
2215
2216
2217
2218
2219
2220
2221
2222
2223
2224
2225
2226
2227
2228
2229
2230
2231
2232
2233
2234
2235
2236
2237
2238
2239
2240
2241
2242
2243
2244
2245
2246
2247
2248
2249
2250
2251
2252
2253

CASE7:

      BEGIN
      WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
      BEGIN
      IF NOT ACOLLISION THEN
      BEGIN
      IF IDEST <> 0 THEN
      BEGIN
      RA := IDEST DIV 100;
      RD := (IDEST MOD 100) DIV 10;
      RS := IDEST MOD 10;
      END
      ELSE
      BEGIN
      RA := DEST DIV 100;
      RD := (DEST MOD 100) DIV 10;
      RS := DEST MOD 10;
      END;
      END;

      WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
      IF TRK1 THEN
      TEMP := DISTFROMA1
      ELSE
      TEMP := ABS(TEMP - DISTFRTA1);
      TEMP := DISTFRTA1;

      IF TRK1 THEN
      TEMP := ABS(TEMP - DISTFROMA1)
      ELSE
      TEMP := ABS(TEMP - DISTFRTA1);

      CARUP := NEXTIX;
      CARDWN := NEXTIX + 12.0E-06 + 2 * (TEMP * PROPAGATION);

      IF TRK1 THEN
      BEGIN
      SEQTALLY := SEQTALLY + 1;
      TRIACTIVE := TRIACTIVE + (CARDWN - CARUP);
      CONTBITS := CONTBITS + 600;
      END
      ELSE
      BEGIN
      SEQTALLY := SEQTALLY + 1;
      TR2ACTIVE := TR2ACTIVE + (CARDWN - CARUP);
      CONT2BITS := CONT2BITS + 600;
      END;

      SEQTALLY := SEQTALLY + 1;
      SECT := SECT + 1;

```

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```

2254 FINALTX := CARDOWN + 20.0E-06;
2255 MESSDELAY := MESSDELAY + (FINALTX - INITIALTX);
2256 M6 := FALSE;
2257 WITH ADAPTER[CR].DEVICE[CRD].SOURCE[CRS] DO
2258   BUSYTIME := BUSYTIME + (CARDOWN - CARUP);
2259
2260 IF (IDEST = 0) AND (NOT M6) THEN
2261   WITH ADAPTER[TA].DEVICE[TD].SOURCE[CRS] DO
2262     WITH ADAPTER[TA].DEVICE[TD] DO
2263       BEGIN
2264         DFLAG[TD] := FALSE;
2265         SFLAG[TS] := FALSE;
2266         NEXTX := NEXTX + TXINTRVL;
2267         DEST := 0;
2268         BLKSENT := 0.0;
2269         WITH ADAPTER[CR].DEVICE[CRD].SOURCE[CRS] DO
2270           WITH ADAPTER[CR].DEVICE[CRD] DO
2271             WITH ADAPTER[CR] DO
2272               BEGIN
2273                 DFLAG[CRD] := FALSE;
2274                 SFLAG[CRS] := FALSE;
2275                 FRONTX := 0;
2276                 RSECT := RSECT + 1;
2277               END;
2278             END;
2279           END;
2280         END;
2281       IF (IDEST <> 0) AND (NOT M6) THEN
2282         BEGIN
2283           WITH ADAPTER[CR].DEVICE[CRD].SOURCE[CRS] DO
2284             WITH ADAPTER[CR].DEVICE[CRD] DO
2285               WITH ADAPTER[CR] DO
2286                 BEGIN
2287                   TBLK := ADAPTER[TA].DEVICE[TD].SOURCE[CRS].DATA[BLKCT];
2288                   DFLAG[CRD] := FALSE;
2289                   SFLAG[CRS] := FALSE;
2290                   M6 := TRUE;
2291                   NEXTX := ADAPTER[TA].DEVICE[TD].SOURCE[CRS].FINALTX;
2292                   FRONTX := 0;
2293                   RSECT := RSECT + 1;
2294                 END;
2295               WITH ADAPTER[TA] DO
2296                 WITH ADAPTER[TA].DEVICE[TD] DO
2297                   WITH ADAPTER[TA].DEVICE[TD].SOURCE[CRS] DO
2298                     BEGIN
2299                       DFLAG[TD] := FALSE;
2300                       SFLAG[TS] := FALSE;
2301                       NEXTX := NEXTX + TXINTRVL;
2302                       DEST := 0;
2303                       IDEST := 0;
2304                       BLKSENT := 0.0;
2305                     END;
2306                   END;
2307                 END;
2308               IF (IDEST = 0) AND (M6) THEN

```

```

2300 WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
2310 WITH ADAPTER[TA].DEVICE[TD] DO
2311 WITH ADAPTER[TA] DO
2312 BEGIN
2313   TRK2TALLY := TRK2TALLY + 1;
2314   MB := FALSE;
2315   NEXTTX := FINALTX + TXINTRVL;
2316   DFLAG[TD] := FALSE;
2317   SFLAG[TS] := FALSE;
2318   DEST := 0;
2319   FROMTX := 0;
2320   TBLK := 0.0;
2321   BLKSENT := 0.0;
2322
2323 WITH ADAPTER[RA].DEVICE[RD].SOURCE[RS] DO
2324 WITH ADAPTER[RA].DEVICE[RD] DO
2325 WITH ADAPTER[RA] DO
2326 BEGIN
2327   DFLAG[RD] := FALSE;
2328   SFLAG[RS] := FALSE;
2329   FROMTX := 0;
2330   RSEQCT := RSEQCT + 1;
2331   END;
2332 END;
2333 ELSE
2334 BEGIN
2335   CARUP := NEXTTX;
2336   CAROWN := NEXTTX + TIMEDI;
2337   NEXTTX := NEXTTX + FIXEDDELAY + PRIDELAY;
2338   COLCT := COLCT + 1;
2339   COLTIME := COLTIME + TIMEDI;
2340   END;
2341 END;
2342 END; (* CASE 7 *)
2343 END; (* CASE COND OF *)
2344 END;
2345 END; (* UPDATE *)
2346
2347
2348
2349
2350
2351
2352
2353
2354
2355
2356
2357
2358
2359
2360
2361
2362
2363

```



OF FOUR

```

2364 IF TRUNKS THEN
2365 BEGIN
2366   PERTACTIVE := (TR1ACTIVE / CURRENTTIME) * 100;
2367   PER2ACTIVE := (TR2ACTIVE / CURRENTTIME) * 100;
2368   PERTACTIVE := (TIMEACTIVE / CURRENTTIME) * 100;
2369 END
2370 ELSE
2371   PERTACTIVE := (TIMEACTIVE / CURRENTTIME) * 100;
2372
2373 FOR I := 1 TO 15 DO WRITELN(AUXOUT);
2374
2375   WRITELN(AUXOUT, ' :25, '*** END OF RUN NETWORK STATISTIC: ***');
2376   WRITELN(AUXOUT);
2377   WRITELN(AUXOUT, ' :20, 'CURRENT TIME : ', CURRENTTIME:12:4, ' SECS');
2378   WRITELN(AUXOUT);
2379   WRITELN(AUXOUT, ' :20, 'SUCCESSFUL SEQUENCE TRANSMISSIONS : ',
2380     SEQTALLY: 5);
2381 IF TRUNKS THEN
2382 BEGIN
2383   WRITELN(AUXOUT, ' :20, 'SUCCESSFUL SEQUENCE TRANSMISSIONS-TRUNK 1 : ',
2384     SEQTALLY: 5);
2385   WRITELN(AUXOUT, ' :20, 'SUCCESSFUL SEQUENCE TRANSMISSIONS-TRUNK 2 : ',
2386     SEQTALLY: 5);
2387 END;
2388   WRITELN(AUXOUT, ' :20, 'COLLISIONS (FRAMES) : ',
2389     COLLTALLY: 5);
2390   WRITELN(AUXOUT, ' :20, 'WAITS (FRAMES) : ',
2391     WAITALLY: 5);
2392   WRITELN(AUXOUT, ' :20, 'TOTAL ATTEMPTS (SEQUENCES) : ',
2393     TOTALATTEMPTS: 5);
2394   WRITELN(AUXOUT, ' :20, 'TOTAL ABORTS : ',
2395     TOTALABORTS: 5);
2396 IF TRUNKS THEN
2397 BEGIN
2398   WRITELN(AUXOUT, ' :20, 'ATTEMPTED TRUNK-TRUNK TRANSMISSIONS : ',
2399     TRKZATTEMPT: 5);
2400   WRITELN(AUXOUT, ' :20, 'SUCCESSFUL TRUNK-TRUNK TRANSMISSIONS : ',
2401     TRKZTALLY: 5);
2402 END;
2403   WRITELN(AUXOUT);
2404 IF TRUNKS THEN
2405 BEGIN
2406   WRITELN(AUXOUT, ' :20, 'TRUNK 1 ACTIVE TIME : ',
2407     TRIACTIVE: 10, ' SECS');
2408   WRITELN(AUXOUT, ' :20, 'TRUNK 2 ACTIVE TIME : ',
2409     TR2ACTIVE: 10, ' SECS');
2410   WRITELN(AUXOUT, ' :20, 'TOTAL TRUNK ACTIVE TIME : ',
2411     TIMEACTIVE: 10, ' SECS');
2412   WRITELN(AUXOUT, ' :20, 'X TRUNK 1 ACTIVE TIME : ',
2413     PERTACTIVE: 6, ' %');
2414   WRITELN(AUXOUT, ' :20, 'X TRUNK 2 ACTIVE TIME : ',
2415     PER2ACTIVE: 6, ' %');
2416   WRITELN(AUXOUT, ' :20, 'X TOTAL ACTIVE TIME : ',
2417     PERTACTIVE: 6, ' %');
2418 END

```

```

2419 ELSE
2420 BEGIN
2421   WRITELN(AUXOUT, ' :20, 'TOTAL TRUNK ACTIVE TIME : ',
2422     TIMEACTIVE: 10:7, ' SECS');
2423   WRITELN(AUXOUT, ' :20, 'X TOTAL ACTIVE TIME : ',
2424     PERTACTIVE: 0:3, ' X');
2425 END;
2426 WRITELN(AUXOUT);
2427
2428 IF NOT TRUNKS THEN
2429 BEGIN
2430   WRITELN(AUXOUT, ' :20, 'CONTROL BYTES TRANSMITTED : ',
2431     CONTBITS / 8.0E+06:12, ' MBYTES');
2432   WRITELN(AUXOUT, ' :20, 'DATA BYTES TRANSMITTED : ',
2433     DATA1BITS / 8.0E+06:12, ' MBYTES');
2434 END;
2435 ELSE
2436 BEGIN
2437   WRITELN(AUXOUT, ' :20, 'CONTROL BYTES TRANSMITTED - TRUNK 1 : ',
2438     CONT1BITS / 8.0E+06:12, ' MBYTES');
2439   WRITELN(AUXOUT, ' :20, 'DATA BYTES TRANSMITTED - TRUNK 1 : ',
2440     DATA1BITS / 8.0E+06:12, ' MBYTES');
2441   WRITELN(AUXOUT, ' :20, 'CONTROL BYTES TRANSMITTED - TRUNK 2 : ',
2442     CONT2BITS / 8.0E+06:12, ' MBYTES');
2443   WRITELN(AUXOUT, ' :20, 'DATA BYTES TRANSMITTED - TRUNK 2 : ',
2444     DATA2BITS / 8.0E+06:12, ' MBYTES');
2445 END;
2446 WRITELN(AUXOUT, ' :20, 'TOTAL BYTES TRANSMITTED : ',
2447     BITSX / 8.0E+06:12, ' MBYTES');
2448 WRITELN(AUXOUT);
2449 WRITELN(AUXOUT, ' :20, 'TOTAL OFFERED LOAD : ',
2450     (OFFLOAD * CURRENTTIME) / 8.0E+06:12, ' MBYTES');
2451
2452 WRITELN(' :15, ' *** END OF RUN NETWORK STATISTICS ***');
2453 WRITELN;
2454 WRITELN(' :10, ' CURRENT TIME : ', CURRENTTIME: 12: 4, ' SECS');
2455 WRITELN;
2456 WRITELN(' :10, ' SUCCESSFUL SEQUENCE TRANSMISSIONS : ',
2457     SEQTALLY: 5);
2458 IF TRUNKS THEN
2459 BEGIN
2460   WRITELN(' :10, ' SUCCESSFUL SEQUENCE TRANSMISSIONS-TRUNK1 : ',
2461     SEQ1ALLY: 5);
2462   WRITELN(' :10, ' SUCCESSFUL SEQUENCE TRANSMISSIONS-TRUNK2 : ',
2463     SEQ2ALLY: 5);
2464 END;
2465 WRITELN(' :10, ' COLLISIONS (FRAMES) : ',
2466     COLLALLY: 5);
2467 WRITELN(' :10, ' WAITS (FRAMES) : ',
2468     WAITALLY: 5);
2469 WRITELN(' :10, ' TOTAL ATTEMPTS (SEQUENCES) : ',
2470     TOTALATTEMPTS: 5);
2471 WRITELN(' :10, ' TOTAL ABORTS : ',
2472     TOTALABORTS: 5);
2473 IF TRUNKS THEN

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```

2474 BEGIN
2475 WRITELN(' :10, ' ATTEMPTED TRUNK-TRUNK TRANSMISSIONS
2476 TRK2ATTEMPT: 5);
2477 WRITELN(' :10, ' SUCCESSFUL TRUNK-TRUNK TRANSMISSIONS
2478 TRK2TALLY: 5);
2479
2480 WRITELN(' :10, ' TRUNK 1 ACTIVE TIME
2481 TRIACTIVE: 10: 7, ' SECS');
2482 WRITELN(' :10, ' TRUNK 2 ACTIVE TIME
2483 TR2ACTIVE: 10: 7, ' SECS');
2484 WRITELN(' :10, ' TOTAL TRUNK ACTIVE TIME
2485 TIMEACTIVE: 10: 7, ' SECS');
2486 WRITELN(' :10, ' X TRUNK 1 ACTIVE TIME
2487 PER1ACTIVE: 6: 3, ' X');
2488 WRITELN(' :10, ' X TRUNK 2 ACTIVE TIME
2489 PER2ACTIVE: 6: 3, ' X');
2490 WRITELN(' :10, ' X TOTAL TRUNK ACTIVE TIME
2491 PERTACTIVE: 6: 3, ' X');
2492
2493 END
2494 ELSE
2495 BEGIN
2496 WRITELN(' :10, ' TOTAL TRUNK ACTIVE TIME
2497 TIMEACTIVE: 10: 7, ' SECS');
2498 WRITELN(' :10, ' X TOTAL TRUNK ACTIVE TIME
2499 PERTACTIVE: 6: 3, ' X');
2500
2501 END
2502
2503 WRITELN(' :10, ' CONTROL BYTES TRANSMITTED
2504 CONTBITS / 8.OE+06: 12, ' MBYTES');
2505 WRITELN(' :10, ' DATA BYTES TRANSMITTED
2506 DATA1BITS / 8.OE+06: 12, ' MBYTES');
2507 WRITELN(' :10, ' DATA BYTES TRANSMITTED
2508 DATA2BITS / 8.OE+06: 12, ' MBYTES');
2509
2510 END
2511 ELSE
2512 BEGIN
2513 WRITELN(' :10, ' CONTROL BYTES TRANSMITTED
2514 CONTBITS / 8.OE+06: 12, ' MBYTES');
2515 WRITELN(' :10, ' DATA BYTES TRANSMITTED
2516 DATA1BITS / 8.OE+06: 12, ' MBYTES');
2517 WRITELN(' :10, ' CONTROL BYTES TRANSMITTED
2518 CONTBITS / 8.OE+06: 12, ' MBYTES');
2519 WRITELN(' :10, ' DATA BYTES TRANSMITTED
2520 DATA2BITS / 8.OE+06: 12, ' MBYTES');
2521
2522 END
2523 WRITELN(' :10, ' TOTAL BYTES TRANSMITTED
2524 BITSTX / 8.OE+06: 12, ' MBYTES');
2525 WRITELN(' :10, ' TOTAL OFFERED LOAD
2526 (OFFLOAD * CURRENTTIME) / 8.OE+06: 12, ' MBYTES');
2527
2528 END

```

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```

2594 [ NETWORK COLD START CONDITIONS ]
2595 INITIALIZE;
2596 CHARACTERIZENETWORK;
2597 PRINTNETDESCRIPTION;
2598
2599 REPEAT
2600   CARDWN := 0.0; CARUP := 0.0;
2601   FINDNEXT(TMITTER);
2602   TA := TMITTER.DNUM DIV 100;
2603   TD := (TMITTER.DNUM MOD 100) DIV 10;
2604   TS := TMITTER.DNUM MOD 10;
2605   IF TMITTER.DEST = 0 THEN
2606     PICKA (TMITTER);
2607     WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
2608       BEGIN
2609         IF TA < COMAD THEN
2610           TRK1 := TRUE
2611         ELSE
2612           TRK1 := FALSE;
2613
2614         IF TA = COMAD THEN
2615           IF ((DEST DIV 100) < COMAD ) THEN
2616             TRK1 := TRUE
2617           ELSE
2618             TRK1 := FALSE;
2619
2620         END;
2621         WITH ADAPTER[TA] DO
2622           IF TRK1 THEN
2623             BEGIN
2624               CARUP := T1;
2625               CARDWN := T2;
2626               TOTALDELAY := TOT1DELAY;
2627               PR1DELAY := PR11DELAY;
2628               ENDD1DELAY := ENDD1DELAY;
2629               FIXE1DELAY := FIX1DELAY;
2630             END
2631           ELSE
2632             BEGIN
2633               CARUP := T3;
2634               CARDWN := T4;
2635               TOT2DELAY := TOT2DELAY;
2636               PR2DELAY := PR22DELAY;
2637               ENDD2DELAY := ENDD2DELAY;
2638               FIXE2DELAY := FIX2DELAY;
2639             END;
2640
2641           IF NOT RESERVED THEN
2642             WITH ADAPTER[TA].DEVICE[TD].SOURCE[TS] DO
2643               BEGIN

```

```

2639         IF M1 OR M2 OR M3 OR M4 OR M5 OR M6 THEN
2640             BEGIN
2641                 IF (NEXTTX >= CARDWN + TOTALDELAY) OR (NEXTTX = CARDWN + FIXEDDELAY
2642                     + PRIDELAY ) THEN
2643                     BEGIN
2644                         IF M1 THEN
2645                             UPDATE(CONDITION(CASE2)) ELSE
2646                         IF M2 THEN
2647                             UPDATE(CONDITION(CASE3)) ELSE
2648                         IF M3 THEN
2649                             UPDATE(CONDITION(CASE4)) ELSE
2650                         IF M4 THEN
2651                             UPDATE(CONDITION(CASE5)) ELSE
2652                         IF M5 THEN
2653                             UPDATE(CONDITION(CASE6)) ELSE
2654                         IF M6 THEN
2655                             UPDATE(CONDITION(CASE7))
2656                     END
2657                 ELSE
2658                     BEGIN
2659                         IF (NEXTTX <= CARDWN + FIXEDDELAY + PRIDELAY) THEN
2660                             NEXTTX := CARDWN + FIXEDDELAY + PRIDELAY;
2661                         IF (NEXTTX > CARDWN + FIXEDDELAY + PRIDELAY ) THEN
2662                             NEXTTX := CARDWN + TOTALDELAY;
2663                     END;
2664
2665                 IF (NEXTTX < CARDWN) AND ((M1) OR (M2) OR (M3) OR (M4) OR (M5)
2666                     OR (M6)) THEN
2667                     NEXTTX := CARDWN + FIXEDDELAY + PRIDELAY;
2668                 END
2669             ELSE
2670                 UPDATE(CONDITION(CASE1));
2671             END;
2672
2673             IF TRK1 THEN
2674                 BEGIN
2675                     T1 := CARUP;
2676                     T2 := CARDWN;
2677                 END
2678             ELSE
2679                 BEGIN
2680                     T3 := CARUP;
2681                     T4 := CARDWN;
2682                 END;
2683             UNTIL ( CURRENTTIME >= MAXTIME) OR ( SEQTALLY >= MAXSEQTX );
2684
2685             TIMEACTIVE := TR1ACTIVE + TR2ACTIVE;
2686             BITSTX := CONTBITS + DATA1BITS + CNT2BITS + DATA2BITS;
2687
2688             PRINTSTATS;
2689             ACTIVITYSUMMARY;
2690             WRITELN(OUTPUT);
2691             WRITELN('END OF RUN');
2692
2693

```

2694      END. (\* MAIN PROGRAM \*)

COMPILATION COMPLETE :      NO ERRORS REPORTED

OPTIONS REQUESTED :-

GENERATE EXTENDED ADDRESSING CODE ( X OPTION )

OBJECT PROGRAM      =    24503 WORDS  
COMPILATION TIME      =    40473 MILLISECONDS  
SOURCE PROGRAM      =    2694 LINES  
COMPILATION RATE      =    67 LINES PER SECOND

====> \$VU-R  
====> SP S+20  
====> MO NX  
====> BEGIN

1      PROGRAM NAME: 2028EING\*XE  
0      LIBRARY INFORMATION  
0      0000SYST\*SAULIB  
0      MODULE INFORMATION

R	0000000	0000000			PSIGVS
R	0000002	0026353			PSMAIN
	0026354	0047373			
	0047374	0057765			
R	0057766	0061733	0070000	0070102	PSREAR
R	0061734	0066446	0070104	0070456	LIBERY
R	0066450	0066557	0070460	0070460	PSSTEQ
			0070462	007106C	*TEMP*
			0071062	0071161	*DBUG*
			0102000	0102000	PSSCOM

S

**APPENDIX II**  
**Summary of ISO-OSI Model of Distributed Networks**

Layer	Definition
1. Physical	Concerned with transmission of unstructured bit stream over physical link; involves such parameters as signal voltage swing and bit duration; deals with the mechanical, electrical, and procedural characteristics to establish, maintain, and deactivate the physical link. (RS-232-C, RS-449, X.29)
2. Data Link	Converts an unreliable transmission channel into a reliable one; sends blocks of data (frames) with checksum; uses error detection and frame acknowledgement (HDLC, SDLC, BiSync)
3. Network	Transmits packets of data through a network; packets may be independent (datagram) or traverse a preestablished network connection (virtual circuit); responsible for routing and congestion control. (X.25, layer 3)
4. Transport	Provides reliable, transparent transfer of data between end points; provides end-to-end error recovery and flow control
5. Session	Provides means of establishing, managing, and terminating connection (session) between two processes; may provide checkpoint and restart service, quarantine service
6. Presentation	Performs generally useful transformations on data to provide a standardized application interface and to provide common communications services; i.e., encryption, text compression, reformatting
7. Application	Provides services to the users of OSI environment; i.e., transaction server, file transfer protocol, network management

This summary taken from, *Local Networks, An Introduction*, by William Stallings [STALL84].



## APPENDIX III

### Simulation Software Module Descriptions

#### 1. Sim1.

Sim1 is the top level procedure of the simulation program. It controls simulation activity and flow in the simulation environment. Referring to Figure 4.2, the first three blocks perform variable initialization, define the simulation network configuration, and prints a description of the network in the auxiliary file Auxout. The loop indicated is the actual simulation activity (described in subsequent sections). Sim1 will print compiled overall network statistics to the system default output device and to the auxiliary file Auxout, by invoking Printstats. The procedure Activitysummary prints a breakdown of the network statistics by device, to the auxiliary file (Auxout).

#### 2. Initialize

This procedure is used to initialize certain global variables which need to be specified for each execution of the program. Table III.1, is a listing of the interactive queries posed by this procedure, along with any constraints involved. The remaining variables which do not require user-intervention are also initialized in this section.

**Table III.1 Interactive Queries Posed by INITIALIZE**

Query: **Is there more than one Trunk ? Yes or No**  
Response: Y or N, if answered yes then the flag Trunks is set true, otherwise, Trunks is set false.  
Example: Y  
Variable: Trunks = True

Query: **Identification heading for run:**  
Response: Valid responses are alphanumeric strings with length less than 50 characters. Heading appears on each output page.  
Example: Simulation Configuration Test  
Variable: Heading

Query: **Maximum run time in seconds**  
Response: Valid responses are real positive numbers which represent the time a simulation run will execute  
Example: 40  
Variable: Maxtime

Query: **Maximum Successful Sequence Transmissions ?**  
Response: Valid responses are real positive numbers which represent the number of successful message-with-data sequences will be transferred over the entire network simulation ends when Maxseqtx or Maxtime is exceeded  
Example: 100000  
Variable: Maxseqtx

Query: **Seed for Random Number Generator**  
Response: Integer number. For best results, the number specified should be an odd, positive number with at least 5 digits and not divisible by 5 or 7.  
Example: 16227  
Variable: U

The following queries will be posed if Trunks is True.

Query: **Was the last Run a Single Trunk Configuration Yes or No**  
Response: Y or N, if answered yes, Inputmode = interactive, thus forcing redefinition of the network. If answered no then the following query will be posed.  
Example: Y

Variable: Inputmode

Query: Input Mode: I)nteractive or F)ile ?

Response: This query will be posed only if the last run was a dual trunk configuration, this is indicated by answering no to the above query. If answered F, the network configuration used will be read out of the Dfile. If answered I, then the network will have be redefined by the user

Example: F

Variable Inputmode

The following queries will be posed if Trunks = False

Query: Was the last run a Dual Trunk configuration  
Y)es or N)o

Response: As before, yes will force redefinition of the network and no will cause the next query to be posed.

Example: N

Variable: Inputmode

Query: Input Mode: I)nteractive or F)ile ?

Response: As before, answering no to the above query will allow this query to be posed. The effect of this query is the same as above

Example: I

Variable: Inputmode

### 3. CharacterizeNetwork

Procedure CharacterizeNetwork establishes the experimental framework of the simulation. The individual adapters, devices, and sources are defined. There are two ways to establish an experimental model, interactively, or from an auxiliary file (Dfile). The method employed is determined by the value of Inputmode, defined by procedure Initialize. If Inputmode is equal to interactive, then the system description will be provided by the user interactively. A sub-procedure RewriteDfile will be called to store this interactive system description in the Dfile. If Inputmode equals file, then the system description used is the one stored in the auxiliary file (Dfile), implying a previous run where Dfile was created interactively. A detailed listing of the interactive queries posed by CharacterizeNetwork is presented in Table III.2.

### 4. PrintnetDescription

The purpose of this procedure is to print a detailed description of the system being modeled in the auxiliary file Auxout.

### 5. FindNext(Tmitter)

As previously stated this model is a discrete event simulation. The event which drives the simulation is an adapter's next scheduled transmit time. The

Table III.2 Queries Posed by CHARACTERIZENETWORK

Query: Length of Trunks in feet (used for end delay)  
 Trunk 1:  
 Trunk 2: ( appears for dual trunk )  
 Response: Positive real numbers  
 Variable: Trunklength[I]  
 Query: Number of Adapters in Network:  
 Response: Integer number in range 1 to Maxnumadapters  
 Variable: Numofadapters

In the Dual Trunk case the following query will be made

Query: Which Adapter is Common to both Trunks ?  
 Response: Integer number in range 1 to Maxnumadapters  
 Variable: Commad

Query: Adapter #i: Distance in ft. from priority 1 adapter on Trunk 1  
 Response: Positive real numbers  
 Variable: Adapter[i].distfromA1

Query: Adapter Priority: Give in integer form, i.e.,  $n = 1, 2, \dots$   
 Response: Positive integer numbers  
 Variable: Adapterp[i].P1

Query: Adapter Retry Count: This must be a unique number for each adapter, in the range 0-64  
 Response: Positive integer numbers  
 Variable: Adapterp[i].retryct

The following two queries are made for the common adapter two both trunks

Query: Distance in ft. from priority 1 adapter on Trunk 2  
 Response: Positive real numbers  
 Variable: Adapter[Commad].DistfrntA1

Query: Adapter Priority: Give in integer form, i.e.,  $n = 1, 2, \dots$   
 Response: Positive real numbers  
 Variable: Adapter[Commad].P2

Query: Adapter[i].Device[j] description  
 Device status (Open or Closed)  
 Response: 0 or C. C if Adapter[i].Device[j] has an active, network device con-

nected to it. 0 otherwise.  
 Variable: Adapter[i].Device[j].Open

Query: **Device ID (<= 24 Char)**  
 Response: Alphanumeric string  
 Variable: Adapter[i].Device[j].Id

Query: **Device to Adapter I/O rate (Bytes/sec)**  
 Response: Positive real number representing the speed of the device I/O port.  
 Variable: Adapter[i].Device[j].tferrate

Query: **Number of Data Sources in Device[j]:**  
 Response: Integer number representing the number of data sources supplying the device with data  
 Variable: Adapter[i].Device[j].Numofsources

Query: **Data Source[k] ID:**  
 Response: Alphanumeric string with length <= 24 characters  
 Variable: Adapter[i].Device[j].Source[k].Id

Query: **Source[k] Data gen rate (Bytes/sec)**  
 Response: Real number, representing the rate at which data arrives at device.  
 Variable: Adapter[i].Device[j].Source[k].Genrate

Query: **Buffer size in bytes**  
 Response: Integer number, size of buffer filled in device before network transmission is requested.  
 Variable: Adapter[i].Device[j].Source[k].Buffersize

Query: **Receiver Id code ? (0 to end list)**  
 Response: 3 digit integer number, representing Adapter#, Device#, and Source#  
 Variable: Adapter[i].Device[j].Source[k].Id

Query: **Probability ?**  
 Response: Positive real number  $0 < \text{number} \leq 1$  representing the relative probability that the above receiver will be transmitted to by this  
 adapter[i].device[j].source[k]  
 Variable: Adapter[i].Device[j].Source[k].Prob

procedure FindNext scans all adapters and picks the one with the smallest next time to transmit, compared to (Currenttime) simulation time. After selecting one adapter, it will then determine if this adapter is reserved for a reception of a message sequence from another adapter. If the adapter is reserved, then it is forced to wait, if not reserved then it is returned to the main program as the current transmitter.

#### 6. PickA(Tmitter)

This procedure is used to pick a receiver for a transmitting adapter. The current transmitter's attributes are passed to this procedure, and an appropriate receiver is selected based on its list of possible receivers and the relative probability of the adapter being a receiver for the transmitter. This procedure also determines whether a transmitter is attempting to transmit to a different trunk. If attempting a dual trunk communication, the transmitter is assigned an intermediate receiver which is common to both trunks.

#### 7. ACollision

The purpose of the boolean function ACollision, is to determine whether or not the current transmitter has unrestricted use of the simulated transmission medium. If another device attempts to transmit during a time period of equal to, or less than , twice the

propagation time between the two, a collision condition will be declared. Thus, ACollision scans the network devices comparing their next transmit time to the current transmitter's next transmit time and determines whether or not a collision has occurred. In dual trunk simulations the function ACollision will scan which ever trunk is being used by the current transmitter. If a collision is declared, then collision statistics are updated, and both the current transmitter's and colliding adapter's next transmission times are updated.

#### **8. Uniform**

The Uniform procedure functions as a Random Number Generator. It generates pseudo-random numbers in the range  $0 < \text{number} < 1$ . This procedure is used in various sections of the simulation in order to inject some randomness in the selection of receivers and in varying some time parameters.

#### **9. Update**

Update is the procedure in which the bulk of the HYPERchannel protocol is modeled. As previously stated, the simulation is driven by a discrete event. This type of simulation is often referred to as activity scanning, or event scanning. The event which drives the simulation is a transmit request by an adapter. Each device is assumed to possess certain attributes



determined from observations of the real system. As an example of this, if a device receives data from an off-net source to transmit over the network at an average rate of 15 Kilobytes per second, and stores this data in a 2 Kbyte buffer, it will request a network transmission every 0.1365 seconds. This then serves to generate transmission requests for the simulation and in turn, becomes the event which drives the simulation clock.

This procedure consists of seven cases, each of which updates the current transmitter according to where it is in a message-with-data sequence transmission. The time periods involved are illustrated in Figure 4.1, where the individual cases are indicated and the program flags that signal the case an adapter will go to on a transmit request.

Case1: The first time an adapter signals a request to transmit there will be no message flags active, indicating the beginning of a message sequence. Case1 will be invoked and the adapter will reserve itself, initialize delay to 1 usec and retry to zero (reservation scheme), set M1 true, and adjust its next time to transmit by 64 usec.

Case2: This case incorporates the adapter reservation scheme (Figure 2.9). An adapter entering (Case2, Case3, Case4, Case5, Case6, or Case7) is first

checked to see if it is involved in a collision with other devices. If no collision is detected the adapter is checked for dual trunk communication, if it is, then an intermediate destination is determined. If not, then the adapter's intended receiver is checked to see if it is reserved by another adapter. If the intended receiver is not reserved, then the receiving adapter will be set reserved. Appropriate adjustments to the various transmission times, bit counts, message flags, and trunk parameters are made. If, however, the intended receiver is already reserved, the transmitting adapter will enter the retry-delay reservation scheme and its message flag will not be changed. Thus, the adapter will return to Case2 each time selected until it reserves a receiver, or aborts its transmission. If a collision is detected when entering (Case2, Case3, Case4, Case5, Case6, or Case7) then, appropriate adjustments to adapter and trunk timing is made.

Case3: This case deals with the message proper portion of the message sequence. If no collision is detected, adjustments are made to the adapter and trunk parameters.

Case4: This case is essentially the same as Case3, with the exception of the values used to update adapter and trunk parameters.

Case5: In Case5 a determination of how many data sequences need to be transmitted is made, this based on the size of the data buffer of the transmitting source. The first sequence will be updated and if more than one sequence is to be sent then message flag M4 will not be changed. Appropriate timing adjustments are made in this section also.

Case6: When all data sequences have been sent, Case6 is invoked. Appropriate timing adjustments are made in this section.

Case7: There are three possibilities encountered in this section: same trunk communication, adapter to common trunk adapter communication, and common trunk adapter to adapter communication. The last two in combination comprise a dual trunk communication. In all cases this is the termination of a message sequence. Both, the receiver and transmitter are released, and appropriate timing adjustments are made.

#### 10 Printstats

This procedure compiles and writes to the system default output device, and auxiliary file (Auxout), an overall summary of network activity. Examples of this follow:

## Single Trunk Simulation Results

\*\*\* End of Run Network Statistics \*\*\*

```
Current Time :      nn.nnnn  secs

Successful Sequence Transmissions      :nnnnn
Collisions      (Frames)               :nnnnn
Waits           (Frames)               :n.nE+nn
Total Attempts (Sequences)             :nnnnn
Total Aborts                                         :nnnnn

Total Trunk Active Time      :nn.nnnn  secs
% Total Active Time         :nn.nnn   %

Control Bytes Transmitted    :n.nnnnnE+nn Mbytes
Data Bytes Transmitted       :n.nnnnnE+nn Mbytes
Total Bytes Transmitted      :n.nnnnnE+nn Mbytes

Total Offered Load          :n.nnnnnE+nn Mbytes
```

## Dual Trunk Simulation Results

\*\*\* End of Run Network Statistics \*\*\*

```
Current Time : nn.nnnn  secs

Successful Sequence Transmissions      :nnnnn
Successful Sequence Transmissions-Trunk 1 :nnnnn
Successful Sequence Transmissions-Trunk 2 :nnnnn
Collisions      (Frames)               :nnnnn
Waits           (Frames)               :n.nE+nn
Total Attempts  (Sequences)            :nnnnn
Total Aborts                                         :nnnnn
Attempted Trunk-Trunk Transmissions     :nnnnn
Successful Trunk-Trunk Transmissions     :nnnnn
Trunk 1 Active Time                     :n.nnnn  secs
Trunk 2 Active Time                     :n.nnnn  secs
Total Trunk Active Time                 :n.nnnn  secs
% Trunk 1 Active Time                   :nn.nnn  %
% Trunk 2 Active Time                   :nn.nnn  %
% Total Trunk Active Time                :nn.nnn  %

Control Bytes Transmitted    Trunk 1    :n.nn Mbytes
Data Bytes Transmitted       Trunk 1    :n.nn Mbytes
Control Bytes Transmitted    Trunk 2    :n.nn Mbytes
Data Bytes Transmitted       Trunk 2    :n.nn Mbytes
Total Bytes Transmitted      :n.nn Mbytes
Total Offered Load          :n.nn Mbytes
```

## 11. Activity Summary

This procedure prints detailed breakdown by device, of network activities. This summary is printed to the system default output device, and the auxiliary file (Auxout). The categories detailed are as follows:

Time Active:	Time device spent transmitting and receiving.
Time Waiting:	Time device spent waiting to transmit due to its adapter being reserved.
Time in Collisions:	Time involved in collisions by device.
Average Message Delay:	This is the average time length of a message sequence sent by this device. If this number is 0, either the device can't transmit, or it tried to but never sent an entire message sequence. In the latter case, message delay would have to be > than simulated run time.
Abort count:	Number of aborted transmission attempts (reservation scheme).
Transmission Count:	Number of successfully transmitted sequences
Reception Count:	Number of successfully received sequences
Wait Count:	Number of times device had to wait to transmit

Collision Count: Number of times engaged  
in a collision. (note:  
these numbers are actually  
double the total shown in  
overall statistics due to  
one count for each col-  
liding adapter.

## APPENDIX IV

### Typical Single Trunk Simulation Results

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NETWORK DESCRIPTION  
ADAPTER # 1

.....

ADAPTER # 1:

PRIORITY DELAY ON TRUNK 1 : 0.0000005 SEC  
FIXED DELAY : 0.0000001 SEC  
TOTAL DELAY ON TRUNK 1 : 0.0000190 SECS  
ADAPTER RETRY COUNT : 1

DEVICE 1 STATUS: CLOSED--DEC 11/24

I/O BUS TRANSFER RATE: 50000.00 BYTES/SEC  
LOAD TIME: 0.000025 SEC  
NUMBER OF DATA SOURCES: 1  
REMOTE PERIPHERAL DEVICE  
DEVICE NUMBER 111  
BUFFER SIZE: 2.1E+03 BYTES  
SOURCE # 1 DATA GENERATION RATE: 15000.00 BYTES  
TRUNK TRANSMISSION INTERVAL: 0.1397 SEC  
DATA BLOCK COUNT : 1.02343750CE+00  
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 111  
RECEIVER ID: 311  
RECEIVER ID: 321  
PROBABILITY: 7.0E-01  
PROBABILITY: 3.0E-01

DEVICE 2 STATUS: OPEN  
DEVICE 3 STATUS: OPEN  
DEVICE 4 STATUS: OPEN

.....

NETWORK DESCRIPTION  
ADAPTER # 2

.....

ADAPTER # 2:



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PRIORITY DELAY ON TRUNK 1 : 0.0000022 SEC  
FIXED DELAY : 0.0000061 SEC  
TOTAL DELAY ON TRUNK 1 : 0.0000190 SECS  
ADAPTER RETRY COUNT : 2

DEVICE 1 STATUS: CLOSED--VAX 3  
I/O BUS TRANSFER RATE: 500000.00 BYTES/SEC  
LOAD TIME: 0.0000002 SEC  
NUMBER OF DATA SOURCES: 1  
SPACE TELESCOPE  
DEVICE NUMBER 211  
BUFFER SIZE: 4.0E+03 BYTES  
SOURCE # 1 DATA GENERATION RATE: 4000.00 BYTES  
TRUNK TRANSMISSION INTERVAL: 1.0000 SEC  
DATA BLOCK COUNT : 1.953125000E+00  
PROBABILITY: 1.0E+00  
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 211  
RECEIVER ID: 431

DEVICE 2 STATUS: CLOSED--VAX 2  
I/O BUS TRANSFER RATE: 500000.00 BYTES/SEC  
LOAD TIME: 0.0000002 SEC  
NUMBER OF DATA SOURCES: 1  
SOFTWARE DEVELOPMENT  
DEVICE NUMBER 221  
BUFFER SIZE: 6.4E+03 BYTES  
SOURCE # 1 DATA GENERATION RATE: 6400.00 BYTES  
TRUNK TRANSMISSION INTERVAL: 1.0000 SEC  
DATA BLOCK COUNT : 3.125000000E+00  
PROBABILITY: 1.0E+00  
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 221  
RECEIVER ID: 421

DEVICE 3 STATUS: OPEN  
DEVICE 4 STATUS: OPEN

.....

NETWORK DESCRIPTION  
ADAPTER # 3

.....

ADAPTER # 3:  
PRIORITY DELAY ON TRUNK 1 : 0.0000037 SEC  
FIXED DELAY : 0.0000061 SEC  
TOTAL DELAY ON TRUNK 1 : 0.0000190 SECS

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ADAPTER RETRY COUNT : 3

DEVICE 1 STATUS: CLOSED--VAX 4

I/O BUS TRANSFER RATE: 500000.00 BYTES/SEC  
LOAD TIME: 0.000002 SEC  
NUMBER OF DATA SOURCES: 1  
MPS PRIME

DEVICE NUMBER 311  
BUFFER SIZE: 5.1E+02 BYTES  
SOURCE # 1 DATA GENERATION RATE: 1000.00 BYTES  
TRUNK TRANSMISSION INTERVAL: 0.5120 SEC  
DATA BLOCK COUNT : 2.50000000E-01

POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR:311  
RECEIVER ID: 211  
RECEIVER ID: 221  
PROBABILITY: 1.0E-02  
PROBABILITY: 1.0E-02

DEVICE 2 STATUS: CLOSED--VAX 1

I/O BUS TRANSFER RATE: 500000.00 BYTES/SEC  
LOAD TIME: 0.000002 SEC  
NUMBER OF DATA SOURCES: 1  
MPS 8/U

DEVICE NUMBER 321  
BUFFER SIZE: 5.1E+02 BYTES  
SOURCE # 1 DATA GENERATION RATE: 1000.00 BYTES  
TRUNK TRANSMISSION INTERVAL: 0.5120 SEC  
DATA BLOCK COUNT : 2.50000000E-01

POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR:321  
RECEIVER ID: 211  
RECEIVER ID: 221  
PROBABILITY: 1.0E-02  
PROBABILITY: 1.0E-02

DEVICE 3 STATUS: CLOSED--FEP

I/O BUS TRANSFER RATE: 3300000.00 BYTES/SEC  
LOAD TIME: 0.000000 SEC  
NUMBER OF DATA SOURCES: 1  
FEP

DEVICE NUMBER 331  
BUFFER SIZE: 6.3E+02 BYTES  
SOURCE # 1 DATA GENERATION RATE: 625.00 BYTES  
TRUNK TRANSMISSION INTERVAL: 1.0000 SEC  
DATA BLOCK COUNT : 3.031757812E-01

POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR:331  
RECEIVER ID: 421  
PROBABILITY: 1.0E+00

DEVICE 4 STATUS: OPEN

\*\*\*\*\*  
NETWORK DESCRIPTION  
ADAPTER # 4  
\*\*\*\*\*

\*\*\*\*\*

ADAPTER # 4:

PRIORITY DELAY ON TRUNK 1 : 0.0000083 SEC  
FIXED DELAY: 0.0000061SEC  
TOTAL DELAY ON TRUNK 1 : 0.0000144SECS  
ADAPTER RETRY COUNT : 4

DEVICE 1 STATUS: CLOSED--PE 3244 #1  
I/O BUS TRANSFER RATE: 3300000.00 BYTES/SEC  
LOAD TIME: 0.000000 SEC  
NUMBER OF DATA SOURCES: 1  
STS PRI E

DEVICE NUMBER 411  
BUFFER SIZE: 2.0E+03 BYTES  
SOURCE # 1 DATA GENERATION RATE: C.00 BYTES  
TRUNK TRANSMISSION INTERVAL: 9999999.9999 SEC  
DATA BLOCK COUNT : 9.765625000E-01  
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR:411

DEVICE 2 STATUS: CLOSED--PE 8/32 # 3  
I/O BUS TRANSFER RATE: 1200000.00 BYTES/SEC  
LOAD TIME: 0.0000001 SEC  
NUMBER OF DATA SOURCES: 1  
SPACE LAB PRIME

DEVICE NUMBER 421  
BUFFER SIZE: 2.0E+03 BYTES  
SOURCE # 1 DATA GENERATION RATE: 0.00 BYTES  
TRUNK TRANSMISSION INTERVAL: 9999999.9999 SEC  
DATA BLOCK COUNT : 9.765625000E-01  
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR:421

DEVICE 3 STATUS: CLOSED--PE 8/32 # 4  
I/O BUS TRANSFER RATE: 1200000.00 BYTES/SEC  
LOAD TIME: 0.0000001 SEC  
NUMBER OF DATA SOURCES: 1  
SPACE LAB B/U

DEVICE NUMBER 431  
BUFFER SIZE: 2.0E+03 BYTES  
SOURCE # 1 DATA GENERATION RATE: 0.00 BYTES  
TRUNK TRANSMISSION INTERVAL: 9999999.9999 SEC  
DATA BLOCK COUNT : 9.765625000E-01  
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR:431

DEVICE 4 STATUS: OPEN

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\*\*\* END OF RUN NETWORK STATISTICS \*\*\*

CURRENT TIME : 40.0508 SECS

SUCCESSFUL SEQUENCE TRANSMISSIONS : 556  
COLLISIONS (FRAMES) : 1  
WAITS (FRAMES) : 6.7E+01  
TOTAL ATTEMPTS (SEQUENCES) : 557  
TOTAL ABORTS : 0

TOTAL TRUNK ACTIVE TIME : 0.4781966 SECS  
X TOTAL ACTIVE TIME : 1.194 X

CONTROL BYTES TRANSMITTED : 1.04252E+00 MBYTES  
DATA BYTES TRANSMITTED : 1.87793E+00 MBYTES  
TOTAL BYTES TRANSMITTED : 2.92045E+00 MBYTES

TOTAL OFFERED LOAD : 1.12242E+00 MBYTES

DEVICE ACTIVITY SUMMARIES  
(SECONDS)

ADP DEV SOURCE # #	TIME ACTIVE	TIME WAITING	TIME IN COLLISIONS	AVG MESSAGE DELAY	ABORT COUNT	TRANSMISSION COUNT	RECEPTION COUNT	WAIT COUNT	COLLISION COUNT
1 1 1	0.2778	0.0000	0.0E+00	1.3E-03	0	283	0	0	0
REMOTE PERIPHERAL DEVICE									
2 1 1	0.1010	0.0000	1.2E-06	1.7E-03	0	39	156	0	1
SPACE TELESCOPE									
2 2 1	0.0736	0.0017	0.0E+00	2.4E-03	0	39	0	39	0
SOFTWARE DEVELOPMENT									
3 1 1	0.3096	0.0000	0.0E+00	5.3E-04	0	78	293	0	0
MPS PRIME									
3 2 1	0.0232	0.0005	0.0E+00	5.3E-04	0	78	0	11	0



## APPENDIX V

### Typical Dual Trunk Simulation Results

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NETWORK DESCRIPTION  
ADAPTER # 1

\*\*\*\*\*  
\*\*\*\*\*

ADAPTER # 1:

PRIORITY DELAY ON TRUNK 1 : 0.0000005 SEC  
FIXED DELAY: 0.0000041SEC  
TOTAL DELAY ON TRUNK 1 : 0.0000185SECS  
ADAPTER RETRY COUNT : 1

DEVICE 1 STATUS: CLOSED--PE 3244 CSO  
I/O BUS TRANSFER RATE: 3300000.00 BYTES/SEC  
LOAD TIME: 0.000000 SEC  
NUMBER OF DATA SOURCES: 1  
DATA GENERATOR

DEVICE NUMBER 111  
BUFFER SIZE: 1.0E+03 BYTES  
SOURCE # 1 DATA GENERATION RATE: 10000.00 BYTES  
TRUNK TRANSMISSION INTERVAL: 0.1024 SEC  
DATA BLOCK COUNT : 5.00000000E-01  
PROBABILITY: 1.0E+00

POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR:111  
RECEIVER ID: 521

DEVICE 2 STATUS: OPEN  
DEVICE 3 STATUS: OPEN  
DEVICE 4 STATUS: OPEN

\*\*\*\*\*  
\*\*\*\*\*

NETWORK DESCRIPTION  
ADAPTER # 2

\*\*\*\*\*  
\*\*\*\*\*

ADAPTER # 2:

PRIORITY DELAY ON TRUNK 1 : 0.0000041 SEC

FIXED DELAY: 0.0000041SEC  
 TOTAL DELAY ON TRUNK 1: 0.0000118SECS  
 ADAPTER RETRY COUNT: 2

PRIORITY DELAY ON TRUNK 2: 0.0000005SEC  
 FIXED DELAY: 0.0000041SEC  
 TOTAL DELAY ON TRUNK 2: 0.0000190SEC

DEVICE 1 STATUS: CLOSED--DEC 11/24  
 I/O BUS TRANSFER RATE: 50000.00 BYTES/SEC  
 LOAD TIME: 0.0000025 SEC  
 NUMBER OF DATA SOURCES: 1  
 REMOTE PERIPHERAL DEVICE  
 DEVICE NUMBER 211  
 BUFFER SIZE: 2.1E+03 BYTES  
 SOURCE #1 DATA GENERATION RATE: 15000.00 BYTES  
 TRUNK TRANSMISSION INTERVAL: 0.1397 SEC  
 DATA BLOCK COUNT: 1.023437500E+0C  
 POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 211  
 RECEIVER ID: 411  
 PROBABILITY: 7.0E-01  
 RECEIVER ID: 421  
 PROBABILITY: 3.0E-01

DEVICE 2 STATUS: OPEN  
 DEVICE 3 STATUS: OPEN  
 DEVICE 4 STATUS: OPEN

\*\*\*\*\*

# NETWORK DESCRIPTION ADAPTER # 3

\*\*\*\*\*

ADAPTER # 3:

PRIORITY DELAY ON TRUNK 2: 0.0000022SECS  
 FIXED DELAY ON TRUNK 2: 0.0000041SECS  
 TOTAL DELAY ON TRUNK 2: 0.0000190SECS  
 ADAPTER RETRY COUNT: 3

DEVICE 1 STATUS: CLOSED--VAX 3  
 I/O BUS TRANSFER RATE: 50000.00 BYTES/SEC  
 LOAD TIME: 0.0000002 SEC  
 NUMBER OF DATA SOURCES: 1  
 SPACE TELESCOPE



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DEVICE NUMBER 311  
BUFFER SIZE: 4.0E+03BYTES  
SOURCE # 1 DATA GENERATION RATE: 4000.00BYTES  
TRUNK TRANSMISSION INTERVAL: 1.0000SECS  
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 311  
RECEIVER ID: 531  
PROBABILITY: 1.0E+00

DEVICE 2 STATUS : CLOSED--VAX 2  
I/O BUS TRANSFER RATE: 500000.00 BYTES/SEC  
LOAD TIME: 0.000002 SEC  
NUMBER OF DATA SOURCES: 1  
SOFTWARE DEVELOPMENT

DEVICE NUMBER 321  
BUFFER SIZE: 6.4E+03BYTES  
SOURCE # 1 DATA GENERATION RATE: 6400.00BYTES  
TRUNK TRANSMISSION INTERVAL: 1.0000SECS  
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 321  
RECEIVER ID: 521  
RECEIVER ID: 111  
PROBABILITY: 1.0E+00  
PROBABILITY: 3.0E-01

DEVICE 3 STATUS : OPEN

DEVICE 4 STATUS : OPEN

\*\*\*\*\*  
NETWORK DESCRIPTION  
ADAPTER # 4  
\*\*\*\*\*

ADAPTER # 4:

PRIORITY DELAY ON TRUNK 2 : 0.0000057SECS  
FIXED DELAY ON TRUNK 2: 0.0000061SECS  
TOTAL DELAY ON TRUNK 2: 0.0000190SECS  
ADAPTER RETRY COUNT : 4

DEVICE 1 STATUS : CLOSED--VAX 4  
I/O BUS TRANSFER RATE: 500000.00 BYTES/SEC  
LOAD TIME: 0.000002 SEC  
NUMBER OF DATA SOURCES: 1  
MPS PRIME

DEVICE NUMBER 411  
BUFFER SIZE: 5.1E+02BYTES  
SOURCE # 1 DATA GENERATION RATE: 1000.00BYTES  
TRUNK TRANSMISSION INTERVAL: 0.5120SECS  
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 411  
RECEIVER ID: 311  
RECEIVER ID: 321  
PROBABILITY: 1.0E-02  
PROBABILITY: 1.0E-02

DEVICE 2 STATUS : CLOSED--VAX 1

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```
I/O BUS TRANSFER RATE: 500000.00 BYTES/SEC
LOAD TIME: 0.0000002 SEC
NUMBER OF DATA SOURCES: 1
MPS-B/U
  DEVICE NUMBER 421
  BUFFER SIZE: 5.1E+02BYTES
  SOURCE # 1 DATA GENERATION RATE: 1000.00BYTES
  TRUNK TRANSMISSION INTERVAL: 0.5120SECS
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 421
  RECEIVER ID: 311
  PROBABILITY: 1.0E-02
  RECEIVER ID: 321
  PROBABILITY: 1.0E-02
  DEVICE 3 STATUS : CLOSED--PEP
I/O BUS TRANSFER RATE: 3300000.00 BYTES/SEC
LOAD TIME: 0.000000 SEC
NUMBER OF DATA SOURCES: 1
FEP
  DEVICE NUMBER 431
  BUFFER SIZE: 6.3E+02BYTES
  SOURCE # 1 DATA GENERATION RATE: 625.00BYTES
  TRUNK TRANSMISSION INTERVAL: 1.0000SECS
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 431
  RECEIVER ID: 521
  PROBABILITY: 1.0E+00
  DEVICE 4 STATUS : OPEN
*****
NETWORK DESCRIPTION
ADAPTER # 5
*****
*****
ADAPTER # 5:
  PRIORITY DELAY ON TRUNK 2 : 0.000003SECS
  FIXED DELAY ON TRUNK 2 : 0.000001SECS
  TOTAL DELAY ON TRUNK 2 : 0.0000190SECS
  ADAPTER RETRY COUNT : 5
  DEVICE 1 STATUS : CLOSED--PE 3244 #1
I/O BUS TRANSFER RATE: 3300000.00 BYTES/SEC
LOAD TIME: 0.000000 SEC
NUMBER OF DATA SOURCES: 1
STS PRIME
  DEVICE NUMBER 511
  BUFFER SIZE: 2.0E+03BYTES
  SOURCE # 1 DATA GENERATION RATE: 0.00BYTES
  TRUNK TRANSMISSION INTERVAL: 9999999.9999SECS
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 511
  DEVICE 2 STATUS : CLOSED--PE 9 32 # 3
```

```

I/O BUS TRANSFER RATE: 1200000.00 BYTES/SEC
LOAD TIME: 0.0000001 SEC
NUMBER OF DATA SOURCES: 1
SPACE LAB PRIME
DEVICE NUMBER 521
BUFFER SIZE: 2.0E+03BYTES
SOURCE # 1 DATA GENERATION RATE: 0.00BYTES
TRUNK TRANSMISSION INTERVAL: 9999999.9999SECS
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 521

DEVICE 3 STATUS : CLOSED--PE 8/32 # 4
I/O BUS TRANSFER RATE: 1200000.00 BYTES/SEC
LOAD TIME: 0.0000001 SEC
NUMBER OF DATA SOURCES: 1
SPACE LAB B/U
DEVICE NUMBER 531
BUFFER SIZE: 2.0E+03BYTES
SOURCE # 1 DATA GENERATION RATE: 0.00BYTES
TRUNK TRANSMISSION INTERVAL: 9999999.9999SECS
POSSIBLE RECEIVERS AND THEIR RESPECTIVE PROBABILITIES FOR: 531

DEVICE 4 STATUS : OPEN

```

\*\*\* END OF RUN NETWORK STATISTICS \*\*\*

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OF POOR QUALITY

TRUNK 1 ACTIVE TIME : 0.1579856 SECS  
 TRUNK 2 ACTIVE TIME : 0.3538636 SECS  
 TOTAL TRUNK ACTIVE TIME : 0.5118492 SECS  
 X TRUNK 1 ACTIVE TIME : 0.394 X  
 X TRUNK 2 ACTIVE TIME : 0.893 X  
 X TOTAL ACTIVE TIME : 1.278 X

CONTROL BYTES TRANSMITTED - TRUNK 1 : 5.30057E+01 MBYTES  
 DATA BYTES TRANSMITTED - TRUNK 1 : 4.22144E+01 MBYTES  
 CONTROL BYTES TRANSMITTED - TRUNK 2 : 1.01627E+00 MBYTES  
 DATA BYTES TRANSMITTED - TRUNK 2 : 1.10921E+00 MBYTES  
 TOTAL BYTES TRANSMITTED : 3.07768E+00 MBYTES

TOTAL OFFERED LOAD : 1.52347E+00 MBYTES

DEVICE ACTIVITY SUMMARIES  
(SECONDS)

ADP DEV SOURCE	TIME	TIME	TIME IN	AVG MESSAGE	ABORT	TRANSMISSION	RECEPTION	WAIT	COLLISION
# # #	# # #	WAITING	COLLISIONS	DELAY	COUNT	COUNT	COUNT	COUNT	COUNT
DATA GENERATOR	1 1 1	0.1475	0.0000	0.0E+00	6.6E-04	0	388	0	0
REMOTE PERIPHERAL DEVICE	2 1 1	0.1081	0.0000	0.0E+00	6.7E-04	0	388	0	0
SPACE TELESCOPE	3 1 1	0.1010	0.0000	1.2E-06	1.7E-03	0	39	0	1
SOFTWARE DEVELOPMENT	3 2 1	0.0736	0.0017	0.0E+00	2.4E-03	0	39	31	0
NPS PRIME	4 1 1	0.0232	0.0000	0.0E+00	5.8E-04	0	78	0	0
NPS B/U	4 2 1	0.0232	0.0005	0.0E+00	5.8E-04	0	78	11	0
FEP	4 3 1	0.0152	0.0000	1.2E-06	1.7E-03	0	39	0	1
STS PRIME	5 1 1	0.0000	0.0000	0.0E+00	0.0E+00	0	0	0	0
SPACE LAB PRIME	5 2 1	0.2518	0.0000	0.0E+00	0.0E+00	0	0	0	0
SPACE LAB B/U	5 3 1	0.0515	0.0000	0.0E+00	0.0E+00	0	0	0	0

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